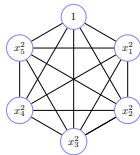
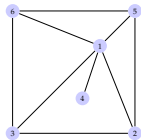


Certified and efficient polynomial optimization via conic programming

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28 January 2020



Motivation: verification of nonlinear systems

SAFETY of critical parts for **computing** \oplus **physical** devices

Cars

Control Software/Hardware



**Smart
Grids**



**Space
Systems**



... **CAST AS CERTIFIED OPTIMIZATION** \rightsquigarrow **SOLVE OFFLINE**

Input: linear  semidefinite  polynomial 

Output: value + numerical/symbolic/formal **certificate**

The Moment-Sums of Squares Hierarchy

NP-hard NON CONVEX Problem $f^* = \inf f(x)$

Theory

(Primal)		(Dual)
$\inf \int f d\mu$		$\sup \lambda$
with μ proba \Rightarrow	INFINITE LP	\Leftarrow with $f - \lambda \geq 0$

The Moment-Sums of Squares Hierarchy

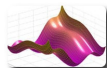
NP-hard NON CONVEX Problem $f^* = \inf f(x)$

Practice

(Primal **Relaxation**)

moments $\int x^\alpha d\mu$

finite number \Rightarrow



SDP

(Dual **Strengthening**)

$f - \lambda =$ **sum of squares**

\Leftarrow **fixed** degree

LASSERRE'S HIERARCHY of **CONVEX PROBLEMS** $\uparrow f^*$
[Lasserre/Parrilo 01]

degree d & n vars $\Rightarrow \binom{n+2d}{n}$ **SDP** VARIABLES

Numeric solvers \Rightarrow **Approx** Certificate

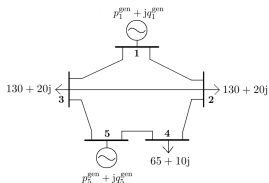


Success Stories: Lasserre's Hierarchy

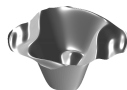
MODELING POWER: Cast as ∞ -dimensional LP over measures

💡 **STATIC Polynomial Optimization**

Optimal Powerflow $n \simeq 10^3$ [Josz et al 16]



💡 **DYNAMICAL Polynomial Optimization**
Regions of attraction [Henrion-Korda 14]



Reachable sets [Magron et al 17]



SDP for Polynomial Optimization

SDP Characterization of Reachable Sets

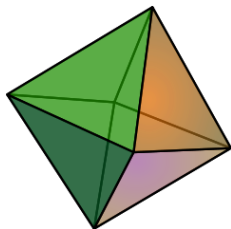
Sparse Polynomial Optimization

Conic Programming: LP

- Linear Programming (LP):

$$\begin{aligned} \min_{\mathbf{z}} \quad & \mathbf{c}^\top \mathbf{z} \\ \text{s.t.} \quad & \mathbf{A} \mathbf{z} \geq \mathbf{d} \end{aligned}$$

- Linear cost \mathbf{c}
- Linear inequalities “ $\sum_i A_{ij} z_j \geq d_i$ ”



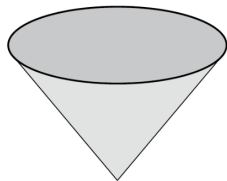
Polyhedron

Conic Programming: SOCP

- Second-order Cone Programming (SOCP):

$$\begin{aligned} \min_{\mathbf{z}} \quad & \mathbf{c}^\top \mathbf{z} \\ \text{s.t.} \quad & z_1 \geq \sqrt{z_2^2 + \dots + z_n^2} \end{aligned}$$

- Linear cost \mathbf{c}
- convex set defined by the linear/quadratic inequalities



**Second-order
Cone**

Conic Programming: SDP

- Semidefinite Programming (SDP):

$$\begin{aligned} \min_{\mathbf{z}} \quad & \mathbf{c}^\top \mathbf{z} \\ \text{s.t.} \quad & \sum_i \mathbf{F}_i z_i \succcurlyeq \mathbf{F}_0 \end{aligned}$$

- Linear cost \mathbf{c}
- Symmetric matrices $\mathbf{F}_0, \mathbf{F}_i$
- Linear matrix inequalities “ $\mathbf{F} \succcurlyeq 0$ ”
(\mathbf{F} has nonnegative eigenvalues)



Spectrahedron

Conic Programming: SDP

- Semidefinite Programming (SDP):

$$\begin{aligned} \min_{\mathbf{z}} \quad & \mathbf{c}^\top \mathbf{z} \\ \text{s.t.} \quad & \sum_i \mathbf{F}_i z_i \succcurlyeq \mathbf{F}_0, \quad \mathbf{A} \mathbf{z} = \mathbf{d}. \end{aligned}$$

- Linear cost \mathbf{c}
- Symmetric matrices $\mathbf{F}_0, \mathbf{F}_i$
- Linear matrix inequalities “ $\mathbf{F} \succcurlyeq 0$ ”
(\mathbf{F} has nonnegative eigenvalues)



Spectrahedron

SDP for Polynomial Optimization

Prove **polynomial inequalities** with SDP:

$$f = a^2 - 2ab + b^2 \geq 0$$

Find \mathbf{z} s.t. $f = \begin{pmatrix} a & b \end{pmatrix} \underbrace{\begin{pmatrix} z_1 & z_2 \\ z_2 & z_3 \end{pmatrix}}_{\succeq 0} \begin{pmatrix} a \\ b \end{pmatrix}$

$$a^2 - 2ab + b^2 = z_1 a^2 + 2z_2 ab + z_3 b^2 \quad (\mathbf{A} \mathbf{z} = \mathbf{d})$$

$$\begin{pmatrix} z_1 & z_2 \\ z_2 & z_3 \end{pmatrix} = \underbrace{\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}}_{\mathbf{F}_1} z_1 + \underbrace{\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}}_{\mathbf{F}_2} z_2 + \underbrace{\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}}_{\mathbf{F}_3} z_3 \succeq \underbrace{\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}}_{\mathbf{F}_0}$$

SDP for Polynomial Optimization

$$\text{Solution } \begin{pmatrix} z_1 & z_2 \\ z_2 & z_3 \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix} \succcurlyeq 0 \quad (\text{eigenvalues } 0 \text{ and } 2)$$

$$a^2 - 2ab + b^2 = (a \quad b) \underbrace{\begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}}_{\succcurlyeq 0} \begin{pmatrix} a \\ b \end{pmatrix} = (a - b)^2$$

Solving **SDP** \implies Finding **SUMS OF SQUARES** certificates

SDP for Polynomial Optimization

NP hard General Problem: $f^* := \min_{\mathbf{x} \in \mathbf{X}} f(\mathbf{x})$

Semialgebraic set $\mathbf{X} = \{\mathbf{x} \in \mathbb{R}^n : g_1(\mathbf{x}) \geq 0, \dots, g_l(\mathbf{x}) \geq 0\}$

SDP for Polynomial Optimization

NP hard General Problem: $f^* := \min_{\mathbf{x} \in \mathbf{X}} f(\mathbf{x})$

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$\mathbf{X} = [0, 1]^2 = \{\mathbf{x} \in \mathbb{R}^2 : x_1(1 - x_1) \geq 0, \quad x_2(1 - x_2) \geq 0\}$

SDP for Polynomial Optimization

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$$\overbrace{x_1 x_2}^f = -\frac{1}{8} + \overbrace{\frac{1}{2} \left(x_1 + x_2 - \frac{1}{2} \right)^2}^{\sigma_0} + \overbrace{\frac{1}{2} x_1(1 - x_1)}^{\sigma_1 g_1} + \overbrace{\frac{1}{2} x_2(1 - x_2)}^{\sigma_2 g_2}$$

SDP for Polynomial Optimization

NP hard General Problem: $f^* := \min_{\mathbf{x} \in \mathbf{X}} f(\mathbf{x})$

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Sums of squares (SOS) σ_j

SDP for Polynomial Optimization

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Sums of squares (SOS) σ_j

Fixed degree: $\mathcal{Q}_r(\mathbf{X}) := \left\{ \sigma_0 + \sum_{j=1}^l \sigma_j g_j, \text{ with } \deg \sigma_j g_j \leq 2r \right\}$

SDP for Polynomial Optimization

Hierarchy of SDP relaxations: $\lambda_r := \sup_{\lambda} \{ \lambda : f - \lambda \in \mathcal{Q}_r(\mathbf{X}) \}$

Convergence guarantees $\lambda_r \uparrow f^*$ [Lasserre 01]

Can be computed with SDP solvers (CSDP, SDPA, MOSEK)

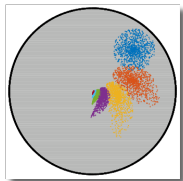
“No Free Lunch” Rule: $\binom{n+2d}{n}$ SDP variables

SDP for Polynomial Optimization

SDP Characterization of Reachable Sets

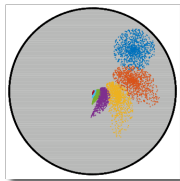
Sparse Polynomial Optimization

SDP Characterization of Reachable Sets



Initial conditions $\mathbf{X}_0 := \{\mathbf{x} \in \mathbb{R}^n : h_j(\mathbf{x}) \geq 0\} \quad h_j \in \mathbb{R}[\mathbf{x}]$

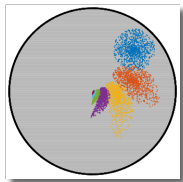
SDP Characterization of Reachable Sets



Initial conditions $\mathbf{X}_0 := \{\mathbf{x} \in \mathbb{R}^n : h_j(\mathbf{x}) \geq 0\}$ $h_j \in \mathbb{R}[\mathbf{x}]$

Polynomial map $f(\mathbf{x}) = (f_1(\mathbf{x}), \dots, f_n(\mathbf{x}))$

SDP Characterization of Reachable Sets



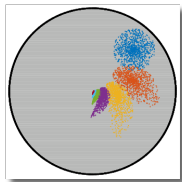
Initial conditions $\mathbf{X}_0 := \{\mathbf{x} \in \mathbb{R}^n : h_j(\mathbf{x}) \geq 0\}$ $h_j \in \mathbb{R}[\mathbf{x}]$

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Reachable Set (RS) of admissible trajectories

$\mathbf{X}^\infty := \{(\mathbf{x}_t)_{t \in \mathbb{N}} : \mathbf{x}_{t+1} = f(\mathbf{x}_t), \mathbf{x}_0 \in \mathbf{X}_0\}$

SDP Characterization of Reachable Sets



Initial conditions $\mathbf{X}_0 := \{\mathbf{x} \in \mathbb{R}^n : h_j(\mathbf{x}) \geq 0\}$ $h_j \in \mathbb{R}[\mathbf{x}]$

Polynomial map $f(\mathbf{x}) = (f_1(\mathbf{x}), \dots, f_n(\mathbf{x}))$

Reachable Set (RS) of admissible trajectories

$\mathbf{X}^\infty := \{(\mathbf{x}_t)_{t \in \mathbb{N}} : \mathbf{x}_{t+1} = f(\mathbf{x}_t), \mathbf{x}_0 \in \mathbf{X}_0\}$

$\mathbf{X}^\infty = \mathbf{X}_0 \cup f(\mathbf{X}_0) \cup f^2(\mathbf{X}_0) \cup \dots \subseteq \mathbf{X}$ (box or ball)

Tractable approximations of RS \mathbf{X}^∞ ?

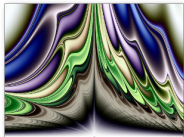
SDP Characterization of Reachable Sets

- Occurs in several contexts :

- 1 program analysis: fixpoint computation

```
toyprogram (x1, x2)
  requires (0.25 ≤ x1 ≤ 0.75 && 0.25 ≤ x2 ≤ 0.75)
  ;
  while (x12 + x22 ≤ 1) {
    x1 = x1 + 2x1x2;
    x2 = 0.5(x2 - 2x13);
  }
```

- 2 hybrid systems, biology: Neuron Model, Growth Model

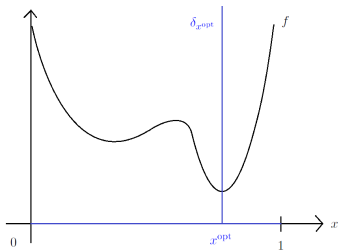


- 3 control: integrator, Hénon map

Characterizing the RS

CHARACTERIZE A VALUE

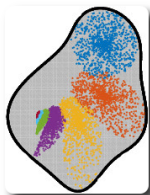
$$f^* = \inf_{\mathbf{x} \in \mathbf{X}} f(\mathbf{x}) = \inf_{\mu \in \mathcal{M}_+(\mathbf{X})} \int_{\mathbf{X}} f d\mu$$



Dirac measure $\mu^* = \delta_{x^{\text{opt}}}$

CHARACTERIZE A SET

?

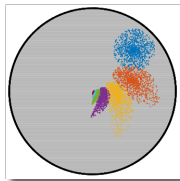


Lebesgue measure $\mu^* = \lambda_{\mathbf{X}}$

Occupation Measures and Liouville's Equation

$$\mathbf{x}_{t+1} = f(\mathbf{x}_t) \quad \mathbf{x}_0 \in \mathbf{X}_0$$

$$\mathbf{x}_1 = f(\mathbf{x}_0) \dots \mathbf{x}_t = f(\mathbf{x}_{t-1})$$



■ Let $\mu_0 \in \mathcal{M}_+(\mathbf{X}_0)$

■ **Pushforward** $f_{\#} : \mathcal{M}_+(\mathbf{X}_0) \rightarrow \mathcal{M}_+(\mathbf{X})$

$$\mu_1(\mathbf{A}) = f_{\#} \mu_0(\mathbf{A}) := \mu_0(f^{-1}(\mathbf{A}))$$

■ $f_{\#} \mu_0$ is the **image measure** of μ_0 under f

Occupation Measures and Liouville's Equation

- Let $\mu_0 \in \mathcal{M}_+(\mathbf{X}_0)$ and

$$\mu_1 = f_{\#} \mu_0$$

...

$$\mu_t = f_{\#} \mu_{t-1}$$

$$\nu_t = \sum_{i=0}^{t-1} \mu_i = \sum_{i=0}^{t-1} f_{\#}^i \mu_0$$

- The measures μ_t, ν_t, μ_0 satisfy **Liouville's Equation**:

$$\mu_t + \nu_t = f_{\#} \nu_t + \mu_0$$

Occupation Measures and Liouville's Equation

- Lebesgue measure $\lambda_{\mathbf{X}_t}$ on $\mathbf{X}_t = f^t(\mathbf{X}_0)$
- $\exists \mu_0 \in \mathcal{M}_+(\mathbf{X}_0)$ s.t. $\lambda_{\mathbf{X}_t} = f_{\#}^t \mu_0$
 $\implies \lambda_{\mathbf{X}_t}$ satisfies **Liouville's Equation**.

Occupation Measures and Liouville's Equation

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- Lebesgue measure $\lambda_{\mathbf{X}^T}$ on $\mathbf{X}^T := \bigcup_{t=0}^T \mathbf{X}_t$
 $\implies \lambda_{\mathbf{X}^T}$ satisfies **Liouville's Equation** by superposition

Occupation Measures and Liouville's Equation

■ Lebesgue measure $\lambda_{\mathbf{X}_t}$ on $\mathbf{X}_t = f^t(\mathbf{X}_0)$

■ $\exists \mu_0 \in \mathcal{M}_+(\mathbf{X}_0)$ s.t. $\lambda_{\mathbf{X}_t} = f_{\#}^t \mu_0$
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■ Lebesgue measure $\lambda_{\mathbf{X}^T}$ on $\mathbf{X}^T := \bigcup_{t=0}^T \mathbf{X}_t$
 $\implies \lambda_{\mathbf{X}^T}$ satisfies **Liouville's Equation** by superposition

$$\lambda_{\mathbf{X}^T} + \nu^T = f_{\#} \nu^T + \mu_0^T$$

average **occupation measure** ν^T : volume occupied in \mathbf{X}^T

Volume Assumption

Discrete Time

Define $\mathbf{Y}^0 = \mathbf{X}^0$ and $\mathbf{Y}^t = \mathbf{X}_t \setminus \mathbf{X}^{t-1}$

$$\lim_{T \rightarrow \infty} \frac{1}{\text{vol}(\mathbf{X})} \sum_{t=0}^T t \text{vol} \mathbf{Y}^t < \infty$$

Volume Assumption

Discrete Time

$$\mathbf{Y}^0 = \mathbf{X}^0 \text{ and } \mathbf{Y}^t = \mathbf{X}_t \setminus \mathbf{X}^{t-1}$$

$$\lim_{T \rightarrow \infty} \underbrace{\frac{1}{\text{vol}(\mathbf{X})} \sum_{t=0}^T t \text{vol } \mathbf{Y}^t}_{\text{average minimal time to reach } \mathbf{X}^T} < \infty$$

Volume Assumption

Discrete Time

$$Y^0 = X^0 \text{ and } Y^t = X_t \setminus X^{t-1}$$

$$\lim_{T \rightarrow \infty} \underbrace{\frac{1}{\text{vol}(X)} \sum_{t=0}^T t \text{vol } Y^t}_{\text{average minimal time to reach } X^T} < \infty$$

Lemma

Under **Volume Assumption**, λ_{X^∞} satisfies **Liouville's Equation**

Infinite Primal LP for Discrete RS

$$\begin{aligned} p^T &:= \sup_{\mu_0, \mu, \nu} \int_{\mathbf{X}} \mu \\ \text{s.t.} \quad & \int_{\mathbf{X}} \nu \leq T \text{vol } \mathbf{X} \\ & \mu + \nu = f_{\#} \nu + \mu_0 \\ & \mu \leq \lambda_{\mathbf{X}} \\ & \mu_0 \in \mathcal{M}_+(\mathbf{X}_0), \quad \mu, \nu \in \mathcal{M}_+(\mathbf{X}) \end{aligned}$$

Infinite Primal LP for Discrete RS

$$\begin{aligned} p^T &:= \sup_{\mu_0, \mu, \nu} \int_{\mathbf{X}} \mu \\ \text{s.t.} \quad & \int_{\mathbf{X}} \nu \leq T \text{vol } \mathbf{X} \\ & \mu + \nu = f_{\#} \nu + \mu_0 \\ & \mu \leq \lambda_{\mathbf{X}} \\ & \mu_0 \in \mathcal{M}_+(\mathbf{X}_0), \quad \mu, \nu \in \mathcal{M}_+(\mathbf{X}) \end{aligned}$$

Lemma

Volume Assumption \implies optimal solution $\mu^* = \lambda_{\mathbf{X}^\infty}$

Primal-dual LP in Discrete Time

Primal LP

$$\begin{aligned} p^T &:= \sup_{\mu_0, \mu, \nu} \int_{\mathbf{X}} \mu \\ \text{s.t.} \quad & \int_{\mathbf{X}} \nu \leq T \text{vol } \mathbf{X} \\ & \mu + \nu = f_{\#} \nu + \mu_0 \\ & \mu \leq \lambda_{\mathbf{X}} \\ & \mu_0 \in \mathcal{M}_+(\mathbf{X}_0) \\ & \mu, \nu \in \mathcal{M}_+(\mathbf{X}) \end{aligned}$$

Dual LP

$$\begin{aligned} d^T &:= \inf_{u, \nu, w} \int_{\mathbf{X}} (w(\mathbf{x}) + T u) d\mathbf{x} \\ \text{s.t.} \quad & \nu \in \mathcal{C}_+(\mathbf{X}_0) \\ & w - \nu - 1 \in \mathcal{C}_+(\mathbf{X}) \\ & w \in \mathcal{C}_+(\mathbf{X}) \\ & u + \nu \circ f - \nu \in \mathcal{C}_+(\mathbf{X}) \\ & u \geq 0 \\ & u \in \mathbb{R}, \nu, w \in \mathcal{C}(\mathbf{X}) \end{aligned}$$

SDP Strengthening of the Dual LP

Discrete Time

$$\begin{aligned}d_r^T &:= \inf_{u,v,w} \int_{\mathbf{X}} (w(\mathbf{x}) + Tu) d\mathbf{x} \\ \text{s.t. } & v \in \mathcal{Q}_r(\mathbf{X}_0) \\ & w - v - 1 \in \mathcal{Q}_r(\mathbf{X}) \\ & u + v \circ f - v \in \mathcal{Q}_{rd}(\mathbf{X}) \\ & w \in \mathcal{Q}_r(\mathbf{X}) \\ & u \geq 0\end{aligned}$$

SDP Strengthening of the Dual LP

Discrete Time

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Theorem [Magron-Garoche-Henrion-Thirioux 19]

$$\mathbf{X}_r^T = \{\mathbf{x} \in \mathbf{X} : v_r(\mathbf{x}) + u_r T \geq 0\} \supseteq \mathbf{X}^T.$$

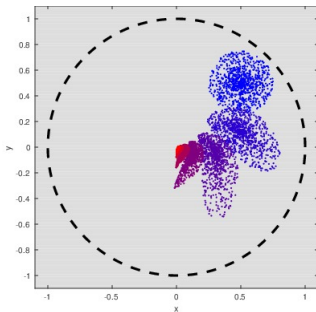
Volume Assumption $\Rightarrow \lim_{r \rightarrow \infty} \text{vol}(\mathbf{X}_r^\infty \setminus \mathbf{X}^\infty) = 0.$

Toy Example

Trajectories from $\mathbf{X}_0 = \{\mathbf{x} \in \mathbb{R}^2 : (x_1 - \frac{1}{2})^2 + (x_2 - \frac{1}{2})^2 \leq \frac{1}{4}\}$ under

$$x_1^+ = \frac{1}{2}(x_1 + 2x_1x_2)$$

$$x_2^+ = \frac{1}{2}(x_2 - 2x_1^3)$$



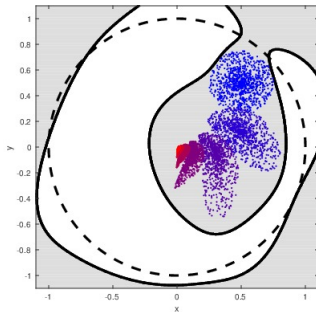
\mathbf{X}_2^∞

Toy Example

Trajectories from $\mathbf{x}_0 = \{\mathbf{x} \in \mathbb{R}^2 : (x_1 - \frac{1}{2})^2 + (x_2 - \frac{1}{2})^2 \leq \frac{1}{4}\}$ under

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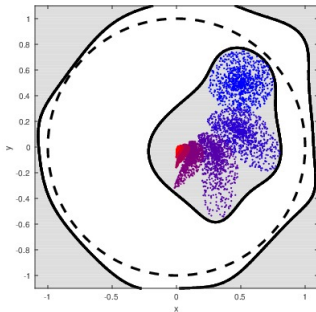
\mathbf{x}_3^∞

Toy Example

Trajectories from $\mathbf{X}_0 = \{\mathbf{x} \in \mathbb{R}^2 : (x_1 - \frac{1}{2})^2 + (x_2 - \frac{1}{2})^2 \leq \frac{1}{4}\}$ under

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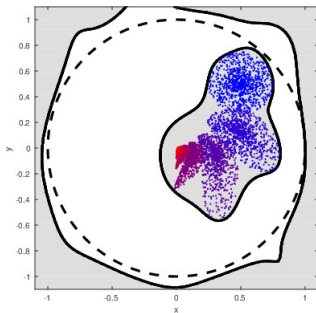
\mathbf{X}_4^∞

Toy Example

Trajectories from $\mathbf{X}_0 = \{\mathbf{x} \in \mathbb{R}^2 : (x_1 - \frac{1}{2})^2 + (x_2 - \frac{1}{2})^2 \leq \frac{1}{4}\}$ under

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$$x_2^+ = \frac{1}{2}(x_2 - 2x_1^3)$$



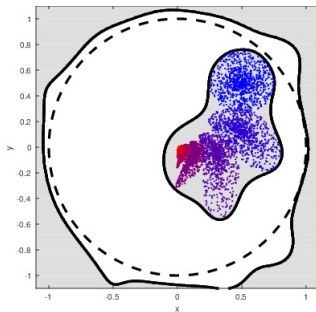
\mathbf{X}_5^∞

Toy Example

Trajectories from $\mathbf{x}_0 = \{\mathbf{x} \in \mathbb{R}^2 : (x_1 - \frac{1}{2})^2 + (x_2 - \frac{1}{2})^2 \leq \frac{1}{4}\}$ under

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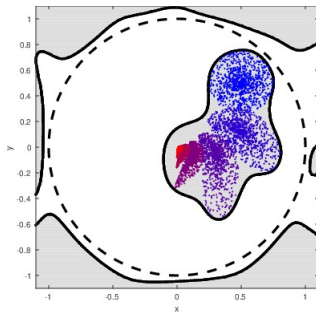
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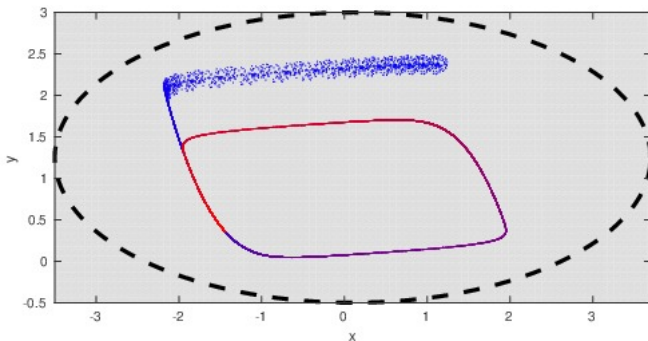
X_7^∞

FitzHugh-Nagumo Neuron Model

Trajectories from $\mathbf{x}_0 = [1, 1.25] \times [2.25, 2.5]$ under

$$x_1^+ = x_1 + 0.2(x_1 - x_1^3/3 - x_2 + 0.875)$$

$$x_2^+ = x_2 + 0.2(0.08(x_1 + 0.7 - 0.8x_2))$$



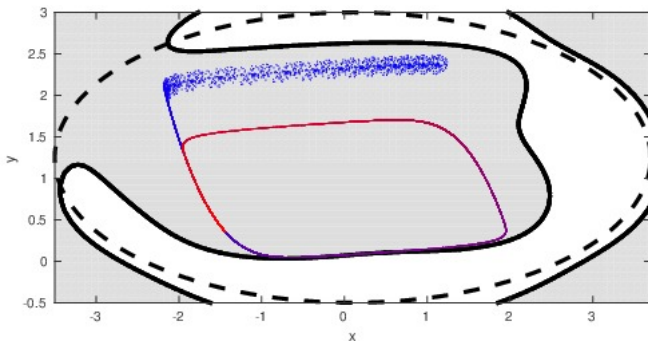
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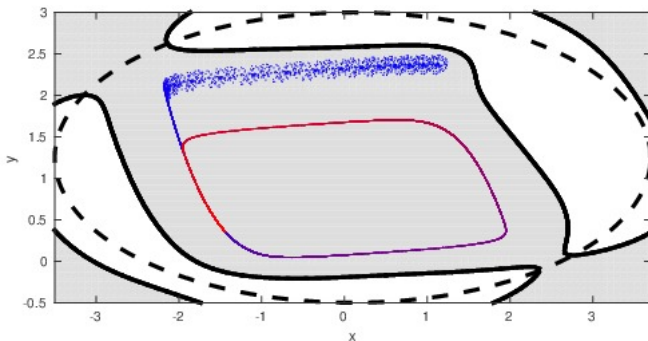
\mathbf{x}_3^∞

FitzHugh-Nagumo Neuron Model

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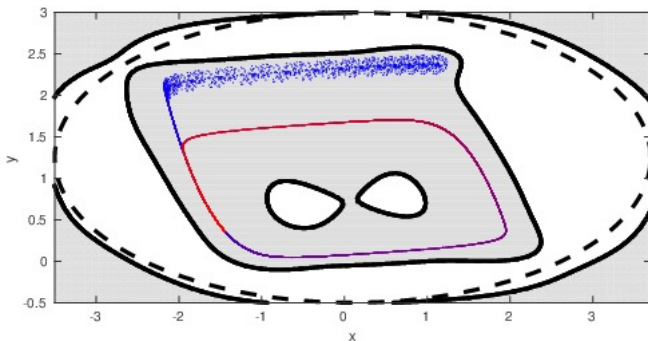
\mathbf{x}_4^∞

FitzHugh-Nagumo Neuron Model

Trajectories from $\mathbf{x}_0 = [1, 1.25] \times [2.25, 2.5]$ under

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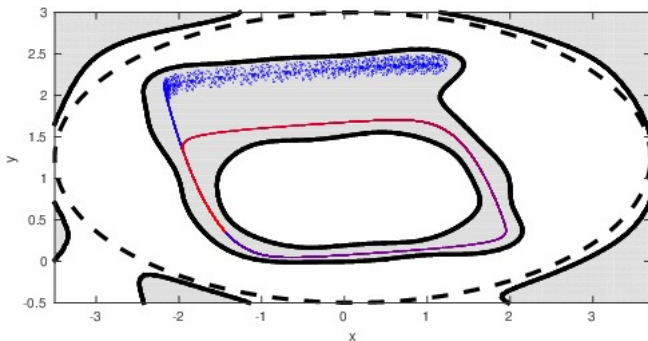
\mathbf{x}_5^∞

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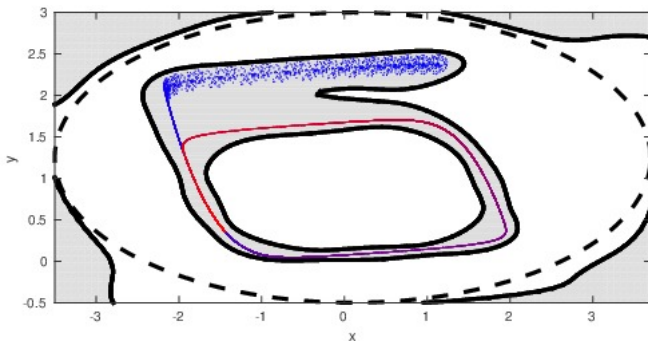
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\mathbf{x}_7^∞

SDP for Polynomial Optimization

SDP Characterization of Reachable Sets

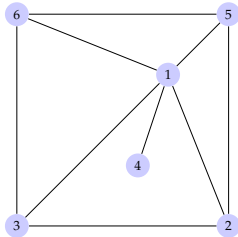
Sparse Polynomial Optimization

Sparse Polynomial Optimization [Waki, Lasserre 06]

- Correlative sparsity pattern (csp) of vars

$$f = x_2x_5 + x_3x_6 - x_2x_3 - x_5x_6 + x_1(-x_1 + x_2 + x_3 - x_4 + x_5 + x_6)$$

Chordal graph G

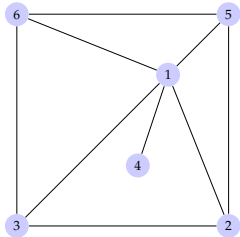


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Chordal graph G



- 1 Maximal cliques C_1, \dots, C_p
- 2 Average size $\kappa \rightsquigarrow \binom{\kappa+2d}{\kappa}$ vars

$$C_1 = \{1, 4\}$$

$$C_2 = \{1, 2, 3, 5\}$$

$$C_3 = \{1, 3, 5, 6\}$$

Dense SDP: 210 vars

Sparse SDP: 115 vars

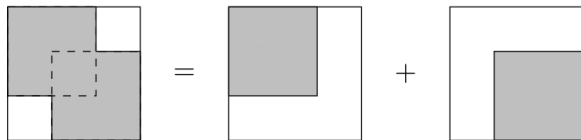
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Theorem [Griewank-Toint 84]

Chordal graph G with maximal cliques C_1, \dots, C_p

$Q_G \succcurlyeq 0$ with nonzero entries at edges of G

$\implies Q_G = \sum_k P_{C_k}^T Q_k P_{C_k}$ with $Q_k \succcurlyeq 0$ indexed by C_k



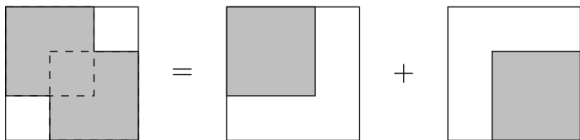
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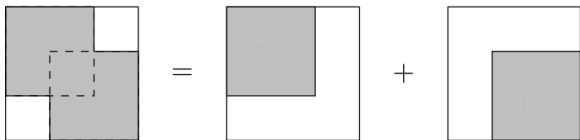
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Theorem: Sparse SOS representation [Waki 06]

f SOS + Chordal Graph G with cliques C_k

$\implies \boxed{f = \sigma_1 + \dots + \sigma_p}$ with σ_k SOS involving vars in C_k

Sparse Examples

Chained singular function:

$$f_{\text{cs}} = \sum_{i \in J} ((x_i + 10x_{i+1})^2 + 5(x_{i+2} - x_{i+3})^2 + (x_{i+1} - 2x_{i+2})^4 + 10(x_i - x_{i+3})^4)$$

$$J = \{1, 3, 5, \dots, n-3\} \ \& \ 4 \mid n$$

$$\text{💡 } C_k = \{k, k+1, k+2, k+3\}$$

Sparse Examples

Chained singular function:

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Generalized Rosenbrock function:

$$f_{gR} = 1 + \sum_{i=1}^{n-1} \left(100(x_{i+1} - x_i^2)^2 + (1 - x_{i+1})^2 \right)$$

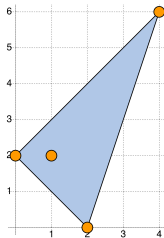
$$\text{💡 } C_k = \{k, k+1\}$$

Exploiting sparsity via Newton polytope

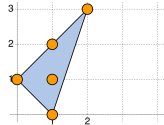
$$f = 4x^4y^6 + x^2 - xy^2 + y^2$$

$$\text{spt}(f) = \{(4, 6), (2, 0), (1, 2), (0, 2)\}$$

$$\text{Newton polytope } \mathcal{P} = \text{conv}(\text{spt}(f))$$



Squares in SOS decomposition $\subseteq \frac{\mathcal{P}}{2} \cap \mathbb{N}^n$
 [Reznick 78]



$$f = \left(x \quad y \quad xy \quad xy^2 \quad x^2y^3 \right) \underbrace{Q}_{\succeq 0} \begin{pmatrix} x \\ y \\ xy \\ xy^2 \\ x^2y^3 \end{pmatrix}$$

Exploiting term sparsity [Wang-Magron-Lasserre 19]

$$f = x^2 - 2xy + 3y^2 - 2x^2y + 2x^2y^2 - 2yz \\ + 6z^2 + 18y^2z - 54yz^2 + 142y^2z^2$$

Newton polytope $\rightarrow f = (1 \ x \ y \ z \ xy \ yz) \underbrace{Q}_{\geq 0}$

$\rightsquigarrow \frac{6 \times 7}{2} = 28$ “unknown” entries in Q

$$\begin{pmatrix} 1 \\ x \\ y \\ z \\ xy \\ yz \end{pmatrix}$$

Exploiting term sparsity [Wang-Magron-Lasserre 19]

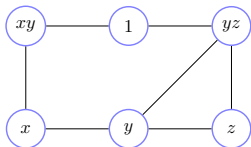
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💡 **Term sparsity pattern graph G**



Exploiting term sparsity [Wang-Magron-Lasserre 19]

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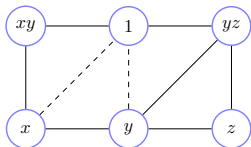
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$$\begin{pmatrix} 1 \\ x \\ y \\ z \\ xy \\ yz \end{pmatrix}$$

💡 **Term sparsity pattern graph G**

Chordal extension



Replace Q by Q_G with nonzero entries at edges of G

$\rightsquigarrow 6 + 9 = 15$ “unknown” entries in Q_G

Lyapunov functions from networked systems

$$f = \sum_{i=1}^N a_i (x_i^2 + x_i^4) - \sum_{i,k=1}^N b_{ik} x_i^2 x_k^2 \quad a_i \in [1, 2] \quad b_{ik} \in \left[\frac{0.5}{N}, \frac{1.5}{N}\right]$$

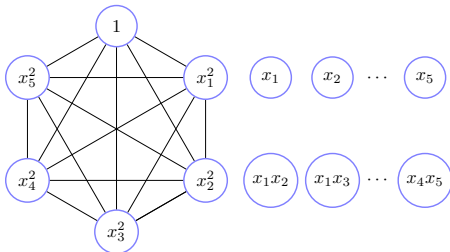
$\rightsquigarrow \binom{N+2}{2} (\binom{N+2}{2} + 1) / 2$ “unknown” entries in $Q = 231$ for $N = 5$

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💡 **tsp** graph G

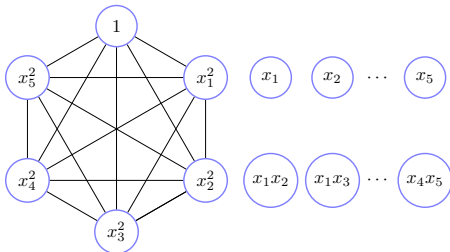


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💡 **tsp** graph G



$\rightsquigarrow (N+1)^2$ “unknown” entries in $Q_G = 36$ for $N = 5$

Proof that $f \geq 0$ for $N = 80$ in ~ 10 seconds!

Network of Duffing oscillators

$$\text{Hamiltonian } V = \sum_{i=1}^N a_i \left(\frac{1}{2} x_i^2 - \frac{1}{4} x_i^4 \right) + \frac{1}{8} \sum_{i,k=1}^N b_{ik} (x_i - x_k)^4$$

On which domain $V > 0$?

$$V - \sum_{i=1}^N \underbrace{\lambda_i}_{>0} x_i^2 (g - x_i^2) \geq 0$$
$$\implies V > 0 \text{ when } x_i^2 < g$$

Network of Duffing oscillators

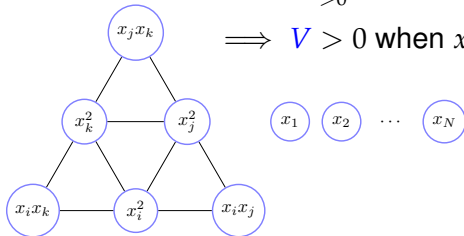
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💡 tsp graph G



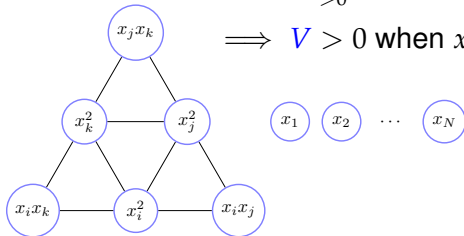
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💡 **tsp graph** G



$$\rightsquigarrow \frac{N(N+1)}{2} + 6\binom{N}{2} + N \text{ "unknown" entries in } Q_G = 80 \text{ for } N = 5$$

Proof that $f \geq 0$ for $N = 50$ in ~ 1 seconds!

Circuit polynomials

$$f = b_{\alpha_1} \mathbf{x}^{\alpha_1} + \cdots + b_{\alpha_r} \mathbf{x}^{\alpha_r} - b_{\beta} \mathbf{x}^{\beta}$$

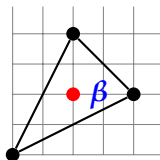
$$b_{\alpha_j} > 0 \quad \alpha_j \in (2\mathbb{N})^n$$

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$$f = 1 + x^2 y^4 + x^4 y^2 - 3x^2 y^2$$

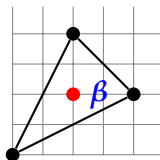


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$$\beta = \lambda_1 \alpha_1 + \cdots + \lambda_r \alpha_r \quad \lambda_j > 0 \text{ and } \lambda_1 + \cdots + \lambda_r = 1$$

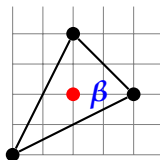
$$\text{Circuit number } \Theta_f = \prod_{j=1}^r \left(\frac{b_{\alpha_j}}{\lambda_j} \right)^{\lambda_j}$$

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Theorem [Illman-de Wolff 16]

$$f \geq 0 \Leftrightarrow |b_{\beta}| \leq \Theta_f \text{ or } (b_{\beta} \geq -\Theta_f, \beta \text{ even})$$

💡 SUMS OF CIRCUITS computed via Geometric programming

Rational mediated sets and SOCP

Averages of distinct rational points in M

$$A(M) := \left\{ \frac{1}{2}(\mathbf{v} + \mathbf{w}) \mid \mathbf{v} \neq \mathbf{w}, \mathbf{v}, \mathbf{w} \in M \right\}$$

M is an \mathcal{A} -rational mediated set if $\mathcal{A} \subseteq M \subseteq A(M) \cup \mathcal{A}$

Rational mediated sets and SOCP

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Theorem [Wang-Magron 20]

There exists an \mathcal{A} -rational mediated set M containing β

Rational mediated sets and SOCP

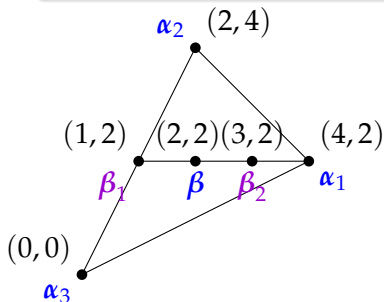
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$$M = \{\alpha_1, \alpha_2, \alpha_3, \beta, \beta_1, \beta_2\}$$

$$\mathbf{u} \in M \setminus \mathcal{A} \implies \mathbf{u} = \mathbf{v} + \mathbf{w}$$

Rational mediated sets and SOCP

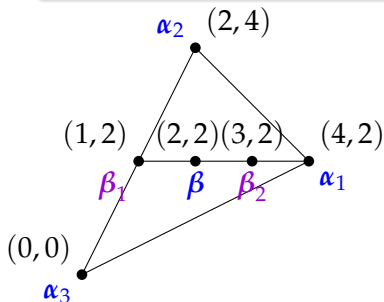
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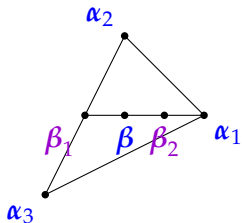
$$\mathbf{u} \in M \setminus \mathcal{A} \implies \mathbf{u} = \mathbf{v} + \mathbf{w}$$

Find a_i, b_i, c_i such that

$$f(\mathbf{x}) = \sum_i 2a_i x^{v_i} + b_i x^{w_i} - 2c_i x^{u_i}$$

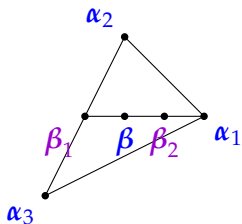
$$(\text{SOCP}) \quad 2a_i b_i \geq c_i^2, \quad a_i, b_i \geq 0$$

Circuits and sums of binomial squares



$$f = (1 - xy^2)^2 + 2(x^{\frac{1}{2}}y - x^{\frac{3}{2}}y)^2 + (xy - x^2y)^2$$
$$\implies \text{sum of 3 binomial squares}$$

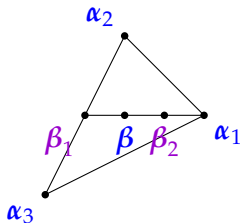
Circuits and sums of binomial squares



$$f = (1 - xy^2)^2 + 2(x^{\frac{1}{2}}y - x^{\frac{3}{2}}y)^2 + (xy - x^2y)^2$$
$$\implies \text{sum of 3 binomial squares}$$

“Arbitrary support” $f = \sum_{\alpha \in \Lambda(f)} c_{\alpha} x^{\alpha} - \sum_{\beta \in \Gamma(f)} d_{\beta} x^{\beta}$
Monomial squares = $\Lambda(f)$ Complement = $\Gamma(f)$

Circuits and sums of binomial squares



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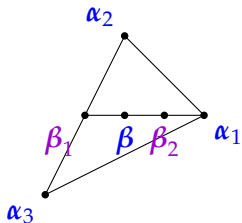
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Circuits and sums of binomial squares



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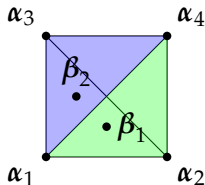
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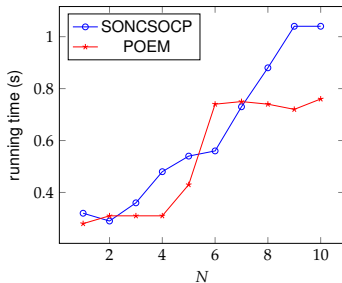
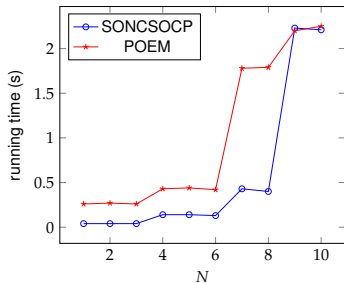
Monomial squares = $\Lambda(f)$ Complement = $\Gamma(f)$

Simplex **Cover** of each $\beta \implies \mathcal{A}$ and mediated set $M_{\mathcal{A}\beta}$

$$f = 50x^4y^4 + x^4 + 3y^4 + 800 - 100xy^2 - 100x^2y$$



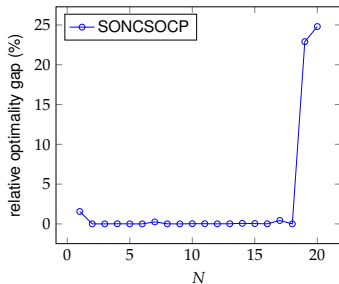
Comparison with previous method (POEM)



Arbitrary support

$$n \sim 40$$

$$d \sim 60$$



Conclusion and Perspectives

1 MODELING tool

SDP approximation of the **whole reachable set** X^∞

Conclusion and Perspectives

1 MODELING tool






SDP approximation of the **whole reachable set** X^∞

2 EFFICIENT tool, new applications of TSSOS/circuits?

- 💡 control/stability analysis
- 💡 optimal powerflow
- 💡 quantum physics
- 💡 robustness of deep networks

Thank you for your attention!

`https://homepages.laas.fr/vmagron`

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-  Wang & Magron. A second order cone characterization for sums of nonnegative circuits [SONCSOCP](#)
-  Wang, Magron & Lasserre. TSSOS: a moment-SOS hierarchy that exploits term sparsity. arxiv:1912.08899 [TSSOS](#)
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-  Magron, Constantinides & Donaldson. Certified Roundoff Error Bounds Using Semidefinite Programming, *TOMS*. arxiv:1507.03331 [Real2Float](#)