# Erratum: Observability implies observer design for switched linear systems 

Proceedings of ACM Conf. on Hybrid Systems: Computation and Control, Pg: 3-12, Chicago, April 2011.

February 14, 2013

1. In the formula for $\mathcal{P}_{1}^{m}$, the subscript of the matrix $G$ must be changed from $G_{j}$ to $G_{i}$. The equation should thus appear as follows:

$$
\mathcal{P}_{1}^{m}:=\left(\mathcal{N}_{1}^{m}\right)^{\perp}=\mathcal{R}\left(G_{1}^{\top}\right)+\sum_{i=2}^{m} \prod_{j=1}^{i-1} e^{A_{j}^{\top} \tau_{j}} E_{j}^{\top} \mathcal{R}\left(G_{i}^{\top}\right) .
$$

2. Equations (8) and (10) hold when all the matrices $E_{i}$ are invertible, and are not true in general otherwise. Another sufficient condition for (8) and (10) to hold is:

$$
\begin{equation*}
\operatorname{ker} E_{i} \subseteq \operatorname{ker} G_{i} \cap \bigcap_{j=i-1}^{2} \prod_{k=i-1}^{j} e^{A_{k+1} \tau_{k+1}} E_{k} \operatorname{ker} G_{j}, \quad \text { for all } i \geq 2 \tag{*}
\end{equation*}
$$

where the left-hand side is simply $\{0\}$ whenever $E_{i}$ is invertible.
3. The invertibility of the jump maps $E_{i}$, or the condition $(*)$, must be included in Assumption 1 for the observer design to be valid.

