

Programme at a Glance : WEDNESDAY 18 <sup>TH</sup> SEPTEMBER, 2002							
	CCA					CACSD	
TRACK	1	2	3	4	5	6	7
ROOM	Lomond	Alsh 1	Alsh 2	Boisdale 1	Boisdale 2	Carron 1	Carron 2
08.30	LOMOND: Welcome						
08.45	LOMOND: CCA Plenary Lecture 1: Kumpati Narendra, Yale University						
09.30	<b>HALL 1 MORNING COFFEE</b>						
	CCA					CACSD	
WM 10.00 – 12.00	Power Systems	Neuro-Fuzzy Control	Observer Design	Motor Control	Aircraft Control	Multiobjective Control System Design	Numerical Software & Applications
12.00-13.00	<b>LUNCH</b>						
13.00	LOMOND: Welcome						
13.05	LOMOND: CCA Plenary Lecture 2: Jeff Cook, Ford Motor Company						
	CCA					CACSD	
WA 14.00 – 15.40	Control of Mechanical Systems	Robotics I	Aerospace System Applications	PID Tuning	Missile and Satellite Control	Nonlinear Control Designs	Control System Design
15.40– 16.00	<b>HALL 1 AFTERNOON TEA</b>						
	CCA					CACSD	
WE 16.00 – 17.40	Noise and Vibrations	Robotics II	Steel Processing	Chemical Processes	Automobile Control	Intelligent Systems	PID and Robust Control
17.40	LOMOND: Welcome						
17.45-18.30	LOMOND: CACSD Plenary Lecture 1: Adriano Cavalcanti Da Silva, Darmstadt University						
19.30	<b>Civic Reception, City Chambers, George Square, Glasgow</b>						

Programme at a Glance : THURSDAY 19 <sup>TH</sup> SEPTEMBER, 2002							
	CCA					CACSD	
TRACK	1	2	3	4	5	6	7
ROOM	Lomond	Alsh 1	Alsh 2	Boisdale 1	Boisdale 2	Carron 1	Carron 2
08.30	LOMOND: Welcome						
08.45	LOMOND: CACSD Plenary 2: Barry Lennox, University of Manchester						
09.30	<b>HALL 1 MORNING COFFEE</b>						
	CCA					CACSD	
<b>ThM</b> <b>10.00 – 12.00</b>	Active Control Methods	Manipulator Control	Communication Systems	Distributed Parameter Systems	PID Control	Optimal Control	Special Session 1 Industrial Control
<b>12.00-13.00</b>	<b>LUNCH</b>						
13.00	LOMOND: Welcome						
13.05	LOMOND: CACSD Plenary 3: Paul Austin, INVENSIS						
	CCA					CACSD	
<b>ThA</b> <b>14.00 – 15.40</b>	Adaptive and Optimal Control	Control of Disk Drives	Predictive Control I	Control System Design and Performance	Control of Engines	Modelling	Special Session 2 Control Funding
<b>15.40 – 16.00</b>	<b>HALL 1 AFTERNOON TEA</b>						
	CCA					CACSD	
<b>ThE</b> <b>16.00 – 18.00</b>	Visual Servo Mechanisms	Power Wheelchair Control	Complex System Applications	Supervision and Monitoring of Processes	Controller Design 1	LFT-based Uncertainty Modelling ... for Aircraft	Numerical Methods & Algorithms
<b>19.00 for 19.30</b>	<b>Conference Banquet, Moat House Hotel</b>						

Programme at a Glance : FRIDAY 20 <sup>TH</sup> SEPTEMBER, 2002							
	CCA						
TRACK	1	2	3	4	5	6	7
ROOM	Lomond	Alsh 1	Alsh 2	Boisdale 1	Boisdale 2	Carron 1	Carron 2
<b>08.30</b>	LOMOND: Welcome						
<b>08.45</b>	LOMOND: CCA Plenary Lecture 3: Sanjoy Mitter, Massachusetts Institute of Technology						
<b>09.30</b>	HALL 1 MORNING COFFEE						
	CCA						
<b>FM 10.00 – 12.00</b>	Integrated Control Applications	Dissipative Control Methods	Modelling	Process Control	Controller Design II	Ship and Hovercraft Control	Stability and System Theory
<b>12.00-13.00</b>	LUNCH						
<b>13.00</b>	LOMOND: Welcome						
<b>13.05</b>	LOMOND: CCA Plenary 4: Roger Benson, ABB Automation(UK) Ltd						
	CCA						
<b>FA 14.00 – 16.00</b>	Miscellaneous Applications	Trajectory Planning & Manufacture	Modelling and Simulation	Predictive Control II	Controller Design III	System Theory + Filtering	Stability
<b>16.00–18.00</b>	HALL 1 AFTERNOON TEA AND FARE-YE WELL RECEPTION						