

NLVerify

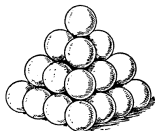
Verification of Polynomial Inequalities using Formal Floating-point Arithmetic

Victor Magron (CNRS VERIMAG)

Joint work with Tillmann Weisser and Benjamin Werner

INRIA Spades Seminar

October 27, 2015



Question:

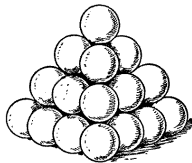
Does $0 \leq x, y \leq 1 \wedge x^2 \leq y$ imply $y - 2x + 1 \geq 0$?

Automated formal proofs for questions like:

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Applications:

- Formal proofs, e. g. Hales proof of the Kepler Conjecture
 - Completed in 2014
 - ~1000 non linear inequalities
 - took ~5000 CPU hours



- Software verification
- System control

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- Taylor/Interval Method
 - Solovyev (HOL)
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$$y - 2x + 1 \in [0, 1] - [2, 2][0, 1] + [1, 1]$$

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Naive Interval Enclosure:

$$y - 2x + 1 \in [0, 1] - [2, 2][0, 1] + [1, 1] \subseteq [-1, 2]$$

(very coarse, very fast, does not use Hypothesis)

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 - Micromega (Besson)
 - NLCertify (Magron)
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Sums-of-Squares:

$$y - 2x + 1 = (x - 1)^2 + (y - x^2)$$

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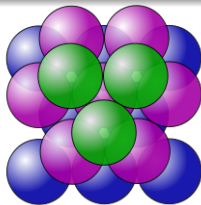
$$y - 2x + 1 = (x - 1)^2 + (y - x^2)$$

tighter but slower, certificate can be computed by external oracles

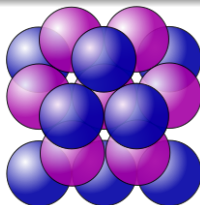
From Oranges Stack...

Kepler Conjecture (1611):

The maximal density of sphere packings in 3D-space is $\frac{\pi}{\sqrt{18}}$



Face-centered cubic Packing



Hexagonal Compact Packing

...to Flyspeck Nonlinear Inequalities

- The proof of T. Hales (1998) contains mathematical and computational parts
- Computation: check thousands of nonlinear inequalities
- Flyspeck [Hales 06]: Formal **P**roof of **K**epler Conjecture

...to Flyspeck Nonlinear Inequalities

- The proof of T. Hales (1998) contains mathematical and computational parts
- Computation: check thousands of nonlinear inequalities
- Flyspeck [Hales 06]: Formal Proof of Kepler Conjecture
- **Project Completion on August 2014 by the Flyspeck team**

A “Simple” Example

In the computational part:

- Multivariate Polynomials:

$\Delta \mathbf{x} :=$

$$x_1x_4(-x_1 + x_2 + x_3 - x_4 + x_5 + x_6) + x_2x_5(x_1 - x_2 + x_3 + x_4 - x_5 + x_6) + x_3x_6(x_1 + x_2 - x_3 + x_4 + x_5 - x_6) - x_2(x_3x_4 + x_1x_6) - x_5(x_1x_3 + x_4x_6)$$

A “Simple” Example

In the computational part:

- Semialgebraic functions: composition of polynomials with $|\cdot|, \sqrt{\cdot}, +, -, \times, /, \sup, \inf, \dots$

$$p(\mathbf{x}) := \partial_4 \Delta \mathbf{x} \qquad q(\mathbf{x}) := 4x_1 \Delta \mathbf{x} \qquad r(\mathbf{x}) := p(\mathbf{x}) / \sqrt{q(\mathbf{x})}$$

$$l(\mathbf{x}) := -\frac{\pi}{2} + 1.6294 - 0.2213 (\sqrt{x_2} + \sqrt{x_3} + \sqrt{x_5} + \sqrt{x_6} - 8.0) + 0.913 (\sqrt{x_4} - 2.52) + 0.728 (\sqrt{x_1} - 2.0)$$

A “Simple” Example

In the computational part:

- Transcendental functions \mathcal{T} : composition of semialgebraic functions with \arctan , \exp , \sin , $+$, $-$, \times , \dots

A “Simple” Example

In the computational part:

- Feasible set $K_{\text{box}} := [4, 6.3504]^3 \times [6.3504, 8] \times [4, 6.3504]^2$

Lemma₉₉₂₂₆₉₉₀₂₈ from Flyspeck:

$$\forall \mathbf{x} \in K_{\text{box}}, \arctan\left(\frac{p(\mathbf{x})}{\sqrt{q(\mathbf{x})}}\right) + l(\mathbf{x}) \geq 0$$

New Framework (in my PhD thesis)

- Certificates for Nonlinear Optimization using SDP and:
 - Maxplus approximation (Optimal Control)
 - Nonlinear templates (Static Analysis)
- Verification of these certificates inside *Coq*:

$$p = \sigma_0 + \sum_j \sigma_j g_j \implies \forall \mathbf{x} \in K_{\text{box}}, \quad p(\mathbf{x}) \geq 0.$$

Introduction

The Oracle

Framework

Interval Methods

Coq Implementation

Benchmarks

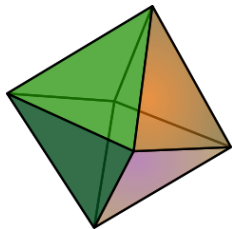
Future Work

A hint on what the oracle is doing:

- Linear Programming (LP):

$$\begin{aligned} \inf_z \quad & c^\top z \\ \text{s.t.} \quad & Fz \geq 0 . \end{aligned}$$

- Linear cost c
- Linear inequalities “ $\sum_i F_{ij} z_j \geq 0$ ”



Polyhedron

A hint on what the oracle is doing:

- Semidefinite Programming (SDP):

$$\begin{aligned} \inf_z \quad & c^\top z \\ \text{s.t.} \quad & \sum_i F_i z_i \succeq 0 . \end{aligned}$$

- Linear cost c
- Symmetric matrices F_i
- Linear matrix inequalities “ $F \succeq 0$ ”
(F has nonnegative eigenvalues)



Spectrahedron

A hint on what the oracle is doing:

Finding an SOS-representation boils down to solving an SDP.

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Finding an SOS-representation boils down to solving an SDP.

There are efficient solvers available to solve SDPs.
(SDPA, CSDP, SDPT3, SeDuMi, Mosek,...)

Example:

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$$\begin{aligned} Y - 2X + 1 &= \begin{pmatrix} 1 & X \end{pmatrix} \begin{pmatrix} 1 - z_8 - z_{10} & (z_8 - z_7 - 2)/2 \\ (z_8 - z_7 - 2)/2 & z_{10} - z_9 + 1 \end{pmatrix} \begin{pmatrix} 1 \\ X \end{pmatrix} \\ &+ \begin{pmatrix} 1 \end{pmatrix} \begin{pmatrix} z_7 \end{pmatrix} \begin{pmatrix} 1 \end{pmatrix} \cdot X \\ &+ \begin{pmatrix} 1 \end{pmatrix} \begin{pmatrix} z_8 \end{pmatrix} \begin{pmatrix} 1 \end{pmatrix} \cdot (1 - X) \\ &+ \begin{pmatrix} 1 \end{pmatrix} \begin{pmatrix} z_9 \end{pmatrix} \begin{pmatrix} 1 \end{pmatrix} \cdot Y \\ &+ \begin{pmatrix} 1 \end{pmatrix} \begin{pmatrix} z_{10} \end{pmatrix} \begin{pmatrix} 1 \end{pmatrix} \cdot (1 - Y) \\ &+ \begin{pmatrix} 1 \end{pmatrix} \begin{pmatrix} z_{10} - z_9 + 1 \end{pmatrix} \begin{pmatrix} 1 \end{pmatrix} \cdot (Y - X^2) \end{aligned}$$

- Find $z_7, z_8, z_9, z_{10} \geq 0$ such that

$$\begin{pmatrix} 1 - z_8 - z_{10} & (z_8 - z_7 - 2)/2 \\ (z_8 - z_7 - 2)/2 & z_{10} - z_9 + 1 \end{pmatrix} \succeq 0.$$

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sdp solvers only find approximate certificates:

$$\begin{aligned} Y - 2X + 1 &\simeq 2.00014(0.707263X + 0.000078Y - 0.70695)^2 \\ &\quad + 0.000332(-0.408035X + 0.816664Y - 0.408126)^2 \\ &\quad + 0.000284Y + 0.000116(1 - Y) + 1.00034(Y - X^2) \end{aligned}$$

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How can we employ such numerical certificates for formal verification?

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How to use numerical certificates in COQ?

tactic

| strategy

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Micromega	uses heuristics to get an exact representation
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How to use numerical certificates in COQ?

tactic	strategy
Micromega	uses heuristics to get an exact representation
NLCertify	gives lower bound on ε by exact computations
NLVerify	use interval arithmetics to bound ε

ε^* := enclosure of ε

General Framework

Consider n -variate polynomials $f, g_0, \dots, g_m \in \mathbb{Q}[\mathbf{X}]$ and a compact set

$$K_{\text{pop}} := \{\mathbf{x} \in \mathbb{R}^n \mid g_0(\mathbf{x}) \geq 0, \dots, g_m(\mathbf{x}) \geq 0\}.$$

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\mathbb{I}		to keep track of rounding errors

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We map rationals to intervals via the *enclosure*

$$\mathbb{Q} \rightarrow \mathbb{I}_p, [a]_p := \left[\max_{x \in \mathbb{F}_p} \{x \mid x \leq a\}, \min_{x \in \mathbb{F}_p} \{x \mid x \geq a\} \right].$$

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Attention!

Interval arithmetic does not carry any ring structure. The enclosure does not commute with the operations in \mathbb{Q} . In general:

$$[a + b]_p \subsetneq [a]_p + [b]_p.$$

Two applications of intervals on polynomials

- Replace coefficients by intervals to speed up computation.
- Replace variables by intervals to obtain bounds on the function.

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Building a *coefficient enclosure* of a polynomial $f \in \mathbb{Q}[\mathbf{X}]$ is done by mapping its coefficients to the corresponding intervals via $[\bullet]_p$. If $f = \sum_{\alpha} f_{\alpha} \mathbf{X}^{\alpha}$, its coefficient enclosure is the set of polynomials

$$[f]_p = \sum_{\alpha} [f_{\alpha}]_p \mathbf{X}^{\alpha} := \left\{ \sum_{\alpha} \hat{f}_{\alpha} \mathbf{X}^{\alpha} \mid \hat{f}_{\alpha} \in [f_{\alpha}]_p \right\}$$

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Keep in mind!

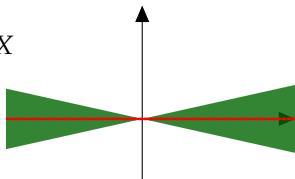
The coefficient enclosure depends on the representation of f .

Two applications of intervals on polynomials

- Replace coefficients by intervals to speed up computation.

Coefficient Enclosure

$$\begin{aligned} f &:= \frac{1}{3}X - \frac{1}{3}X = 0 \\ [f]_2 &= [0.33, 0.34]X - [0.33, 0.34]X \\ [0]_2 &= [0, 0] \end{aligned}$$



Two applications of intervals on polynomials

- Replace variables by intervals to obtain bounds on the function.

Variable Enclosure

The *variable enclosure* $|f|_{\mathbf{B}}$ of a polynomial f with respect to a hyper box $\mathbf{B} = (I_1 \cdots, I_n) \subseteq \mathbb{I}_p^n$ is built by replacing every variable X_i by the corresponding interval I_i . If $f = \sum_{\alpha} f_{\alpha} \mathbf{X}^{\alpha}$, its variable enclosure is

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Of course:

The variable enclosure depends on the representation of f .

Two applications of intervals on polynomials

- Replace variables by intervals to obtain bounds on the function.

Variable Enclosure

Let $\mathbf{B} = [-1, 1] \times [0, 1] \times [0, 1]$. Then

$$\begin{aligned}X(Y - Z) &= XY - YZ \\|X(Y - Z)|_{\mathbf{B}} &= [-1, 1][0, 1] = [-1, 1] \\|XY - XZ|_{\mathbf{B}} &= [-1, 1] - [-1, 1] = [-2, 2]\end{aligned}$$

Two applications of intervals on polynomials

- COEFFICIENT ENCLOSURE
- VARIABLE ENCLOSURE

We are combining both methods and SOS-certification.

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COQVersion:

Lemma toPolI_ok p box pt :
pt ∈ box → eval pt p ∈ Venc1 box (toPolI p).

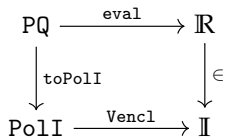
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$$\begin{array}{ccc} \text{PQ} & \xrightarrow{\text{eval}} & \mathbb{R} \\ \downarrow \text{toPolI} & & \downarrow \in \\ \text{PolI} & \xrightarrow{\text{Venc1}} & \mathbb{I} \end{array}$$

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Inductive PQ :=

| PEc : $\mathbb{Q} \rightarrow$ PQ

| PEx : positive \rightarrow PQ

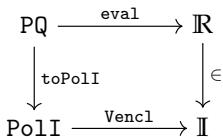
| PEadd: PQ \rightarrow PQ \rightarrow PQ

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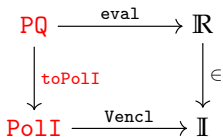
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Inductive PolI :=

- | IPc : $\mathbb{I} \rightarrow$ PolI
- | IPinj: positive \rightarrow PolI \rightarrow PolI
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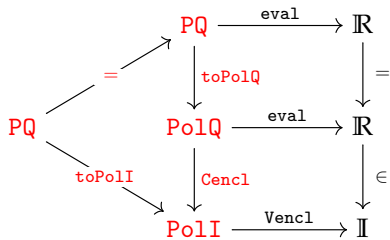


Inductive PQ :=
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Proof:

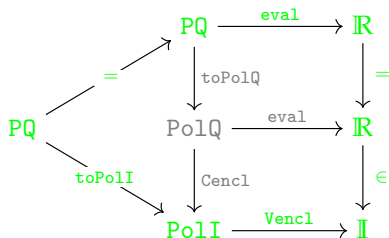


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NLVerify:



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Correctness lemmas for PolQ

For PolQ a correctness lemma looks like:

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Lemma QPadd_ok (p q: PolQ) pt :  
eval pt (p !++ q) = eval pt p + eval pt q.
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Correctness lemmas for PolI

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The direct translation of this lemma to PolI is false.

Correctness lemmas for PolI

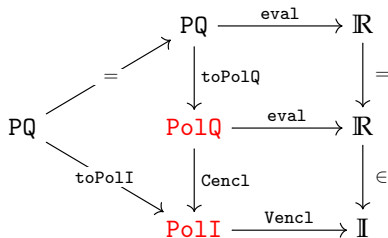
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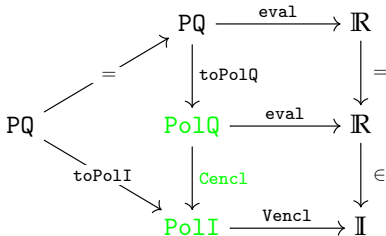
The direct translation of this lemma to PolI is false. A PolI operation can only be correct w.r.t. the underlying PolQ expressions:

```
Lemma Padd_coef_ok (p q: PolQ) (P Q: PolI) :  
p ∈ P -> q ∈ Q -> (p !++ q) ∈ (P ?++ Q).
```

Correctness lemmas for PolI

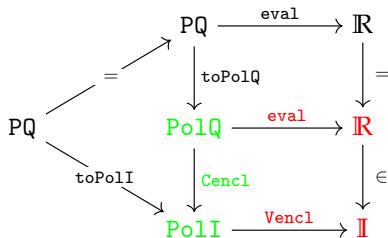


Correctness lemmas for PolI



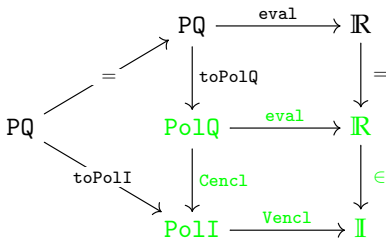
→ Correctness lemmas

Proof of Lemma



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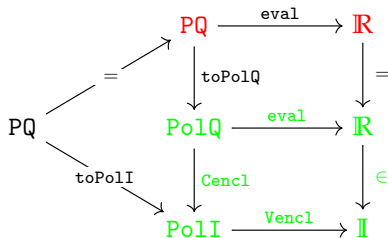
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→ Correctness lemmas

→ easy because of same structure

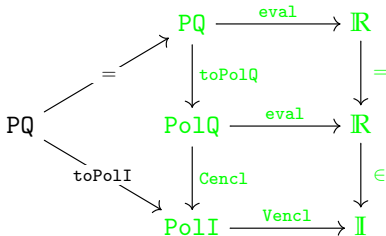
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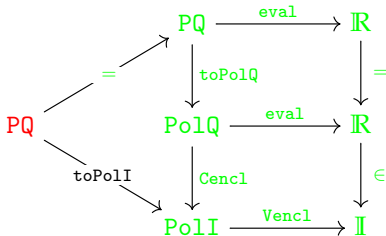
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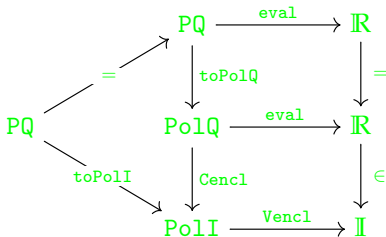
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Proof of Lemma



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Proof of Lemma



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- easy because of same structure
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- follows from the correctness of interval arithmetic

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Speedup NLVerify (p=50) vs. NLCertify

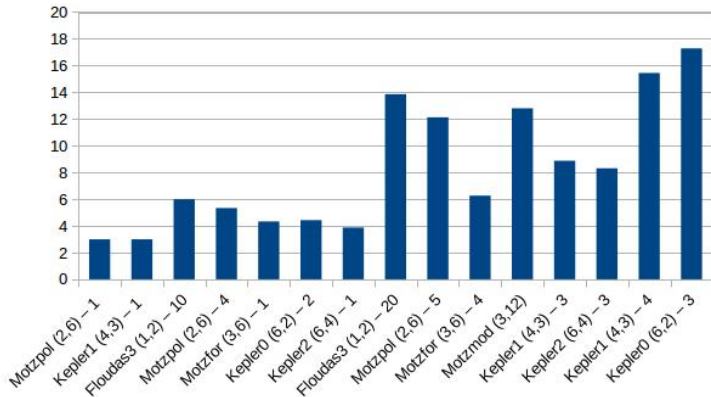
x-Axis: examples (ordered by time_nlc)

y-Axis: ratio time_nlv / time_nlc

Speedup NLVerify (p=50) vs. NLCertify

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Speedup Decreasing Precision

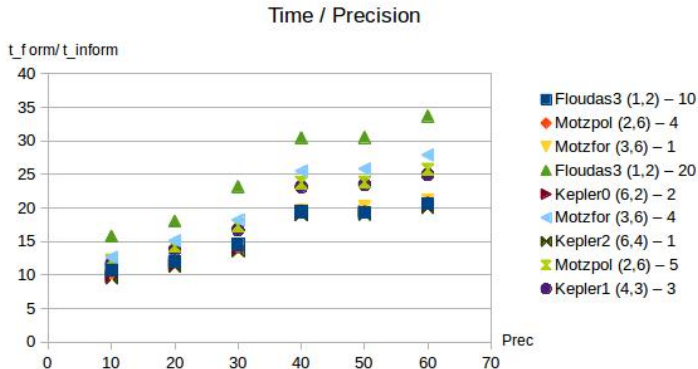
x-Axis: precision

y-Axis: $\text{ratio time_formal} / \text{time_informal}$

Speedup Decreasing Precision

x-Axis: precision

y-Axis: ratio time_formal / time_informal

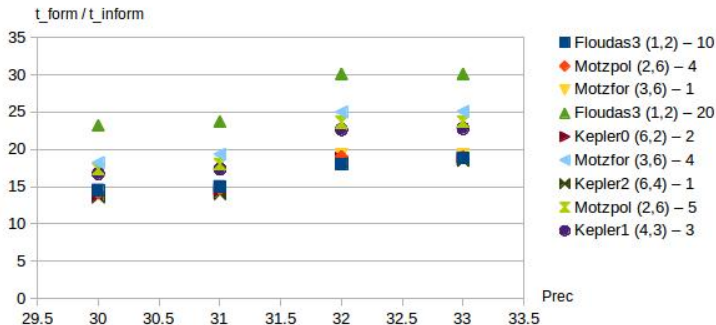


Speedup Decreasing Precision (detail)

x-Axis: precision

y-Axis: ratio time_formal / time_informal

Time / Preciscion (detail)



Precision vs. Accuracy w.r.t. NLCertify

x-Axis: precision

y-Axis: ratio $\varepsilon_p / \varepsilon^*$

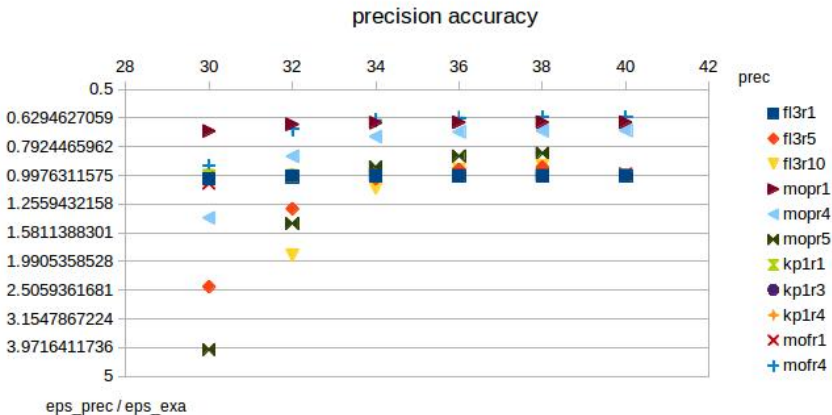
ε_p : loss with NLVerify precision p

ε^* : loss with NLCertify

Precision vs. Accuracy w.r.t. NLCertify

x-Axis: precision
y-Axis: ratio ϵ_p / ϵ^*

ϵ_p : loss with NLVerify precision p
 ϵ^* : loss with NLCertify



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Future Work

- ToDo: Generalization to semi algebraic and transcendental functions
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Future Work

- ToDo: Generalization to semi algebraic and transcendental functions
- Open: Can the performance be improved by using another SDP solver?
- Open: Is Po1I the best polynomial representation for computation?
- Open: Should we use different precisions for the different interval operations?
- Open: Is there a better way to order arithmetic operations in the certificates?
- Open: Would the computation be faster using 50bit words?

Primal-dual Moment-SOS in COQ

- $\mathcal{M}_+(\mathbf{S})$: space of probability measures supported on \mathbf{S}
- $\Sigma[\mathbf{x}]$: polynomial sums of squares

Theory:

$$\begin{array}{ll} \text{(Primal)} & \text{(Dual)} \\ \inf \int_{\mathbf{S}} f d\mu & = \sup \lambda \\ \text{s.t. } \mu \in \mathcal{M}_+(\mathbf{S}) & \text{s.t. } \lambda \in \mathbb{R}, \\ & f - \lambda \in \Sigma[\mathbf{x}] \end{array}$$

Primal-dual Moment-SOS in COQ

- Finite moment sequences \mathbf{z} of measures in $\mathcal{M}_+(\mathbf{S})$
- Truncated quadratic module $\Sigma_k[\mathbf{x}] := \Sigma[\mathbf{x}] \cap \mathbb{R}_{2k}[\mathbf{x}]$

Practice:

(Moment)	=	(SOS)
$\inf \sum_{\alpha} f_{\alpha} \mathbf{z}_{\alpha}$		$\sup \lambda$
s.t. $\mathbf{M}_{k-v_j}(\mathbf{g}_j \mathbf{z}) \succcurlyeq 0, \quad 0 \leq j \leq l,$		s.t. $\lambda \in \mathbb{R},$
$\mathbf{z}_1 = 1$		$f - \lambda \in \Sigma_k[\mathbf{x}]$

End

Thank you for your attention!

<http://www-verimag.imag.fr/~magron>