#### A specialized SDP solver for sums-of-squares problems in discrete geometry

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# $\begin{array}{ll} \mbox{maximize} & \langle C,X\rangle + b^{\mathsf{T}}y \\ \mbox{subject to} & p_{X,y}(x) \geq 0 \quad \forall x \in S \end{array}$



$$\begin{array}{ll} \text{maximize} & \boldsymbol{b}^{\mathsf{T}}\boldsymbol{y} \\ \text{subject to} & \sum_{i}y_{i}\boldsymbol{p}_{i}(\boldsymbol{x})\geq 0 & -1\leq \boldsymbol{x}\leq 1 \end{array}$$



$$\begin{array}{ll} \text{maximize} & \left\langle C,X\right\rangle \\ \text{subject to} & \sum\limits_{i} \left\langle X_{i},Y_{i}(u,v,t)\right\rangle \geq 0 & \begin{pmatrix} 1 & u & v \\ u & 1 & t \\ v & t & 1 \end{pmatrix} \geq 0 \\ \end{array}$$



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## From polynomials to numbers

Consider

$$p(x) = \langle b(x)b(x)^T, Y \rangle.$$

We want:

$$\langle A_i, X \rangle = c_i \quad i = 1, \dots, m$$

Two approaches:

• Coefficient matching

• Sampling



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**TU**Delft



A set  $S = \{x_1, \ldots, x_N\} \subset \mathbb{R}^n$  is unisolvent for *n*-variate polynomials of degree *d* if

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Note: Sampling is coefficient matching in the Lagrange basis  $\{L_i\}$  corresponding to S, which are the polynomials of degree d with

$$L_i(x_j) = \delta_{ij}$$



Sampling versus coefficient matching

General coefficient matching:

$$p_i = \langle B_i, Y_i \rangle.$$

Sampling:

$$p(x_i) = \langle b(x_i)b(x_i)^T, Y \rangle.$$



## Sampling versus coefficient matching

General coefficient matching: Possibly sparsity

 $p_i = \langle B_i, Y_i \rangle.$ 

Sampling: Low-rank structure

$$p(x_i) = \langle b(x_i)b(x_i)^T, Y \rangle.$$



#### Clustered low-rank semidefinite program

$$\begin{split} \text{maximize} & \sum_{j=1}^{J} \langle C^{j}, Y^{j} \rangle + \langle b, y \rangle \\ \text{subject to} & \left\langle A^{j}_{p}, Y^{j} \right\rangle + B^{j}_{p} y = c^{j}_{p}, \quad j = 1, \dots, J, p = 1, \dots, N_{J} \\ & Y^{j} \geq 0, \qquad \qquad j = 1, \dots, J, \end{split}$$

with

$$\mathcal{A}_{p}^{j} = \bigoplus_{l=1}^{L_{j}} \sum_{r,s=1}^{R_{j}(l)} \mathcal{A}_{p}^{j}(l;r,s) \otimes E_{r,s}^{R_{j}(l)}$$

and  $A_p^j(l; r, s)$  of low rank.





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We further investigate:

- Combining samples and symmetry
- Finding good bases and samples
- Numerical experiments showing speed and stability



## Semidefinite programming solver

Main steps:

- Calculate the so-called Schur complement matrix  $S_{pq} = \langle A_p X^{-1} A_q, Y \rangle$
- Solve a system Dz = d, where S is a leading principal submatrix of D.
- Use z to determine the increments of the variables



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=  $(a_p^T X^{-1} a_q)(a_q^T Y a_p)$ 



#### Using the clustering

Recall that  $A_p^j = 0$  if p is not contained in cluster j. Thus

$$\begin{split} S_{pq}^{ij} &= \langle A_p^i X^{-1} A_q^j, Y \rangle \\ &= \begin{cases} 0 & i \neq j \\ \langle A_p^i X^{-1} A_q^i, Y \rangle & i = j \end{cases} \end{split}$$

Then Dz = d is given by

$$\begin{pmatrix} S^1 & 0 & \cdots & 0 & -B^1 \\ 0 & S^2 & \cdots & 0 & -B^2 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & S^J & -B^J \\ (B^1)^\mathsf{T} & (B^2)^\mathsf{T} & \cdots & (B^J)^\mathsf{T} & 0 \end{pmatrix} z = d$$



Let  $S = LL^T$  be a Cholesky decomposition of S. The matrix D has the decomposition

$$\begin{pmatrix} S & -B \\ B^{\mathsf{T}} & 0 \end{pmatrix} = \begin{pmatrix} L & 0 \\ B^{\mathsf{T}}L^{-\mathsf{T}} & I \end{pmatrix} \begin{pmatrix} I & 0 \\ 0 & B^{\mathsf{T}}L^{-\mathsf{T}}L^{-1}B \end{pmatrix} \begin{pmatrix} L^{\mathsf{T}} & -L^{-1}B \\ 0 & I \end{pmatrix},$$





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#### Results - Three-point bound for the kissing number





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- 20× faster computations for previously computed bounds
- computations up to degree 20 (up to 16 before)
- new kissing number bounds in dimension  $11 \le n \le 23$  and  $25 \le n \le 48$



## Results - Binary sphere packing (n=2)





## Results - Binary sphere packing (n=24)





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Optimal limiting density



## Results - Binary sphere packing (n=24)





## Results - Binary sphere packing (n=23)





Thank you!



#### Bonus slide - Iteratively improving samples and bases

Let  $V = (p_i(x_j))_{ji}$  be the Vandermonde matrix of a basis  $p = (p_1 \dots, p_N)$  with respect to the sample points  $\{x_j\}$ . Consider the QR decomposition V = QR.



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Let  $PV^T = QR$  be a pivoted QR decomposition. Let S be the set of samples corresponding to the first N pivots. Then  $V|_S$  is relatively well-conditioned.

