

# Foundations of Computing

## Module Introduction

Emmanuel Hebrard (adapted from) João Marques Silva



LAAS-CNRS  
/ Laboratoire d'analyse et d'architecture des systèmes du CNRS

Laboratoire conventionné  
avec l'Université Fédérale  
de Toulouse Midi-Pyrénées



## Outline

- 1 Constraint Programming
- 2 Clause Learning in CP

## 1 Constraint Programming

## 2 Clause Learning in CP

- Constraint Satisfaction Problems are generalization of Boolean satisfiability to non-Boolean domains
- Standard constraint programming solvers are similar to DPLL
  - ▶ No clause learning (Clause-learning CSP solvers existed before CDCL but were not that successful)
  - ▶ But stronger propagation

### Constraint Propagation

Given a constraint  $c = (R(c), S(c))$ , a *propagator* is an algorithm that reduce the domains so that the constraint is *arc consistent*.

- A constraint solver is a library of constraints, each with its dedicated propagator

### Arc Consistency

A constraint  $c$  is *Arc Consistent* on domain  $\mathcal{D}$  if and only if for every  $x \in S(c)$  and for every  $j \in \mathcal{D}(x)$ , there exists a tuple  $\sigma \in R(c) \cap \prod_{x \in \mathcal{X}} \mathcal{D}(x)$  such that  $\sigma(x) = j$ .

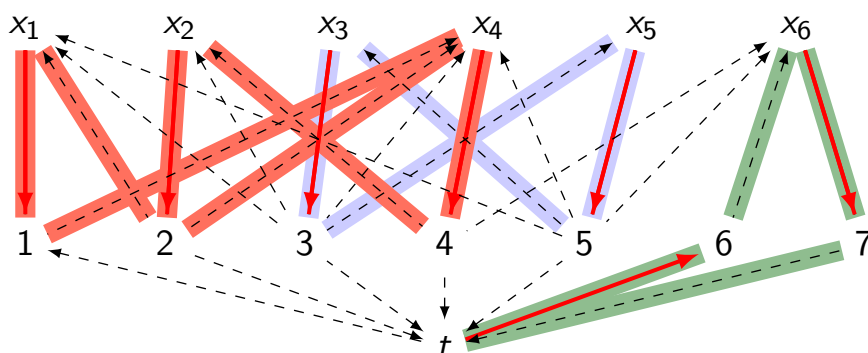
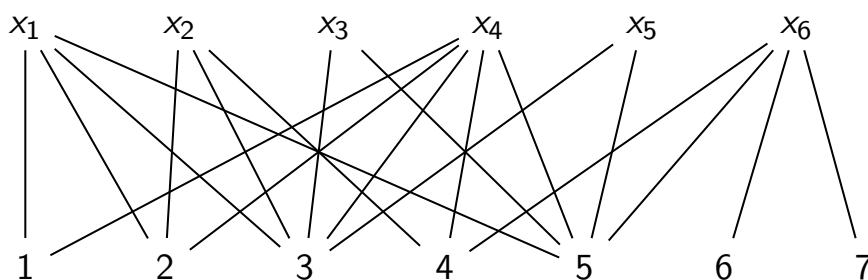
- The constraint can be a clause: arc consistency corresponds to **unit propagation**
- The constraint can be a primitive relation (e.g., ' $\leq$ ') and arc consistency is easy and efficient
  - ▶ Propagation of  $x \leq y$ :
    - ★ Event *lower bound of  $x$  ( $\min(x)$ ) has changed*: update  $\min(y)$  to  $\min(x)$
    - ★ Event *upper bound of  $y$  has changed*: update  $\max(x)$  to  $\max(y)$
    - ★ Do not wake up on other events
- Can be a much larger and more complex relation, even an **NP-hard** relation
  - ▶ E.g., "the graph given by the incidence matrix  $x$  is a clique of size greater than or equal to  $y$ "
  - ▶ Arc consistency is not required for correctness (and is **NP-hard** when the constraint relation is **NP-hard**)

- $\text{ALLDIFFERENT}(x_1, \dots, x_n) \Leftrightarrow \forall 1 \leq i < j \leq n, x_i \neq x_j$
- For instance:  $\text{ALLDIFFERENT}(x_1, x_2, x_3, x_4)$ 
  - ▶  $\mathcal{D}(x_1) = \{1\}$
  - ▶  $\mathcal{D}(x_2) = \{1, 2, 3\} \mathcal{D}(x_2) = \{2, 3\}$
  - ▶  $\mathcal{D}(x_3) = \{1, 2, 3\} \mathcal{D}(x_3) = \{2, 3\}$
  - ▶  $\mathcal{D}(x_4) = \{1, 2, 3, 4\} \mathcal{D}(x_4) = \{4\}$
- Only two solutions:  $(1, 2, 3, 4)$  and  $(1, 3, 2, 4)$ , therefore:
  - ▶  $x_2 = 1, x_3 = 1, x_4 = 1, x_4 = 2, x_4 = 3$  are not *viable*
- How can we compute that *efficiently*?
  - ▶ Generating and testing the validity all permutations would take exponential time

●  $\text{ALLDIFFERENT}(x_1, \dots, x_n) \Leftrightarrow \forall 1 \leq i < j \leq n, x_i \neq x_j$

● For instance:  $\text{ALLDIFFERENT}(x_1, x_2, x_3, x_4, x_5, x_6)$

- ▶  $\mathcal{D}(x_1) = \{1, 2, 3, 5\}$
- ▶  $\mathcal{D}(x_2) = \{2, 3, 4\}$
- ▶  $\mathcal{D}(x_3) = \{3, 5\}$
- ▶  $\mathcal{D}(x_4) = \{1, 2, 3, 4, 5\}$
- ▶  $\mathcal{D}(x_5) = \{3, 5\}$
- ▶  $\mathcal{D}(x_6) = \{4, 5, 6, 7\}$



- A solution of the  $\text{ALLDIFFERENT}$  constraint is a *maximal matching* of the graph
- We can compute a maximal matching in  $O(n^{\frac{3}{2}}m)$  (Hopcroft Karp)
- Cycle: alternative matching. *Strongly Connected Components* are set of vertices all pairwise connected by a cycle. Tarjan's Algorithm finds them all in  $O(nm)$
- An edge  $(x, v)$  belongs to a strongly connected component iff the value  $v$  is viable for  $x \Rightarrow$  pruning!

- $\text{ALLDIFFERENT}(x_1, \dots, x_n) \Leftrightarrow \forall 1 \leq i < j \leq n, x_i \neq x_j$
- For instance:  $\text{ALLDIFFERENT}(x_1, x_2, x_3, x_4, x_5, x_6)$ 
  - ▶  $\mathcal{D}(x_1) = \{1, 2, 3, 5\}$
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  - ▶  $\mathcal{D}(x_3) = \{3, 5\}$
  - ▶  $\mathcal{D}(x_4) = \{1, 2, 3, 4, 5\}$
  - ▶  $\mathcal{D}(x_5) = \{3, 5\}$
  - ▶  $\mathcal{D}(x_6) = \{4, 5, 6, 7\}$
- ▶  $\mathcal{D}(x_1) = \{1, 2\}$
  - ▶  $\mathcal{D}(x_2) = \{2, 4\}$
  - ▶  $\mathcal{D}(x_3) = \{3, 5\}$
  - ▶  $\mathcal{D}(x_4) = \{1, 2, 4\}$
  - ▶  $\mathcal{D}(x_5) = \{3, 5\}$
  - ▶  $\mathcal{D}(x_6) = \{6, 7\}$

- When and how propagators are called?
- Typically via a *Constraint Queue* and an *Event Stack*
- The event stack contains events corresponding to domain *reduction*
  - ▶ Variable  $x$  is assigned a value  $v$
  - ▶ The lower (resp. upper) bound of variable  $x$  has increased (resp. decreased)
  - ▶ The domain of variable  $x$  has lost at least one value
  - ▶ The domain of variable  $x$  has lost at value  $v$
- Every propagator *watches* some events

### Algorithm 0: Constraint Propagation

```

repeat
    while Event-Stack  $\neq \emptyset$  do
        e  $\leftarrow$  Event-Stack.pop-back();
        foreach c  $\in$  Watchers(e) do
            Constraint-Queue.add(c);
    if Constraint-Queue  $\neq \emptyset$  then
        c  $\leftarrow$  Constraint-Queue.pop-priority();
        c.propagate(e);
        /* might push events on the event stack */
until Event-Stack =  $\emptyset$ ;

```

7 8 9 4 5 6 1 2 3	2	7 8 9 4 5 6 1 2 3	5	7 8 9 4 5 6 1 2 3	1	7 8 9 4 5 6 1 2 3	9	7 8 9 4 5 6 1 2 3
8	7 8 9 4 5 6 1 2 3	7 8 9 4 5 6 1 2 3	2	7 8 9 4 5 6 1 2 3	3	7 8 9 4 5 6 1 2 3	7 8 9 4 5 6 1 2 3	6
7 8 9 4 5 6 1 2 3	3	7 8 9 4 5 6 1 2 3	7 8 9 4 5 6 1 2 3	6	7 8 9 4 5 6 1 2 3	7 8 9 4 5 6 1 2 3	7	7 8 9 4 5 6 1 2 3
7 8 9 4 5 6 1 2 3	7 8 9 4 5 6 1 2 3	1	7 8 9 4 5 6 1 2 3	7 8 9 4 5 6 1 2 3	7 8 9 4 5 6 1 2 3	6	7 8 9 4 5 6 1 2 3	7 8 9 4 5 6 1 2 3
5	4	7 8 9 4 5 6 1 2 3	7 8 9 4 5 6 1 2 3	7 8 9 4 5 6 1 2 3	7 8 9 4 5 6 1 2 3	7 8 9 4 5 6 1 2 3	1	9
7 8 9 4 5 6 1 2 3	7 8 9 4 5 6 1 2 3	2	7 8 9 4 5 6 1 2 3	7 8 9 4 5 6 1 2 3	7 8 9 4 5 6 1 2 3	7	7 8 9 4 5 6 1 2 3	7 8 9 4 5 6 1 2 3
7 8 9 4 5 6 1 2 3	9	7 8 9 4 5 6 1 2 3	7 8 9 4 5 6 1 2 3	3	7 8 9 4 5 6 1 2 3	7 8 9 4 5 6 1 2 3	8	7 8 9 4 5 6 1 2 3
2	7 8 9 4 5 6 1 2 3	7 8 9 4 5 6 1 2 3	8	7 8 9 4 5 6 1 2 3	4	7 8 9 4 5 6 1 2 3	7 8 9 4 5 6 1 2 3	7
7 8 9 4 5 6 1 2 3	1	7 8 9 4 5 6 1 2 3	9	7 8 9 4 5 6 1 2 3	7	7 8 9 4 5 6 1 2 3	6	7 8 9 4 5 6 1 2 3

7 4 6	2	7 4 6	5	7 8	1	4 8 3	9	4 8 3
8	7 5	7 4 5 9	2	7 9	3	4 5 1	4 5	6
9 1	3	5 9	4	6	8 9	8 5 1 2	7	8 5 1 2
7 9 3	7 8	1	7 3	7 8 9 4 5 2	8 9 5 2	6	4 5 2 3	8 4 5 2 3
5	4	7 8 6 3	7 6 3	7 8 2	8 2 6	8 2 3	1	9
9 6 3	8 6	2	6 1 3	8 9 4 5 1	8 9 5 6	7	4 5 3	8 4 5 3
7 4 6	9	7 4 5 6	6 1	3	5 6 2	4 5 1 2	8	4 5 1 2
2	5 6	5 6 3	8 1	5	4	9 5 3	5 3	7
4 3	1	8 4 5 3	9	5 2	7	4 5 2 3	6	4 5 2 3

7 4 6	2	7 4 6	5	7 8	1	4 8 3	9	4 8 3
8	7 5	7 4 5 9	2	7 9	3	4 5 1	4 5	6
1	3	5 9	4	6	8 9	8 5 1 2	7	8 5 1 2
7 9 3	7 8	1	7 3	7 8 9 4 5	8 9 5	6	2	4 8 5 3
5	4	7 6 3	7 6 3	7 8 2	8 6 2	8 3	1	9
9 6 3	8 6	2	6 4 5 1 3 1	8 9 4 5	8 9 5 6	7	4 5 3	8 4 5 3
7 4 6	9	7 4 5 6	6 1	3	5 6 2	4 5 1 2	8	4 5 1 2
2	5 6	5 6 3	8	5 1	4	9	5 3	7
4 3	1	8	9	5 2	7	4 5 2 3	6	4 5 2 3

7 4 6	2	7 4 6	5	7 8	1	4 8 3	9	4 8 3
8	7 5	7 4 5 9	2	7 9	3	1	4 5	6
1	3	5 9	4	6	8 9	8 5 2	7	8 5 2
7 9 3	7 8	1	7 3	4 8 9 5	8 9 5	6	2	4 8 5 3
5	4	7 6 3	7 3	8 2	8 6 2	8 3	1	9
9 6 3	8 6	2	1	8 9 4 5	8 9 5 6	7	4 5 3	8 4 5 3
7 4	9	7 4 5	6	3	5 2	4 5 2	8	1
2	5 6	5 6 3	8	1	4	9	5 3	7
4 3	1	8	9	5 2	7	4 5 2 3	6	4 5 2 3

4	2	6	5	7	1	3	9	8
8	5	7	2	9	3	1	4	6
1	3	9	4	6	8	2	7	5
9	7	1	3	8	5	6	2	4
5	4	3	7	2	6	8	1	9
6	8	2	1	4	9	7	5	3
7	9	4	6	3	2	5	8	1
2	6	5	8	1	4	9	3	7
3	1	8	9	5	7	4	6	2

$$\sum_{i=1}^n a_i x_i = K$$

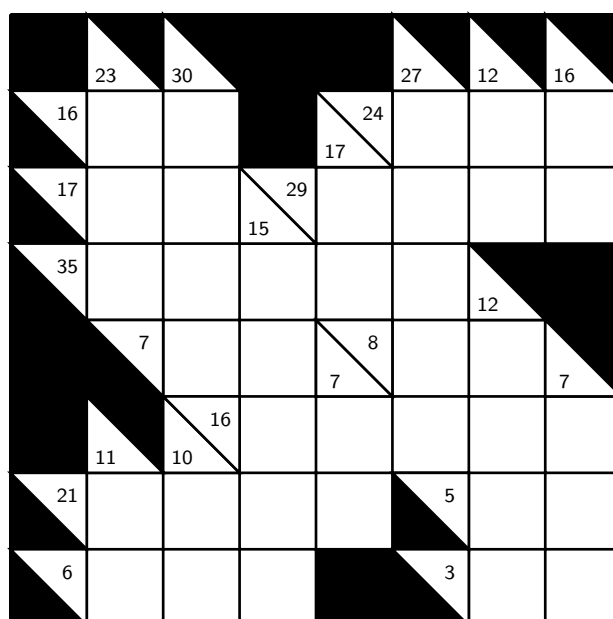
- SUBSET SUM: given a set of integers and an integer  $K$ , does there exist a subset whose sum is equal to  $K$ 
  - ▶ A variable with domain  $\{0, 1\}$  for each integer, coefficients are the integers
- Finding a support is NP-hard
  - ▶ Therefore, achieving AC is NP-hard
  - ▶ Achieving BC is NP-hard too, since on  $\{0, 1\}$  domains, a bounds support is a support
- However, one can enforce BC on each conjunct of:

$$\sum_{i=1}^n a_i x_i \leq K \text{ and } \sum_{i=1}^n a_i x_i \geq K$$



$$\sum_{i=1}^n a_i x_i \leq K$$

- Assume that all coefficients are positive
- $\max(x_i) + \sum_{j=1}^n a_j \min(x_j) - \min(x_i) \leq K$ 
  - ▶  $x_i \leq K - \sum_{j=1}^n a_j \min(x_j) + \min(x_i)$
- $\min(x_i) + \sum_{j=1}^n a_j \max(x_j) - \max(x_i) \geq K$ 
  - ▶  $x_i \geq K - \sum_{j=1}^n a_j \max(x_j) + \max(x_i)$



- $\sum_{i=1}^6 x_i = 39$
- $\text{ALLDIFFERENT}(\{x_1, \dots, x_6\}, \{1, \dots, 9\})$

$x_1 : \{ \quad \quad \quad \quad \quad 8 \ 9 \}$   
 $x_2 : \{ 1 \ 2 \quad \quad \quad 6 \ 7 \ 8 \ 9 \}$   
 $x_3 : \{ \quad \quad \quad \quad \quad 8 \ 9 \}$   
 $x_4 : \{ 1 \quad \quad \quad 5 \ 6 \quad \quad 8 \ 9 \}$   
 $x_5 : \{ 1 \ 2 \quad \quad \quad 6 \ 7 \ 8 \ 9 \}$   
 $x_6 : \{ \quad \quad \quad 4 \ 5 \quad \quad \quad 8 \ 9 \}$



## Propagation

- $\sum_{i=1}^6 x_i = 39$
- $\text{ALLDIFFERENT}(\{x_1, \dots, x_6\}, \{1, \dots, 9\})$

$x_1 : \{ \quad \quad \quad \quad \quad 8 \ 9 \}$   
 $x_2 : \{ 1 \ 2 \quad \quad \quad 6 \ 7 \quad \quad \}$   
 $x_3 : \{ \quad \quad \quad \quad \quad 8 \ 9 \}$   
 $x_4 : \{ 1 \quad \quad \quad 5 \ 6 \quad \quad \}$   
 $x_5 : \{ 1 \ 2 \quad \quad \quad 6 \ 7 \quad \quad \}$   
 $x_6 : \{ \quad \quad \quad 4 \ 5 \quad \quad \quad \}$

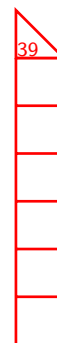


## Propagation

- $\text{ALLDIFFERENT}(\{x_1, x_3\}, \{8, 9\})$

- $\sum_{i=1}^6 x_i = 39$
- $\text{ALLDIFFERENT}(\{x_1, \dots, x_6\}, \{1, \dots, 9\})$

$x_1 : \{ \quad \quad \quad 8 \ 9 \}$   
 $x_2 : \{ \quad \quad 6 \ 7 \quad \}$   
 $x_3 : \{ \quad \quad \quad 8 \ 9 \}$   
 $x_4 : \{ \quad \quad 5 \ 6 \quad \}$   
 $x_5 : \{ \quad \quad 6 \ 7 \quad \}$   
 $x_6 : \{ \quad 4 \ 5 \quad \}$

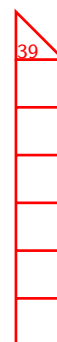


### Propagation

- $\sum_{i=1}^6 x_i = 39$ 
  - ▶  $\Rightarrow \min(x_2) \geq 39 - \sum_{i \neq 2} \max(x_i)$
  - ▶  $\Rightarrow \min(x_2) \geq 3, (\& \min(x_5) \geq 3 \& \min(x_4) \geq 2)$

- $\sum_{i=1}^6 x_i = 39$
- $\text{ALLDIFFERENT}(\{x_1, \dots, x_6\}, \{1, \dots, 9\})$

$x_1 : \{ \quad \quad \quad 8 \ 9 \}$   
 $x_2 : \{ \quad \quad 6 \ 7 \quad \}$   
 $x_3 : \{ \quad \quad \quad 8 \ 9 \}$   
 $x_4 : \{ \quad \quad 5 \quad \quad \}$   
 $x_5 : \{ \quad \quad 6 \ 7 \quad \}$   
 $x_6 : \{ \quad 4 \quad \quad \}$



### Propagation

- $\text{ALLDIFFERENT}(\{x_2, x_5\}, \{6, 7\})$
- $\text{ALLDIFFERENT}(\{x_4\}, \{5\})$

## 1 Constraint Programming

## 2 Clause Learning in CP

- Constraint programming has powerful propagation algorithm
- Example, Kakuro:

### Constraint Programming

- ▶ One variable  $x_{i,j} \in \{1, \dots, 9\}$  for every cell
- ▶ For every clue:
  - ★ One ALLDIFFERENT constraint and two CARDINALITY constraints

- But **no clause learning!**

- ▶ Clause learning was developed in CP (even before zChaff and GRASP) but was not as successful

### SAT Encoding

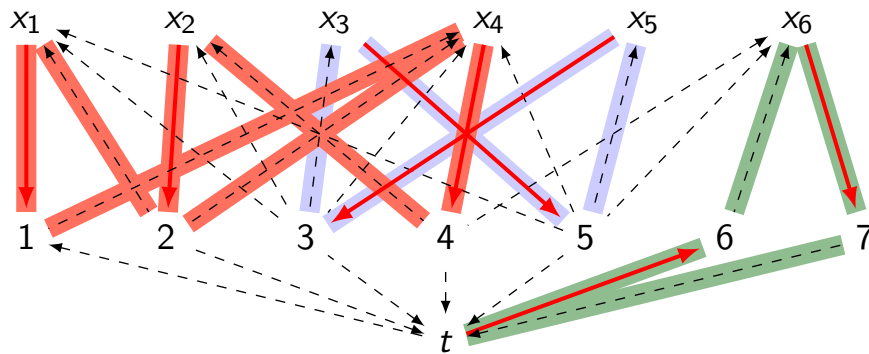
- ▶ One variable  $x_{i,j,v}$  for every cell and every  $v \in \{1, \dots, 9\}$  plus a linear number of clauses (somewhat equivalent)
- ▶ For every clue of size  $n$ :
  - ★  $9(n-1)n/2$  binary clauses to encode ALLDIFFERENT: unit propagation is **not as strong as** constraint propagation on ALLDIFFERENT
  - ★ SAT encoding of cardinality: unit propagation is **not as efficient as** constraint propagation on CARDINALITY

- There are efficient encoding of domains, e.g., *sequential counters*
  - ▶  $x_v$ : variable  $x$  takes value  $v$ ,  $s_v$ : variable  $x$  lower than or equal to  $v$
- Same space complexity ( $O(|\mathcal{D}|)$ )
- Domain change slightly less efficient
  - ▶ Assignment, value removal and bound change take  $O(|\mathcal{D}|)$  time in the SAT encoding
  - ▶ They are in constant time in CP
  - ▶ However, amortized to the same worst-case down a branch (removing all values one at a time takes  $O(|\mathcal{D}|)$  time in both cases)
  - ▶ There are many more *read* operations than *write* operations
- Domain events correspond to *domain literals*:
  - ▶ Upper bound of  $x$  has changed to  $v$ :  $s_v$
  - ▶ Lower bound of  $x$  has changed to  $v$ :  $s_v^-$
  - ▶ Value  $v$  was removed from the domain of  $x$ :  $\bar{x}_v$
  - ▶ Value  $v$  has been assigned to variable  $x$ :  $x_v$

- Initially only *domain clauses*, constraints are propagated as in CP
- For every domain reduction  $/$  made by propagating a constraint generate an asserting explanation clause  $(p_1 \vee p_2 \vee \dots \vee /)$ 
  - ▶ Used during conflict analysis, but *not* for unit propagation (the propagator already does this pruning)
  - ▶ Learn first UIP clauses exactly as **CDCL** (and unit propagate them)
- Every constraint has a dedicated propagation algorithm *and an explanation algorithm*
  - ▶ Explanation clauses can be generated *a posteriori* (during conflict analysis) to avoid unnecessary calls to the explanation algorithm

[Katsirelos & Bacchus]

- Propagation of  $x \leq y$ :
  - ▶ Event  $\bar{x}_v$  (lower bound of  $x$  has changed to  $v + 1$ ): triggers  $\bar{y}_v$ 
    - ★ Explanation clause  $(x_v \vee \bar{y}_v)$
  - ▶ Event  $y_v$  (upper bound of  $y$  has changed): triggers  $x_v$ 
    - ★ Explanation clause  $(x_v \vee \bar{y}_v)$
- Suited for lazy explanation: the context is irrelevant



- Strongly connected components that do not include  $t$  have as many variables as values (*Hall sets*)
  - ▶ The only way to a free value is via  $t$
- Consider any edge  $(v \rightarrow x)$  connecting a Hall set to a distinct SCC
  - ▶ There cannot be an edge between  $x$  and the Hall set of  $v$  otherwise the SCCs would not be distinct
- A *Hall set* is a set of variables  $\mathcal{X}$  such that  $|\bigcup_{x \in \mathcal{X}} \mathcal{D}(x)| = |\mathcal{X}|$ 
  - ▶ An edge  $(v \rightarrow x)$  is arc inconsistent if **and only if**  $v$  is in a Hall set and  $x$  is not in the same SCC

- For instance:  $\text{ALLDIFFERENT}(x_1, x_2, x_3, x_4)$ 
  - ▶  $\mathcal{D}(x_1) = \{1, 2, 3\}$
  - ▶  $\mathcal{D}(x_2) = \{1, 2, 3\}$
  - ▶  $\mathcal{D}(x_3) = \{1, 2, 3\}$
  - ▶  $\mathcal{D}(x_4) = \{1, 2, 3, 4\}$
- $\{1, 2, 3\}$  is a Hall set, therefore  $\{1, 2, 3\}$  are not viable for  $x_4$
- We can use the Hall set as explanation clause:

$$\begin{aligned}
 (s_{1,3} \wedge s_{2,3} \wedge s_{3,3}) &\implies \neg s_{4,3} \\
 &\iff \\
 (\neg s_{1,3} \vee \neg s_{2,3} \vee \neg s_{3,3} \vee \neg s_{4,3})
 \end{aligned}$$

(i.e., if  $x_1 \leq 3$  and  $x_2 \leq 3$  and  $x_3 \leq 3$ , then  $x_4 > 3$ )

- Mapping between CSP variables and Boolean variables (can be implicit)
- Propagation of the original constraints is done via propagators (dedicated algorithms)
- Propagators generate explanation clauses, used to encode the *conflict graph*
- Learn First-UIP clauses with this conflict graph
- Propagate the learnt clauses via unit-propagation