

Certified and fast computation of supremum norms of approximation errors

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**Intel Corp. SSG-DPD-PLL-Numerics Group

- **Motivation**
 - Correctly rounded elementary functions
 - Supremum norm of error functions
 - Previous approaches and difficulties
- **Our approach**
 - Automatic differentiation and Taylor models
 - Isolation of roots of polynomials
 - Enclosure of roots of functions
- **Results & Conclusion**

Motivation - Mathematical Libraries

- **What?** Compute \sin , \cos , \exp in finite precision, floating-point environment.
- **Why?** Software systems: scientific computing, financial, embedded systems.

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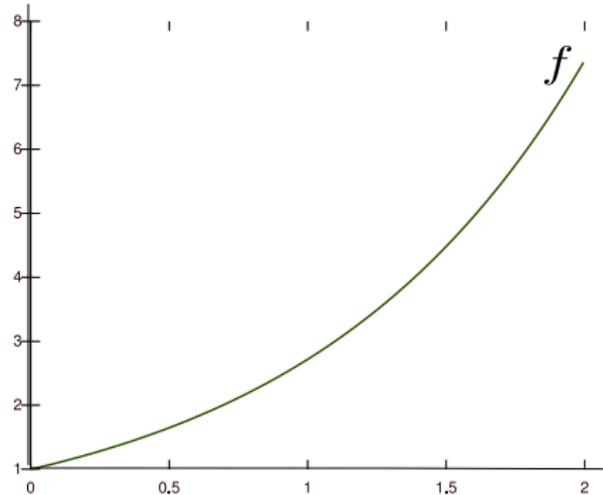
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- IEEE-754-2008 recommends correct rounding.

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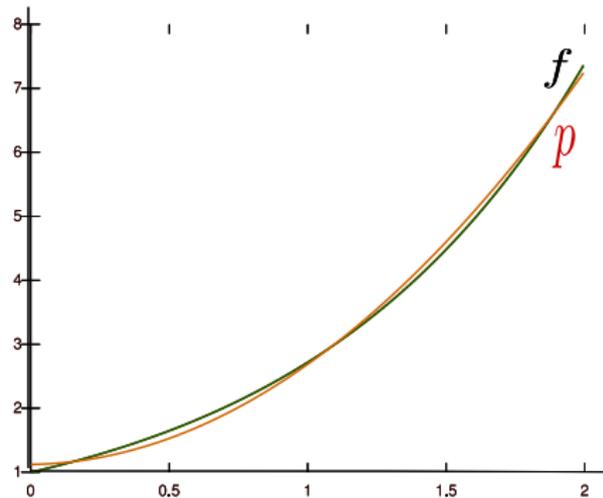
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- Ainaire team develops the Correctly Rounded Libm (CRLibm)¹.

¹<http://lipforge.ens-lyon.fr/www/crlibm/>

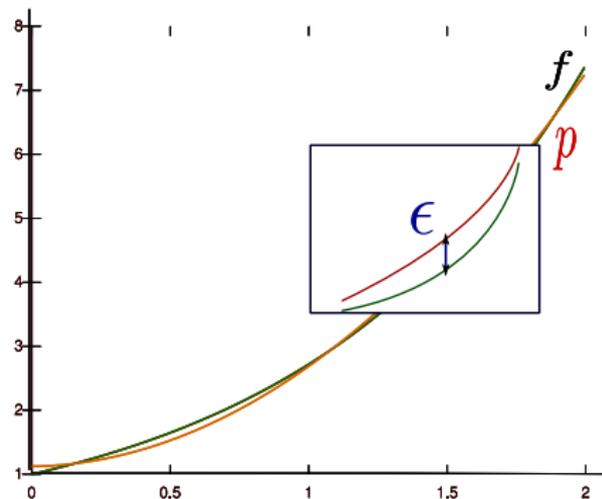
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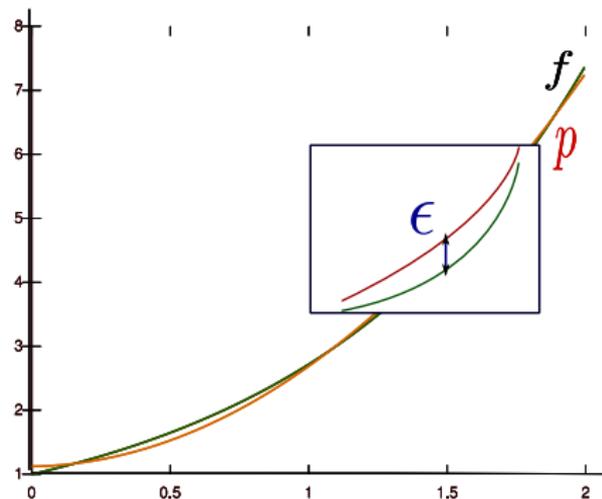


$$\epsilon(x) = f(x) - p(x), \quad x \in [a, b] \text{ or}$$

$$\epsilon(x) = \frac{p(x)}{f(x)} - 1, \quad x \in [a, b]$$

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Compute certified bound for supremum norm of error function

Supremum Norms of Error Functions

- Error $\varepsilon(x) = f(x) - p(x)$ or $\varepsilon(x) = \frac{p(x)}{f(x)} - 1$, $x \in [a, b]$
- Define $\|\varepsilon\|_\infty = \sup_{x \in [a, b]} |\varepsilon(x)|$
- Given p and f find a narrow interval \mathbf{r} such that $\|\varepsilon\|_\infty \in \mathbf{r}$.

Need for a fast and certified algorithm:

- Correctly rounded elementary functions
- Compute error bounds between a function and thousands of polynomials

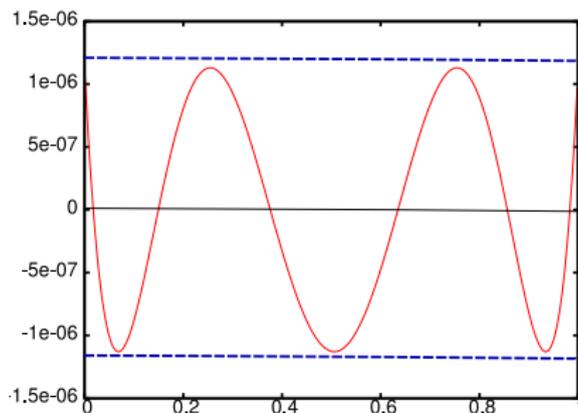
Our Problem - Prone to High Dependency Phenomenon

Example:

$$f(x) = e^x, \quad x \in [0, 1]$$

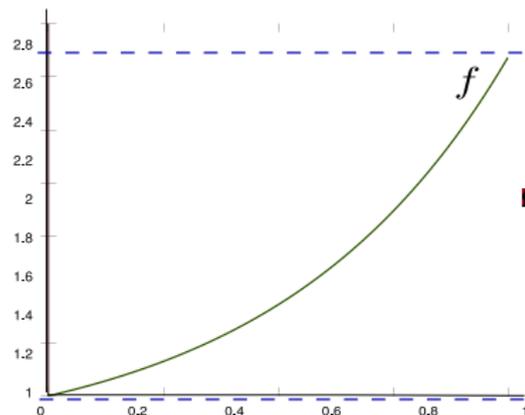
$$p(x) = \sum_{i=0}^5 c_i x^i \text{ s.t. } \|f - p\|_{\infty} \text{ is as small as possible (Remez)}$$

$$\varepsilon(x) = f(x) - p(x)$$

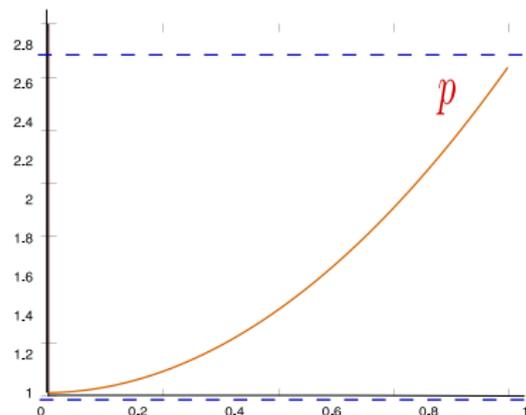


Using IA, $\varepsilon(x) \in [-0.4, 0.4]$, but $\|\varepsilon(x)\|_{\infty} \simeq 1.1295e - 6$:

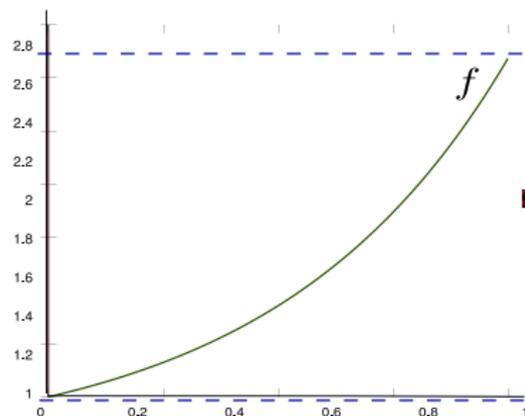
Interval Arithmetic - Overestimation



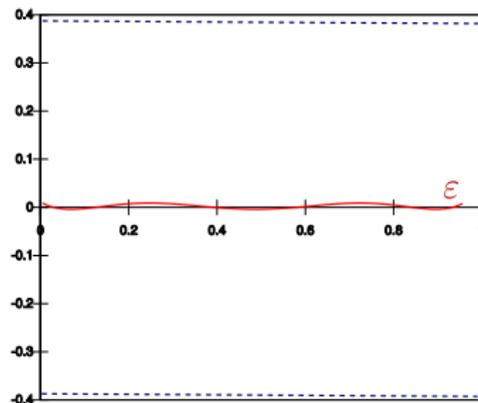
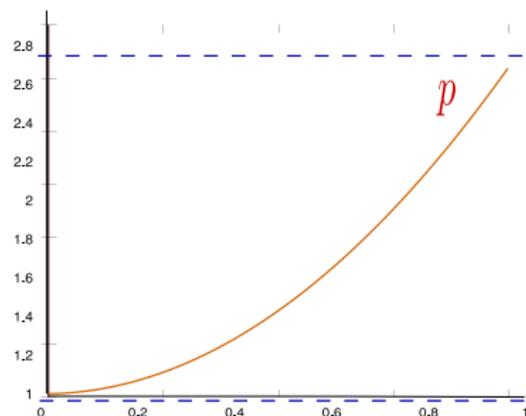
IA



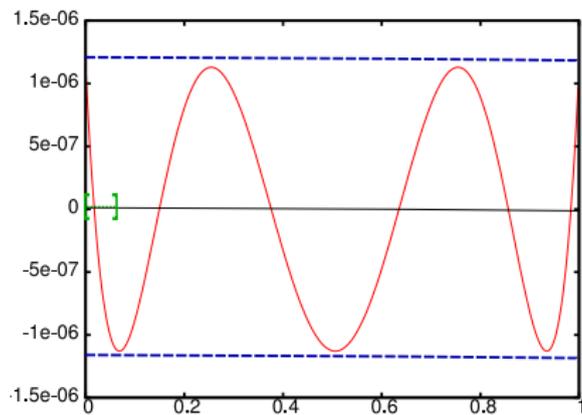
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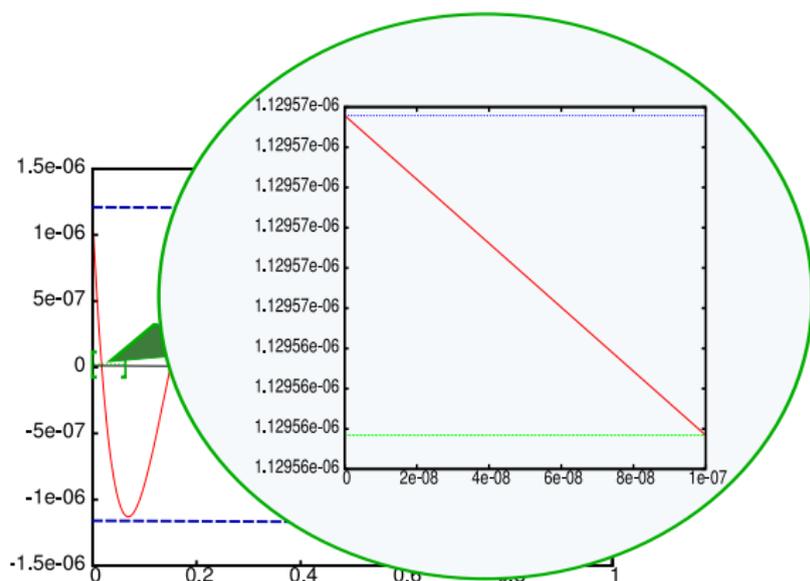
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In this case, over $[0, 1]$ we need 10^7 intervals!

Previous Approaches

- Floating-point techniques: not “safe”
- Existent Interval Arithmetic methods: not sufficient
- Global optimization software: not tailored for specific problem
- Chevillard and Lauter’s technique:
 - interval arithmetic
 - tight bounding of the zeros of the derivative
 - removes false singularities (like $x = 0$ for $\sin(x)/x$)
 - high computation time for $\deg(p) > 10$.
- Taylor expansion techniques:
 - replace error function with a polynomial
 - bound remainder sufficiently close
- Certified polynomial approximations of analytic functions.

Our Approach

- How to obtain a certified and tight bound for $\|\varepsilon\|_\infty = \|f - p\|_\infty$ **AND** $\|\varepsilon\|_\infty = \|p/f - 1\|_\infty$, over given interval $[a, b]$?

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- $\varepsilon' = (p'f - pf')/f^2$. Consider $\tau = p'f - pf'$.

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- Use multiprecision interval arithmetic: MPFI ²

²<http://gforge.inria.fr/projects/mpfi/>

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- How to Solve $\tau(x) = 0$?
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How to compute $(T, [-\theta, \theta])$?

Taylor Formula with Lagrange form of remainder

Let $n \in \mathbb{N}$; Consider τ an n times differentiable function over $[a, b]$ around x_0 :

$$\tau(x) = \sum_{i=0}^{n-1} \frac{\tau^{(i)}(x_0)(x - x_0)^i}{i!} + \Delta_n(x, \xi)$$

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$\Delta_n(x, \xi) = \frac{\tau^{(n)}(\xi)(x-x_0)^n}{n!}$, $x \in [a, b]$, ξ lies strictly between x and x_0

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- Compute coefficients of T : $\frac{\tau^{(i)}(x_0)}{i!}, i \in \{0, \dots, n-1\}$
- Compute $[-\theta, \theta]$ as an enclosure for $\frac{\tau^{(n)}(\xi)}{n!}$, when $\xi \in [a, b]$.

Computing $(T, [-\theta, \theta])$ - Automatic differentiation (AD)

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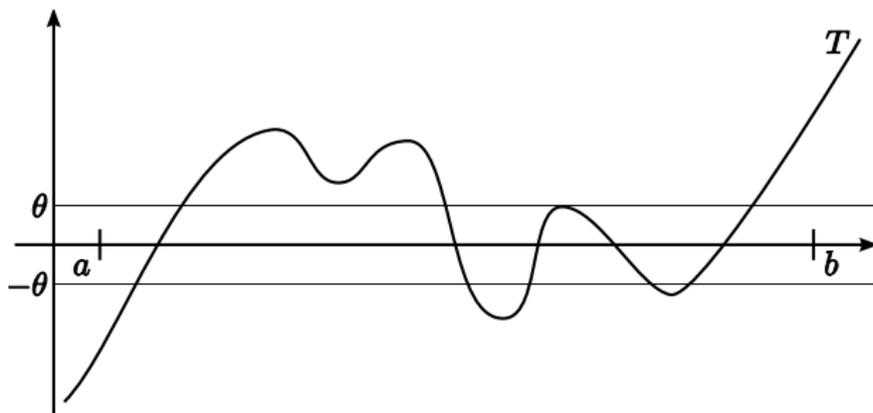
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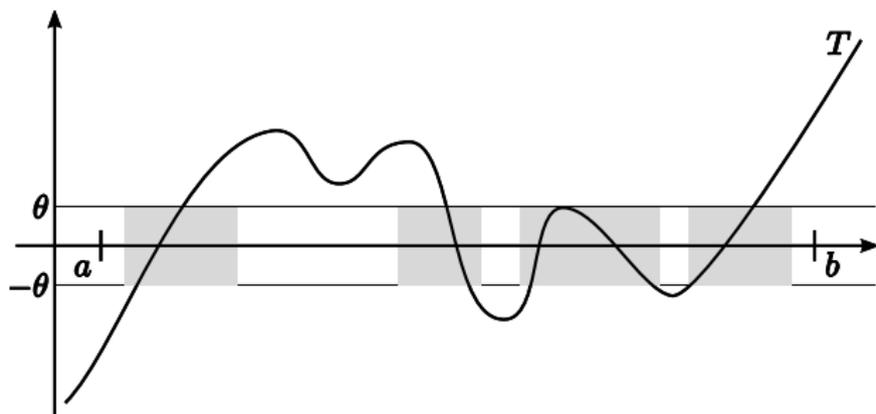
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- Solution: same operations like when evaluating the expression of the derivative, don't write this expression
- AD: usually developed by program code transformation, operators overloading
- Can be easily extended to work with interval arithmetic

How to solve $T(x) \in [-\theta, \theta]$?

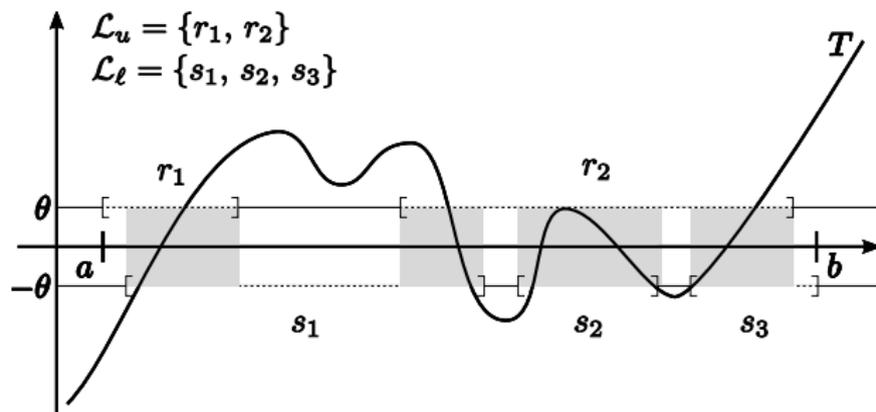


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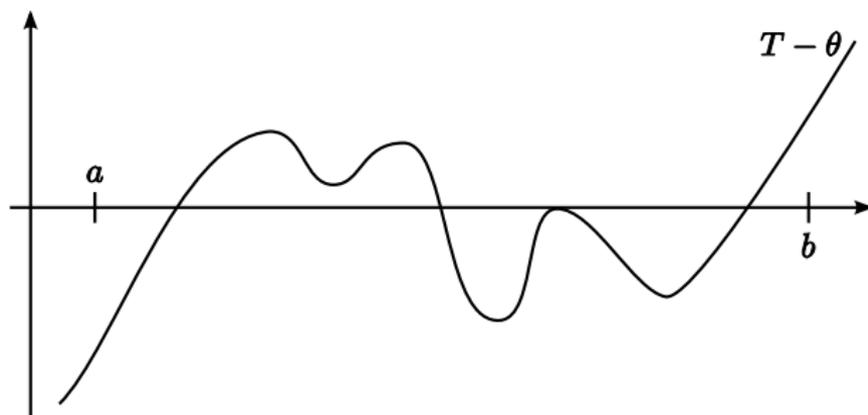
How to solve $T(x) \in [-\theta, \theta]$?

- Compute a list \mathcal{L}_u of intervals where $T - \theta \leq 0$ and \mathcal{L}_l where $T + \theta \geq 0$



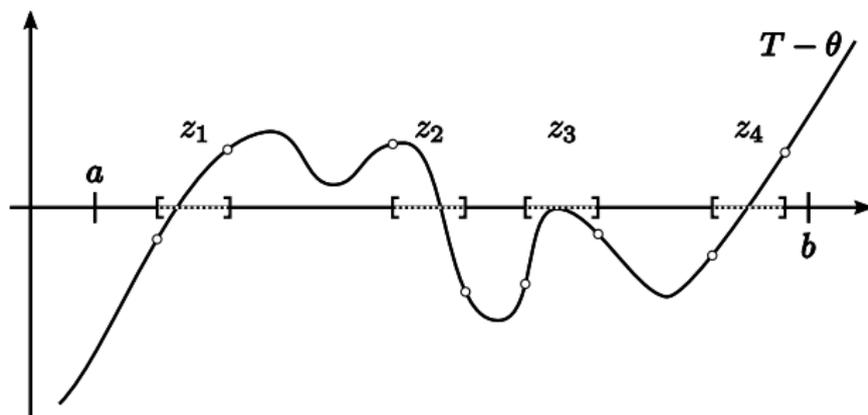
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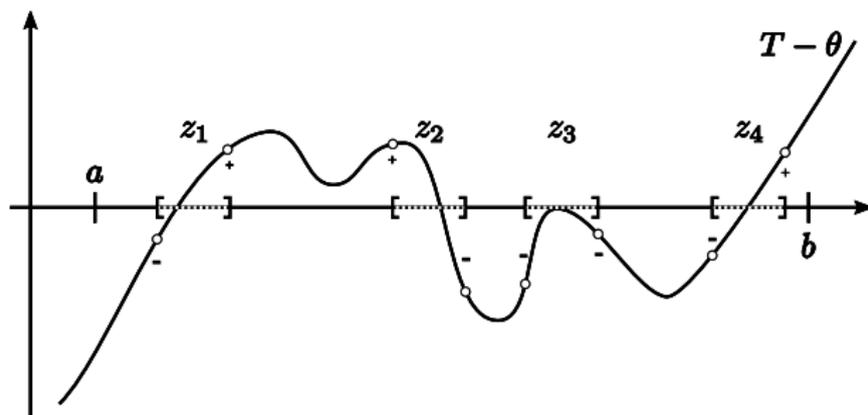
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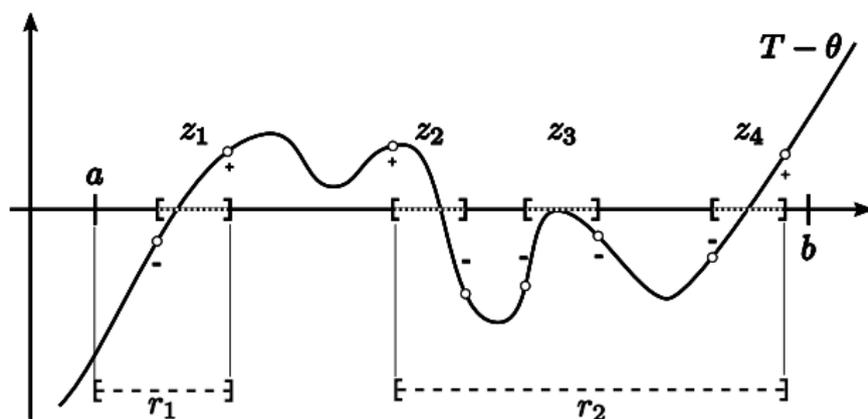
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- Compute enclosures of the roots of $T - \theta$
- Compute sign changes
- Find suitable intervals



Isolation and refinement of roots of polynomials

- Techniques based on counting the number of roots inside an interval considered

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 - Sturm Theorem
 - Descartes' Rule of Signs
- Use a bisection strategy for isolating the roots
- Use dichotomy or Newton iteration process

Our example - Relative error

Example:

$$f(x) = \cos(x) \text{ over } [-1, 1], p(x) = \sum_{i=0}^5 c_i x^i,$$
$$\varepsilon(x) = p(x)/f(x) - 1$$

Our example - Relative error

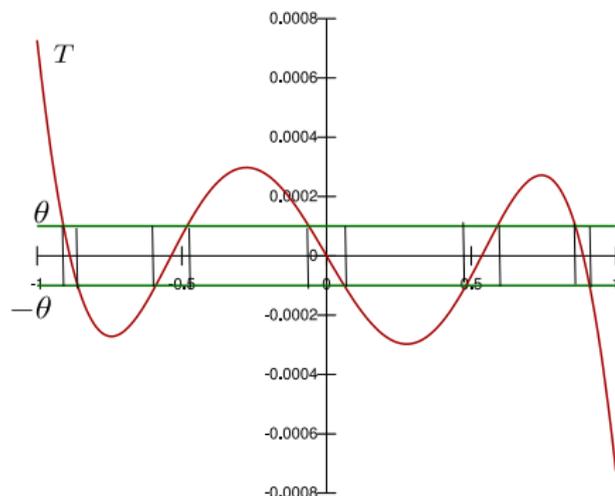
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Compute Taylor Model for $\tau = p'f - pf'$, order 12.

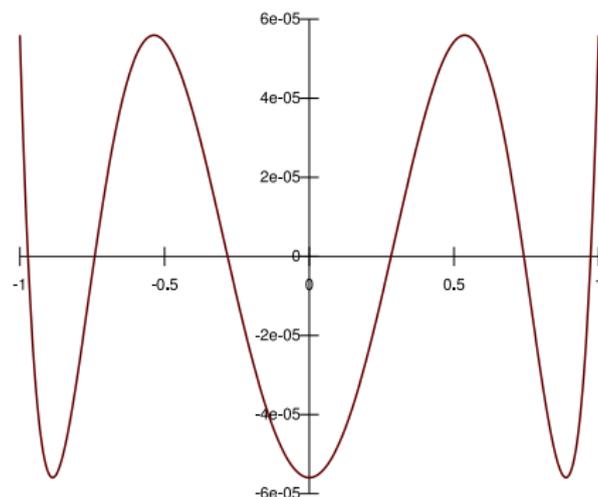
Remainder: $[-1.67352e - 7; 1.67352e - 7]$

Our example - Relative error



$$\begin{aligned}r_0 &\in -0.886[9; 8], & r_1 &\in -0.536[6; 4], \\r_2 &\in [-0.000001; 0.000001], & r_3 &\in 0.536[4; 6], \\r_4 &\in 0.886[8; 9]\end{aligned}$$

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Our Approach - Summary

- Purpose: fast and safely compute the supremum norm $\|f - p\|_\infty$ and $\|p/f - 1\|_\infty$ over an interval $[a, b]$
- Enclose all the zeros of the first derivative of the error
- Evaluate the approximation error on these small intervals only, using multiprecision IA
- Use a Taylor Model based approach to overcome the dependency
- Enclose the zeros of a function using our algorithm

Results

Experiments were made on an Intel Pentium D 3.00GHz with a 2GB RAM.

f	$[a, b]$	d_p^1	m^2	acc^3	$time^4$
$\exp(x) - 1$	$[-0.25, 0.25]$	5	r	37.6	412
$\log_2(1 + x)$	$[-2^{-9}, 2^{-9}]$	7	r	83.3	2186
$\cos(x)$	$[-0.5, 0.25]$	15	r	19.5	2235
$\exp(x)$	$[-0.125, 0.125]$	25	r	42.3	7753
$\sin(x)$	$[-0.5, 0.5]$	9	a	21.5	520
$\exp(\cos(x)^2 + 1)$	$[1, 2]$	15	r	25.5	10984
$\tan(x)$	$[0.25, 0.5]$	10	r	26.0	1072
$x^{2.5}$	$[1, 2]$	7	r	15.5	1362

¹Degree of p

²Error mode considered: a=absolute, r=relative

³Accuracy

⁴Timings in ms

Conclusion

- Safe and fast algorithm for bounding the supremum norm of the error functions
- Combination and reusal of various techniques (Taylor Models, polynomial roots isolation, interval arith)
- Absolute and Relative errors handled
- Faster and more accurate than other current approaches
- Future works:
 - Formal proof (Taylor Models (AD), multiple precision interval arithmetic are needed in the proof checker)
 - Generalization of the algorithm to multivariate functions.

Thank you for your attention!

Questions?

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