

Algorithms for Computational Logic

Introduction

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Outline

1 Extensions

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- Pseudo Boolean Optimisation
- Cutting Planes

Facility Location Problem

Suppose that a company has to decide where to install new factories from n potential locations in order to be able to serve m clients.

Let c_i denote the cost for opening a factory at location i and let d_{ij} denote the cost of serving client j from location i .

Provide a formulation that helps the administration to decide where to open the factories such that the overall costs (factory open and serving clients) are minimized.

Facility Location Problem

- Problem variables

- ▶ x_i : denotes if a factory is to be open at location i
- ▶ y_{ij} : denotes if client j is served from location i

$$\begin{aligned}
 &\text{Minimize} && \sum_{i=1}^n c_i x_i + \sum_{i=1}^n \sum_{j=1}^m d_{ij} y_{ij} \\
 &\text{Subject to} && \sum_{i=1}^n y_{ij} = 1 && \forall j \in \{1 \dots m\} \\
 &&& x_i - y_{ij} \geq 0 && \forall i \in \{1 \dots n\}, j \in \{1 \dots m\} \\
 &&& x_i \in \{0, 1\}, y_{ij} \in \{0, 1\}
 \end{aligned}$$

Pseudo-Boolean Optimization (PBO)

Formulation

$$\begin{aligned}
 &\text{Minimize} && \sum_{j=1}^n c_j x_j \\
 &\text{Subject to} && \sum_{j=1}^n a_{ij} x_j && \{\geq, =, \leq\} && b_i \\
 &&& x_j \in \{0, 1\} && \forall j \in \{1, 2, \dots, n\}
 \end{aligned}$$

- 0-1 Integer Linear Programming (0-1 ILP)

- If we identify $\{\text{false}, \text{true}\}$ to $\{0, 1\}$, a clause $(x \vee y \vee z)$ is equivalent to $x + y + z \geq 1$
 - ▶ $(x \vee \bar{y} \vee z)$ is $x + (1 - y) + z \geq 1$
- Not quite *Integer Programming* because the domain is Boolean
 - ▶ Particular case

Algorithmic Solutions

- Integer Programming solvers are very powerful
 - ▶ We are not going to discuss Integer Programming
- When there is a linear objective, MaxSAT can be a good approach (we will see MaxSAT)
- In some case, a CDCL-like algorithm can be better than IP
 - ▶ **Replace clauses by cutting planes**

Combination of two constraints

$$\begin{array}{r} \delta \left(\sum_{j=1}^n a_j x_j \leq b \right) \\ \delta' \left(\sum_{j=1}^n a'_j x_j \leq b' \right) \\ \hline \delta \sum_{j=1}^n a_j x_j + \delta' \sum_{j=1}^n a'_j x_j \leq \delta b + \delta' b' \end{array}$$

Rounding can also be applied

$$\begin{array}{r} \sum_{j=1}^n a_j x_j \leq b \\ \hline \sum_{j=1}^n \lfloor a_j \rfloor x_j \leq \lfloor b \rfloor \end{array}$$

- The correctness of the rounding operation follows from $\lfloor x \rfloor + \lfloor y \rfloor \leq \lfloor x + y \rfloor$
- Hence, δ coefficients in cutting plane operations do not need to be integer. Rounding can be safely applied afterwards

Rounding Example

$$\begin{array}{rcl} 0.5(3x_1 + 2x_2 + x_3 + 2x_4 + x_5) & \leq & 5 \\ \hline 1.5x_1 + x_2 + 0.5x_3 + x_4 + 0.5x_5 & \leq & 2.5 \end{array}$$

After rounding: $x_1 + x_2 + x_4 \leq 2$

- Cutting Planes generalize (p-simulate) CNF clause resolution

Example

| | |
|---|---|
| $\begin{array}{rcl} (\bar{x}_1 \vee x_2 \vee x_3) & & \\ (x_2 \vee x_4 \vee \bar{x}_3) & & \\ \hline \bar{x}_1 \vee x_2 \vee x_4 & & \end{array}$ | $\begin{array}{rcl} (1 - x_1) + x_2 + x_3 & \geq & 1 \\ x_2 + x_4 + (1 - x_3) & \geq & 1 \\ (1 - x_1) & \geq & 0 \\ x_4 & \geq & 0 \\ \hline 2(1 - x_1) + 2x_2 + 2x_4 & \geq & 1 \quad \text{addition} \\ (1 - x_1) + x_2 + x_4 & \geq & 1 \quad \text{division} \end{array}$ |
|---|---|

- Cutting planes is a stronger proof system than resolution

Use of Cutting Planes

- Used in branch and bound algorithms for PBO
 - And in the more general case of Integer Linear Programming (ILP)
- Very common at preprocessing (i.e., at the root node of the search tree)
- Algorithms that use cutting plane techniques during the search process are also known as branch and cut algorithms
- Other types of cutting planes exist (e.g., clique cuts)

Backtrack search with Cutting Plane learning

- DPLL-like algorithms for PBO can perform cutting plane learning instead of clause learning
- Replace clause resolution with cutting planes in implication graph analysis
- Important note: It is not guaranteed that the new constraint will be assertive

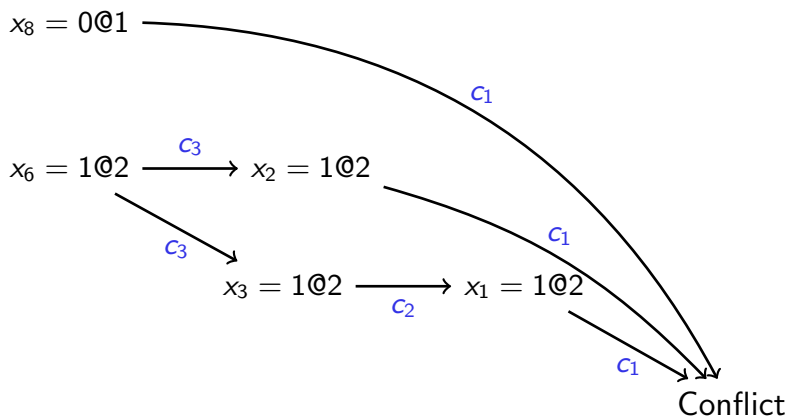
Backtrack search with Cutting Plane learning

Consider the following constraints:

$$\begin{aligned} c_1 : \quad & 3x_1 + x_2 + x_7 - 2x_8 && \leq 3 \\ c_2 : \quad & -3x_1 + x_3 + 2x_7 + x_9 && \leq 0 \\ c_3 : \quad & -x_2 - x_3 + x_6 && \leq -1 - 1 \end{aligned}$$

- Suppose you start with assignment $x_8 = 0$ at first decision level
- Next, you decide to assign $x_6 = 1$. What happens?
- Constraint propagation on c_3 sets $x_2 = 1, x_3 = 1$
- Constraint propagation on c_2 sets $x_1 = 1$
- Constraint c_1 is violated

$$\begin{aligned} c_1 : \quad & 3x_1 + x_2 + x_7 - 2x_8 \leq 3 \\ c_2 : \quad & -3x_1 + x_3 + 2x_7 + x_9 \leq 0 \\ c_3 : \quad & -x_2 - x_3 + x_6 \leq -1 \end{aligned}$$



- Conflict in constraint c_1

- Start backward traversal of graph

Cutting plane between c_1 and c_2 to remove x_1

$$\begin{array}{rcl} 1(3x_1 + x_2 + x_7 - 2x_8 & \leq & 3) \\ 1(-3x_1 + x_3 + 2x_7 + x_9 & \leq & 0) \\ \hline x_2 + x_3 + 3x_7 - 2x_8 + x_9 & \leq & 3 \end{array}$$

Cutting plane with c_3 to remove x_3

$$\begin{array}{rcl} 1(x_2 + x_3 + 3x_7 - 2x_8 + x_9 & \leq & 3) \\ 1(-x_2 + -x_3 + x_6 & \leq & -1) \\ \hline x_6 + 3x_7 - 2x_8 + x_9 & \leq & 2 \end{array}$$

- Backward traversal to the decision variable x_6

- Learned constraint:

$$x_6 + 3x_7 - 2x_8 + x_9 \leq 2$$

- Backtrack to level 1 and assert $x_7 = 0$