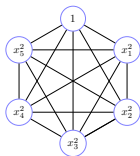


The quest of modeling, certification and efficiency in polynomial optimization

Victor Magron, Chargé de recherche
MAC Team, LAAS CNRS

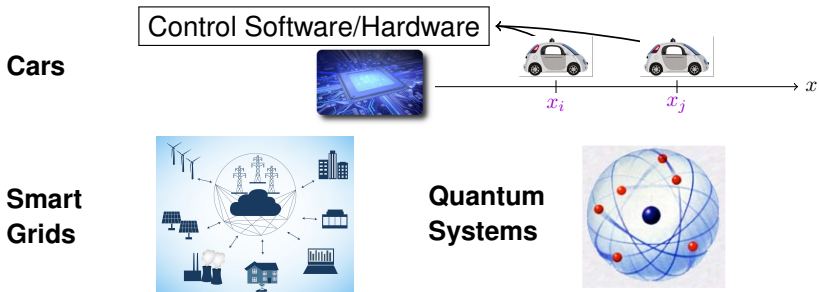
Soutenance pour l'habilitation à diriger les recherches
LAAS/Visio 25 Mai 2021



Why optimizing over polynomials?

VERIFICATION/ANALYSIS OF COMPLEX NONLINEAR SYSTEMS ...

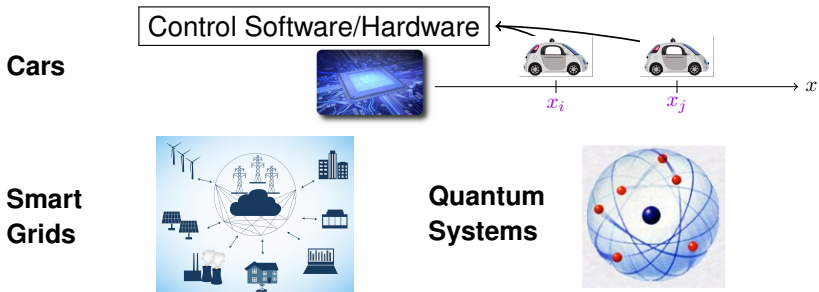
SAFETY of critical parts for **computing** \oplus **physical** devices



Why optimizing over polynomials?

VERIFICATION/ANALYSIS OF COMPLEX NONLINEAR SYSTEMS ...

SAFETY of critical parts for **computing** \oplus **physical** devices



... **CAST AS OPTIMIZATION PROBLEM** \rightsquigarrow SOLVE **OFFLINE**

Input: linear  semidefinite  polynomial 

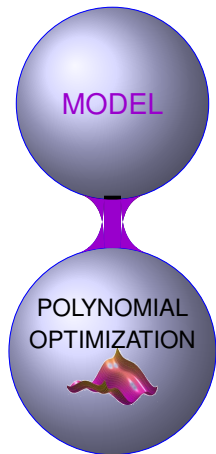
Output: value + numerical/symbolic/formal **certificate**

The quest of modeling: applications

STATIC Optimization

$f = \text{sum of squares } \sigma \implies \inf f \geq 0$

$$f, g \in \mathbb{R}[\mathbf{x}]$$



The quest of modeling: applications

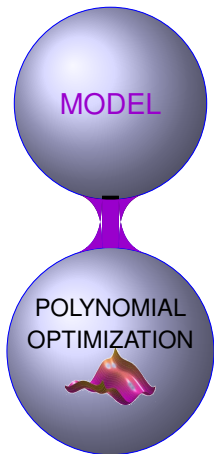
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Semialgebraic constraints $\mathbf{X} = \{\mathbf{x} : g(\mathbf{x}) \geq 0\}$

$$f = \sigma_0 + \sigma_1 g \implies f \geq 0 \text{ on } \mathbf{X}$$



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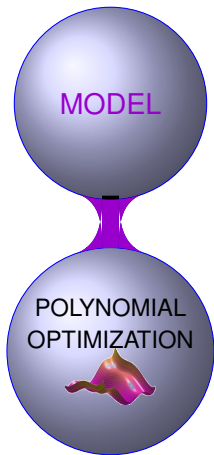
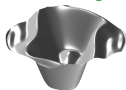
DYNAMICAL Optimization

Optimal control

[Henrion Lasserre Prieur Trelat '08]

Regions of attraction

[Henrion Korda '14]



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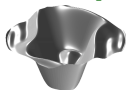
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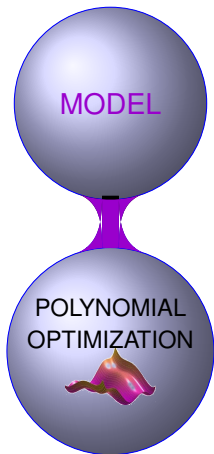


NONCOMMUTATIVE Optimization ($x_1 x_2 \neq x_2 x_1$)

Minimal eigenvalue/trace

💡 Useful in quantum information (Bell inequalities)

[Navascués Pironio Acín '08]



The quest of modeling: the hierarchy

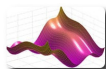
NP-hard NON CONVEX Problem $f_{\min} = \inf f(x)$

Theory

(Primal)

$$\inf \int f d\mu$$

with μ proba \Rightarrow



INFINITE LP

(Dual)

$$\sup b$$

\Leftarrow with $f - b \geq 0$

The quest of modeling: the hierarchy

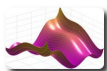
NP-hard NON CONVEX Problem $f_{\min} = \inf f(x)$

Practice

(Primal **Relaxation**)

$$\text{moments } \int x^\alpha d\mu$$

finite number \Rightarrow



SDP

(Dual **Strengthening**)

$$f - b = \text{sum of squares}$$

\Leftarrow fixed degree

[Lasserre '01] HIERARCHY of **CONVEX PROBLEMS** $\uparrow f_{\min}$

Based on representation of positive polynomials [Putinar '93]

Numerical

Solvers



Approximate

Certificate

degree d

n vars



$\binom{n+d}{n}$ **SDP** VARIABLES

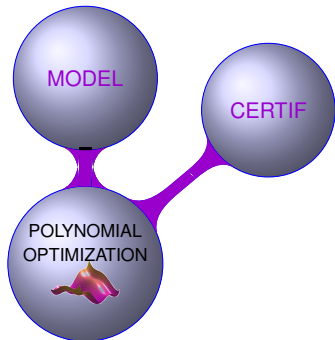


The quest of certification (past)

Kepler's conjecture (1611): the max density of sphere packings is $\pi/\sqrt{18}$



Flyspeck : Formalizing the proof of Kepler [Hales et al. '94]
Certification of thousands of "tight" non-linear inequalities [Hales et al. '17]



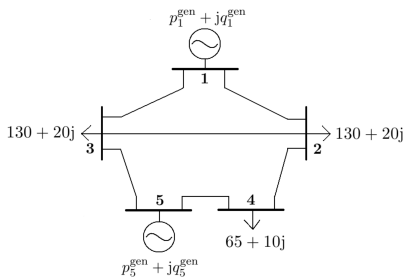
The quest of efficiency (past)

💡 Exploiting sparsity

few terms [Reznick '78]

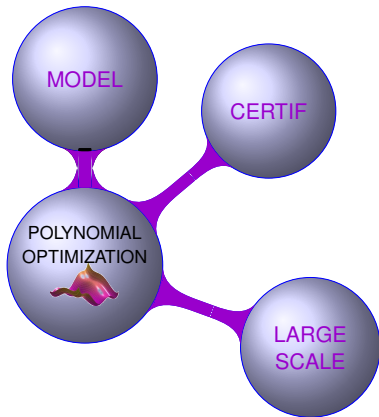
few correlations

[Lasserre, Waki et al. '06]



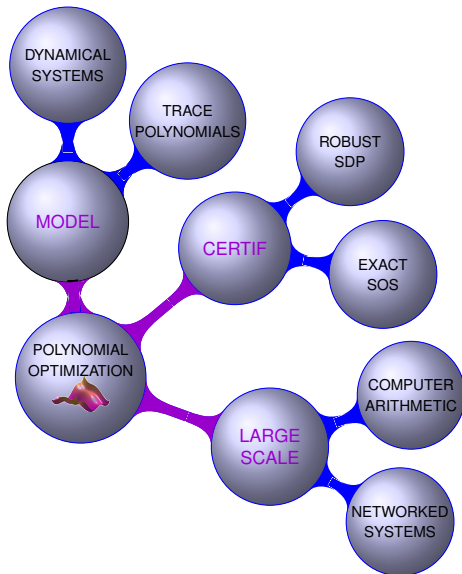
Optimal Powerflow $n \simeq 10^3$

[Josz et al. '18]



Contributions in polynomial optimization

51 papers =
23 journals
14 conf. proceedings
14 preprints



Introduction

The quest of modeling

The quest of certification

The quest of efficiency

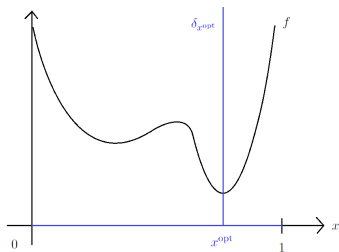
Research projects in polynomial optimization

The quest of modeling: dynamical systems

CHARACTERIZE A VALUE

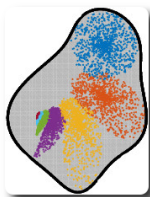
CHARACTERIZE A SET

$$f_{\min} = \inf_{\mathbf{x} \in \mathbf{X}} f(\mathbf{x}) = \inf_{\mu \in \mathcal{M}_+(\mathbf{X})} \int_{\mathbf{X}} f d\mu$$



Dirac measure at a
minimizer

?



Uniform measure on this set

The quest of modeling: dynamical systems

4 papers with Henrion

Polynomial map $f(\mathbf{x}) = (f_1(\mathbf{x}), \dots, f_n(\mathbf{x}))$

The quest of modeling: dynamical systems

4 papers with Henrion

Polynomial map $f(\mathbf{x}) = (f_1(\mathbf{x}), \dots, f_n(\mathbf{x}))$

Semialgebraic state set constraints \mathbf{X} = either a box  or a ball 

Discrete-time

$$\mathbf{x}_{t+1} = f(\mathbf{x}_t), \quad \mathbf{x}_t \in \mathbf{X}, \quad t \in \mathbb{N}$$

The quest of modeling: dynamical systems

4 papers with Henrion

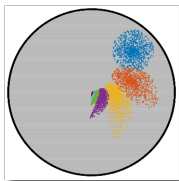
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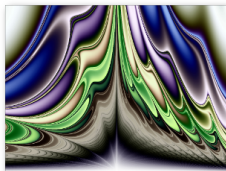
REACHABLE SET



Semialgebraic initial states \mathbf{X}_0

All admissible trajectories \mathbf{X}^∞

ATTRACTORS



Support of invariant measure

$$\mu(\mathbf{A}) = \mu(f^{-1}(\mathbf{A})) = f_{\#}\mu(\mathbf{A})$$

\forall Borel set $\mathbf{A} \in \mathcal{B}(\mathbf{X})$

The quest of modeling: dynamical systems

REACHABLE SET X^∞

$$\mu_0 \in \mathcal{M}_+(\mathbf{X}_0), \quad \mu_1 = f_\# \mu_0 \quad \dots \quad \mu_t = f_\# \mu_{t-1}$$

The quest of modeling: dynamical systems

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The quest of modeling: dynamical systems

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The occupation measures μ_t, v_t, μ_0 satisfy **Liouville's Equation**:

$$\mu_t + v_t = f_\# v_t + \mu_0 \leftarrow \text{linear in } \mu_t, v_t, \mu_0$$

The quest of modeling: dynamical systems

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💡 The uniform measure on X^∞ satisfies Liouville and is the (unique) solution of an LP over measures [Magron Henrion et al. '19]

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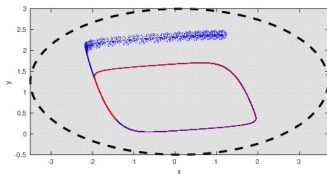
💡 In both cases, the support of all measures is **bounded** to ensure that the LP has an **optimal solution**

💡 Zero duality gap follows from [Barvinok '02]

The quest of modeling: dynamical systems

💡 Use the moment-SOS hierarchy to relax the LP into a hierarchy of SDP

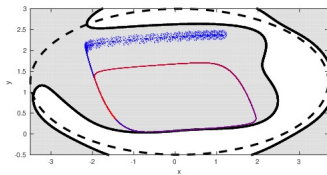
REACHABLE SET for FitzHugh-Nagumo Neuron model



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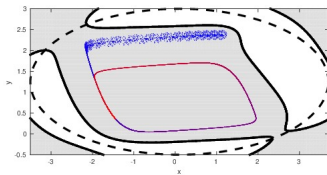
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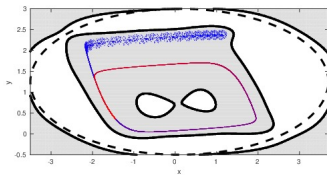
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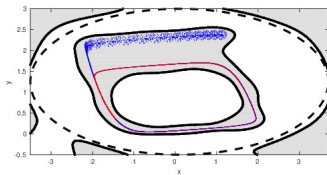
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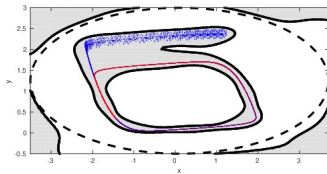
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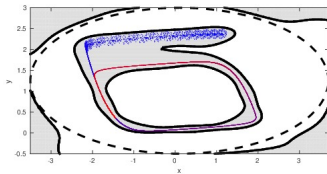
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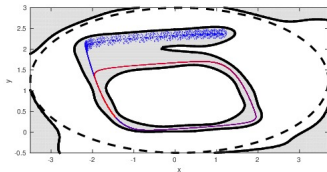
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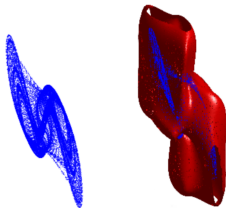
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ATTRACTOR of Arneodo-Coulet



The quest of modeling: trace polynomials

💡 They arise from entanglement: Werner witnesses [Werner '89], polynomial Bell inequalities [Pozsgay et al. '17]

$$\mathbb{T} = \mathbb{T}\langle x \rangle$$

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$$\mathbb{T} = \mathbb{T}\langle \underline{x} \rangle$$

Symmetric noncommutative variables $\underline{x} = (x_1, \dots, x_n)$
& sums of product traces $\mathbb{T} =$ pure trace polynomials

$$f = x_1 x_2 x_1^2 - \text{tr}(x_2) \text{tr}(x_1 x_2) \text{tr}(x_1^2 x_2) x_2 x_1 \in \mathbb{T}$$

with $x_1 x_2 \neq x_2 x_1$, **involution** $(x_1 x_2)^* = x_2 x_1$

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sums of hermitian squares $(f^* f)$

$S \subset \text{Sym } \mathbb{T}$ X_j operators from finite von Neumann algebra

Constraints $\{\underline{X} = (X_1, \dots, X_n) : g(\underline{X}) \succcurlyeq 0, \quad \forall g \in S\}$

The quest of modeling: trace polynomials

💡 Restrict the set of constraints to operators from “nice” von Neumann algebra of type II_1

The quest of modeling: trace polynomials

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- \implies One can minimize **pure trace** polynomials on such sets!

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⇒ One can minimize **pure trace** polynomials on such sets!

💡 $S[N] = S \cup \{N - x_j^2\}$: add “ball” constraints to ensure convergence

The quest of modeling: trace polynomials

💡 Restrict the set of constraints to operators from “nice” von Neumann algebra of type II_1
 \implies One can minimize **pure trace** polynomials on such sets!

💡 $S[N] = S \cup \{N - x_j^2\}$: add “ball” constraints to ensure convergence
 \implies **Pure trace** variant of Helton-McCullough representation

Theorem [Klep Magron Volcic '21]

Let $S \subset \text{Sym } \mathbb{T}$ and $f \in \mathbb{T}$. There is a hierarchy of SDP lower bounds converging to f_{\min} on the II_1 -von Neumann semialgebraic set associated to $S[N]$.

Introduction

The quest of modeling

The quest of certification

The quest of efficiency

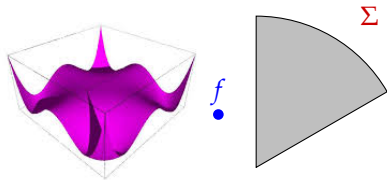
Research projects in polynomial optimization

The quest of certification: two-player games

MOTZKIN POLYNOMIAL

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$$f \geq 0 \text{ but } f \notin \Sigma = \text{SOS}$$

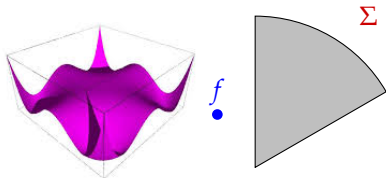


The quest of certification: two-player games

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$$f_{\min} = \min_{x_i \in \mathbb{R}} f(x_1, x_2) = 0 \text{ for } |x_i| = \frac{\sqrt{3}}{3}$$

Moment-SOS hierarchy [Henrion-Lasserre '05]

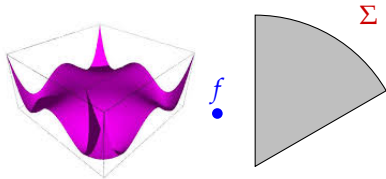
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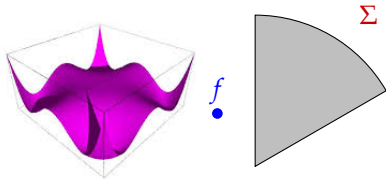
order 4 = “ $-\infty$ ”

The quest of certification: two-player games

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order 4 = “ $-\infty$ ”

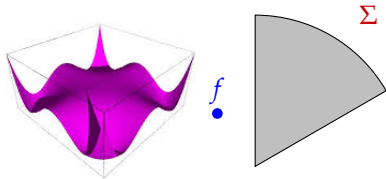
order 5 $\simeq -0.4$

The quest of certification: two-player games

MOTZKIN POLYNOMIAL

$$f = \frac{1}{27} + x_1^2 x_2^4 + x_1^4 x_2^2 - x_1^2 x_2^2$$

$$f \geq 0 \text{ but } f \notin \Sigma = \text{SOS}$$



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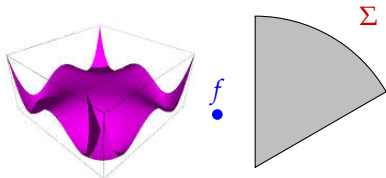
order 8 $\simeq -10^{-8} \oplus$ extraction of optimizers **Paradox** ?!

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Similar paradox in quantum information [Navascués et al. '13]

The quest of certification: two-player games

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The quest of certification: two-player games

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[Lasserre Magron '19] Inaccurate SDP Relaxations ...

(Primal **Relaxation**)

$$\inf_{\mathbf{y}} \sum_{\alpha} \tilde{f}_{\alpha} y_{\alpha}$$

$$\text{s.t. } \mathbf{M}_d(\mathbf{y}) \succeq 0$$

$$y_0 = 1$$

(Dual **Strengthening**)

$$\sup b$$

$$\tilde{f} - b = \sigma$$

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The quest of certification: two-player games

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💡 ... of the **robust** problem $\max_{\tilde{f} \in \mathbf{B}_{\infty}(f, \eta)} \min_{\mathbf{x}} \tilde{f}(\mathbf{x})$

The quest of certification: two-player games

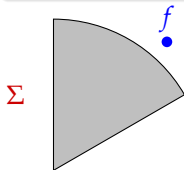
Theorem [Lasserre 06]

For fixed n , any $f \geq 0$ can be approximated arbitrarily closely by SOS polynomials.

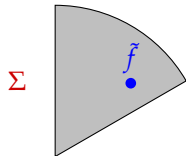
The quest of certification: two-player games

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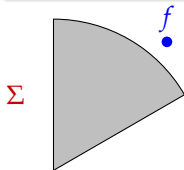
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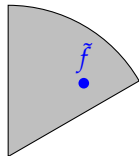
The quest of certification: two-player games

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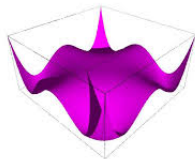
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At fixed η , when $d \nearrow$, $\tilde{f} \in \Sigma!$



$$f + 10^{-7} \sum_{|\beta| \leq 4} \mathbf{x}^{2\beta} \in \Sigma$$

Paradox Explanation

The quest of certification: two-player games



max – min ROBUST OPTIMIZATION

Player 1 (solver) picks $\tilde{f} \in \mathbf{B}_\infty(f) \rightsquigarrow$ **SDP leads**

Player 2 (optimizer) picks an SOS \rightsquigarrow **User follows**

The quest of certification: two-player games



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The quest of certification: two-player games



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Player 1 (robust optimizer) picks an SOS \rightsquigarrow **User leads**

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The quest of certification: exact SOS

APPROXIMATE SOLUTIONS

sum of squares of $x_1^2 - 2x_1x_2 + x_2^2$?



$(1.00001x_1 - 0.99998x_2)^2!$



$$x_1^2 - 2x_1x_2 + x_2^2 \simeq (1.00001x_1 - 0.99998x_2)^2$$

$$x_1^2 - 2x_1x_2 + x_2^2 \neq 1.0000200001x_1^2 - 1.9999799996x_1x_2 + 0.9999600004x_2^2$$

$$\boxed{\simeq \rightarrow = ?}$$

The quest of certification: exact SOS

Win **TWO-PLAYER GAME**: given $f \in \mathbb{Q}[x]$ compute $f_i \in \mathbb{Q}[x], c_i \in \mathbb{Q}^{>0}$
s.t. $f = \sum_i c_i f_i^2$



sum of squares of f ?



\simeq Output!



The quest of certification: exact SOS

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 **Hybrid** Symbolic/Numeric Algorithms

sum of squares of $f - \epsilon$?

\simeq Output!



Error Compensation



$\simeq \rightarrow =$

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💡 **Hybrid** Symbolic/Numeric Algorithms

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\approx Output!



Error Compensation



$\approx \rightarrow =$

💡 **PERTURBATION**: approximate SOS $f(\mathbf{x}) - \epsilon \sum_{\alpha} \mathbf{x}^{2\alpha} = \tilde{\sigma} + u$

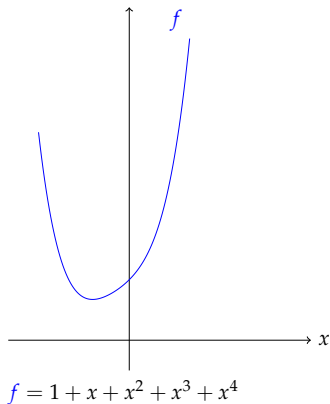
4 papers [Magron Safey El Din Schweighofer '17-21]

Software library: RealCertify

The quest of certification: exact SOS

[Chevillard et. al 11]

$$f \in \mathbb{Q}[X], \deg f = d = 2k, f > 0$$



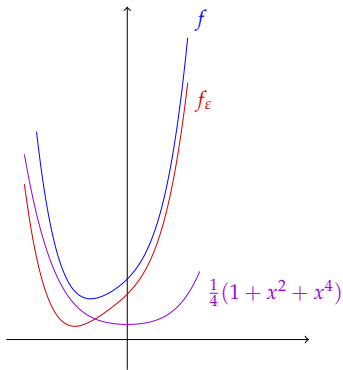
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$$f = 1 + x + x^2 + x^3 + x^4$$

$$\varepsilon = \frac{1}{4}$$

The quest of certification: exact SOS

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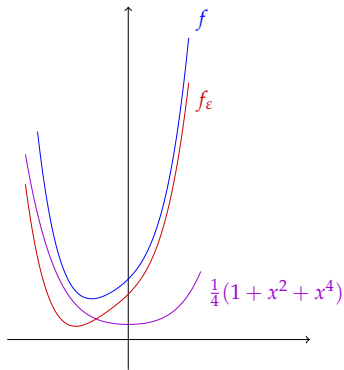
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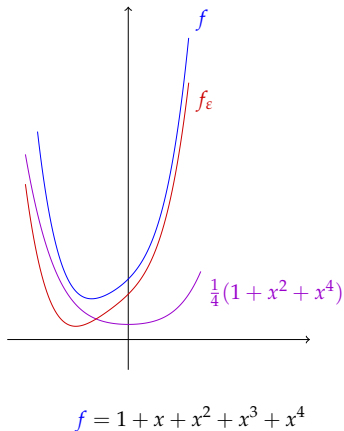
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💡 **ABSORB** small enough u_i

$$\implies \varepsilon \sum_{i=0}^k x^{2i} + u \text{ SOS}$$



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The quest of certification: complexity

💡 Analysis weapons: quantifier elimination, root isolation [Cauchy 1832]

$n = 1$ → polynomial in d , linear in τ = input bit size

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💡 Extension to non SOS polynomials, $\mathbb{C}[x]$ [PhD Hieu '19-22]

Introduction

The quest of modeling

The quest of certification

The quest of efficiency

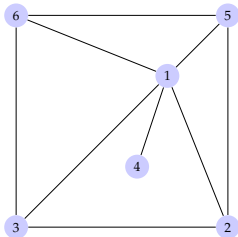
Research projects in polynomial optimization

The quest of efficiency: correlative sparsity

💡 Exploit few links between **variables** [Lasserre, Waki et al. '06]

$$x_2x_5 + x_3x_6 - x_2x_3 - x_5x_6 + x_1(-x_1 + x_2 + x_3 - x_4 + x_5 + x_6)$$

Chordal graph G

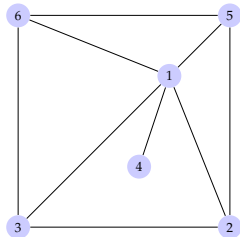


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Chordal graph G



maximal cliques I_k

$$I_1 = \{1, 4\}$$

$$I_2 = \{1, 2, 3, 5\}$$

$$I_3 = \{1, 3, 5, 6\}$$

Dense SDP: 210 vars

Sparse SDP: 115 vars

Average size $\kappa \rightsquigarrow \kappa^{2d}$ vars

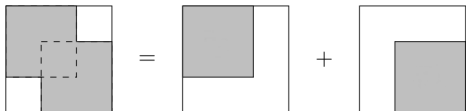
The quest of efficiency: correlative sparsity

Theorem [Griewank Toint '84]

Chordal graph G with maximal cliques I_1, I_2

$Q_G \succcurlyeq 0$ with nonzero entries at edges of G

$\implies Q_G = P_{I_1}^T Q_1 P_{I_1} + P_{I_2}^T Q_2 P_{I_2}$ with $Q_k \succcurlyeq 0$ indexed by I_k



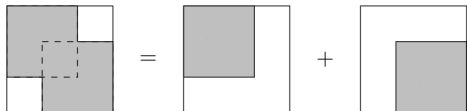
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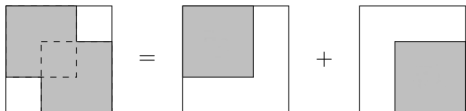
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Theorem: Sparse Putinar's representation [Lasserre '06]

$f > 0$ on $\{x : g_j(x) \geq 0\}$

chordal graph G with cliques $I_k \implies$

ball constraints for each $x(I_k)$

$$f = \sigma_0 + \sum_j \sigma_j g_j$$

SOS σ_0 "sees" vars in I_k

σ_j "sees" vars from g_j

The quest of efficiency: roundoff errors

[Magron Constantinides Donaldson '17]

Exact $f(\mathbf{x}) = x_1x_2 + x_3x_4$

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3: Bound $\ell(\mathbf{x}, \mathbf{e})$ with **SPARSE SUMS OF SQUARES**

💡 $I_k \rightarrow \{\mathbf{x}, e_k\} \implies \boxed{m(n+1)^{2d} \text{ instead of } (n+m)^{2d}}$ SDP vars

The quest of efficiency: roundoff errors

$$f = x_2x_5 + x_3x_6 - x_2x_3 - x_5x_6 + x_1(-x_1 + x_2 + x_3 - x_4 + x_5 + x_6)$$

$$\mathbf{x} \in [4.00, 6.36]^6, \quad \mathbf{e} \in [-\epsilon, \epsilon]^{15}, \quad \epsilon = 2^{-53}$$

Dense SDP: $\binom{6+15+4}{6+15} = 12650$ variables \leadsto **Out of memory**

The quest of efficiency: roundoff errors

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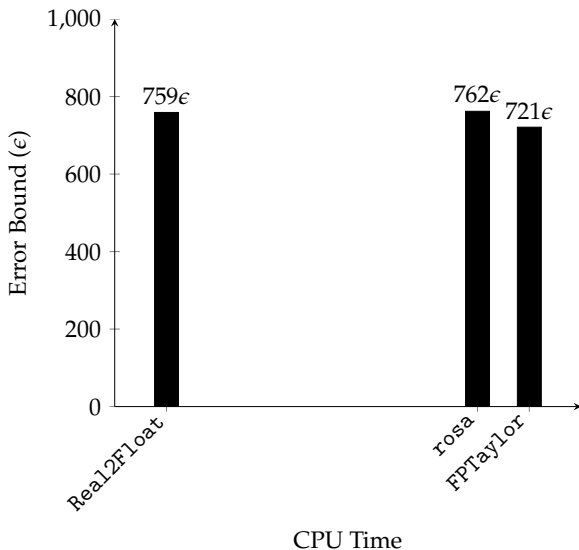
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SMT-based rosa tool: 762ϵ (19 \times more CPU)

The quest of efficiency: roundoff errors



The quest of efficiency: back to the NC world

symmetric noncommutative (NC) variables $\underline{x} = (x_1, \dots, x_n)$

Theorem [Helton-McCullough 02]

$f \succcurlyeq 0 \Leftrightarrow f \in \Sigma$ (all positive polynomials are sums of squares)

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[Klep Magron Povh '21]

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GOOD NEWS: there is an NC analog of the sparse Putinar's representation!

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BAD NEWS: there is **no** sparse analog!

sparse $f \in \Sigma \not\Rightarrow f$ is a sparse SOS

[Klep Magron Povh '21]

Take $f = (x_1 + x_2 + x_3)^2$

GOOD NEWS: there is an NC analog of the sparse Putinar's representation! Based on GNS construction & **amalgamation**

[Blackadar '78, Voiculescu '85]

The quest of efficiency: back to the NC world

symmetric noncommutative (NC) variables $\underline{x} = (x_1, \dots, x_n)$

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Theorem [Klep Magron Povh '21]

$f \succcurlyeq 0$ on $\{\underline{x} : g_j(\underline{x}) \succcurlyeq 0\}$

chordal graph G with cliques $I_k \Rightarrow$

ball constraints for each $x(I_k)$

$$f = \sum_{k,i} s_{ki}^* s_{ki} + \sum_{j,i} t_{ji}^* g_j t_{ji}$$

s_{ki} "sees" vars in I_k

t_{ji} "sees" vars from g_j

The quest of efficiency: back to the NC world

I₃₃₂₂ Bell inequality (entanglement in quantum information)

$$f = x_1(y_1 + y_2 + y_3) + x_2(y_1 + y_2 - y_3) + x_3(y_1 - y_2) - x_1 - 2y_1 - y_2$$

Maximal violation levels \rightarrow **upper bounds** on λ_{\max} of f on $\{(x, y) : x_i^2 = x_i, y_j^2 = y_j, x_i y_j = y_j x_i\}$

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💡 $C_k \rightarrow \{x_1, x_2, x_3, y_k\}$

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level	sparse	dense [Pál-Vértesi 18]
2	0.2550008	0.2509397

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6	0.2508753977180	(1 hour)

PERFORMANCE



VS



ACCURACY

The quest of efficiency: term sparsity

[Postdoc Wang '19-21] ANR Tremplin-ERC



$$f = x_1^2 - 2x_1x_2 + 3x_2^2 - 2x_1^2x_2 + 2x_1^2x_2^2 - 2x_2x_3 \\ + 6x_3^2 + 18x_2^2x_3 - 54x_2x_3^2 + 142x_2^2x_3^2$$

[Reznick '78] $\rightarrow f = (1 \quad x_1 \quad x_2 \quad x_3 \quad x_1x_2 \quad x_2x_3) \underbrace{\mathcal{Q}}_{\neq 0} \begin{pmatrix} 1 \\ x_1 \\ x_2 \\ x_3 \\ x_1x_2 \\ x_2x_3 \end{pmatrix}$

$\rightsquigarrow \frac{6 \times 7}{2} = 28$ "unknown" entries in \mathcal{Q}

The quest of efficiency: term sparsity

[Postdoc Wang '19-21] ANR Tremplin-ERC



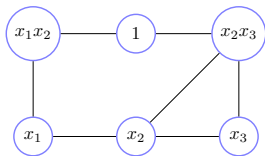
$$f = x_1^2 - 2x_1x_2 + 3x_2^2 - 2x_1^2x_2 + 2x_1^2x_2^2 - 2x_2x_3 \\ + 6x_3^2 + 18x_2^2x_3 - 54x_2x_3^2 + 142x_2^2x_3^2$$

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💡 **Term sparsity pattern graph G**



The quest of efficiency: term sparsity

[Postdoc Wang '19-21] ANR Tremplin-ERC



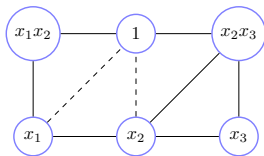
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+ chordal extension



The quest of efficiency: term sparsity

[Postdoc Wang '19-21] ANR Tremplin-ERC



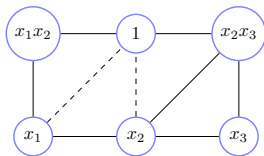
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💡 **Term sparsity pattern graph G**
+ chordal extension



Replace Q by Q_G with nonzero entries at edges of G

$\rightsquigarrow 6 + 9 = 15$ "unknown" entries in Q_G

The quest of efficiency: term sparsity

Lyapunov functions from NETWORKED SYSTEMS

$$f = \sum_{i=1}^N a_i (x_i^2 + x_i^4) - \sum_{i,k=1}^N b_{ik} x_i^2 x_k^2 \quad a_i \in [1, 2] \quad b_{ik} \in \left[\frac{0.5}{N}, \frac{1.5}{N}\right]$$

$\rightsquigarrow \binom{N+2}{2} (\binom{N+2}{2} + 1) / 2 = 231$ “unknown” entries in \mathcal{Q} for $N = 5$

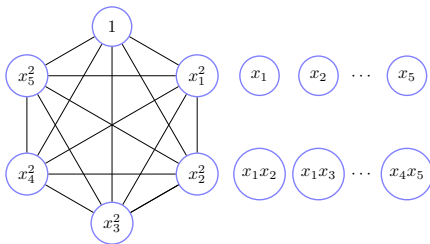
The quest of efficiency: term sparsity

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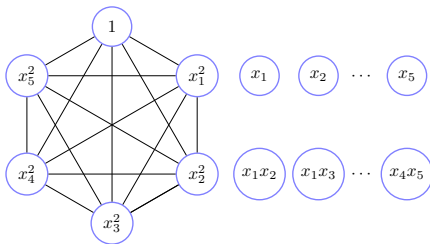
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💡 **term sparsity graph G**



$\rightsquigarrow (N+1)^2 = 36$ “unknown” entries in Q_G for $N = 5$

Proof that $f \geq 0$ for $N = 80$ in ~ 10 seconds!

The quest of efficiency: term sparsity

💡 CONVERGENCE GUARANTEES

💡 handles NC polynomials, $\mathbb{C}[\mathbf{x}]$, joint spectral radii, combo with correlative sparsity → 7 papers

💡 Julia libraries TSSOS & NCTSSOS → solve problems with $n = 10^3$!

💡 choice of the CHORDAL EXTENSION: min / max

Introduction

The quest of modeling

The quest of certification

The quest of efficiency

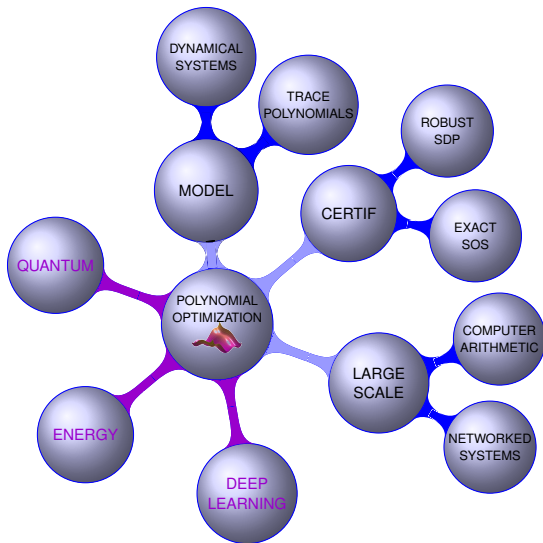
Research projects in polynomial optimization

Research projects in polynomial optimization

Embed polynomial optimization in **academic** & **industrial** frameworks

For each project: I will present

- 1 context + ideas
- 2 zoom on a specific application target



Quantum information & free probabilities

QUANTUM APPLICATIONS

Ground state energy, trace polynomials for Werner witnesses

 **symmetric & sparse**

Quantum information & free probabilities

QUANTUM APPLICATIONS

Ground state energy, trace polynomials for Werner witnesses

 **symmetric & sparse**

RESEARCH DIRECTIONS RELYING ON FREE PROBABILITIES

Minimizer approximation: noncommutative Christoffel-Darboux kernels and the Siciak function [[Beckermann et al. '20](#)]

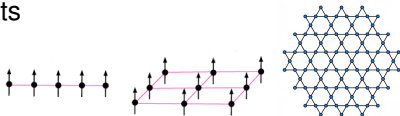
Zoom: condensed matter

Ground-state energy \Leftrightarrow minimal eigenvalue of an Hamiltonian

$$H = \sum_{\langle i,j \rangle} (x_i x_j + y_i y_j + z_i z_j)$$

spin states (x_i, y_i, z_i) , constraints

Lattices: 1D 2D Kagome



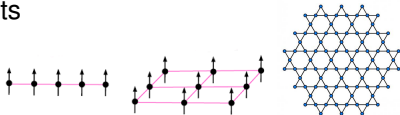
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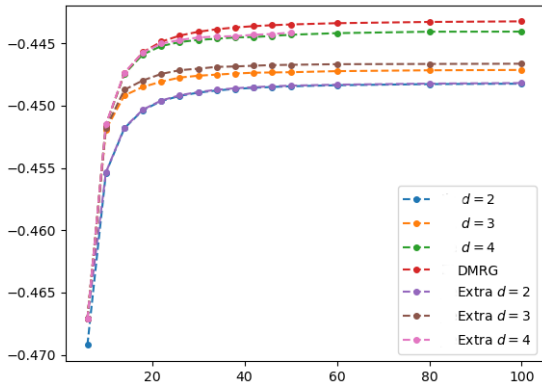


Existing \pm efficient techniques: quantum Monte Carlo & variational algorithms \Rightarrow **upper bounds** on minimal energy

Zoom: condensed matter

Lower bounds of the energy

1D lattice

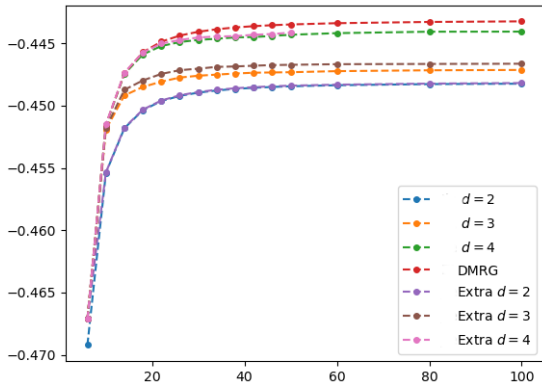


Dense $d = 4, n = 10^2 \Rightarrow 10^{19}$ variables (solvers handle $\simeq 10^4$)

Zoom: condensed matter

Lower bounds of the energy

1D lattice



Dense $d = 4, n = 10^2 \Rightarrow 10^{19}$ variables (solvers handle $\simeq 10^4$)






Sparse solved within 1 hour on PFCALCUL at LAAS

Quantum & free probabilities: interaction

MODELING AND EFFICIENCY



MAC Bhardwaj Korda Lasserre
Mai Wang
(ANR/CIMI funding)
IRSAMC, LPT Nechita
IMT Belinschi

 **ICFO** Acín's group (Inst. Quantique Occitan funding)
 **U. Ljubljana** Klep Povh
(PHC funding)
 **Texas A&M** Volčič
 **U. Ben Gourion** Vinnikov
 **U. Krakow** Huber

💡 Mini-symposium with I. Klep *Computational aspects of commutative and noncommutative positive polynomials* at EUROPEAN CONGRESS OF MATHEMATICIANS

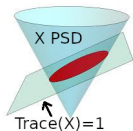
Energy networks

OPTIMAL POWER FLOW → large-scale problems with
structured relaxations



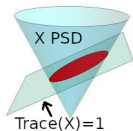
sparse & constant trace

[PhD Mai '19-22]



Energy networks

OPTIMAL POWER FLOW → large-scale problems with structured relaxations
💡 **sparse & constant trace**
[PhD Mai '19-22]

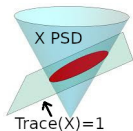


FINITE IMPULSE RESPONSE FILTERS → noise reduction for smart grids
💡 **Certification** [PhD Hieu '19-22]



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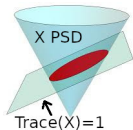


STABILITY OF LARGE-SCALE POWER SYSTEMS → reachability analysis of continuous-time systems
💡 **Sparse** [Kundur '07]



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OPTIMAL POWER FLOW → large-scale problems with structured relaxations
💡 **sparse & constant trace**
[PhD Mai '19-22]



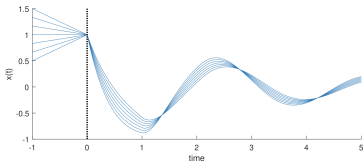
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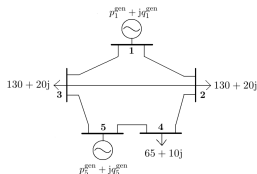


TIME DELAY SYSTEMS → deteriorate controllers of networked power systems
💡 **occupation measures**



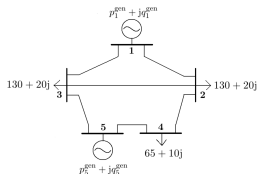
Zoom: optimal power flow

Solving Alternative Current OPF to **global optimality**
→ benchmarks [PGLIB '18] with up to **25 000 buses!**



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COMPLEX vs **REAL** hierarchy of relaxations?

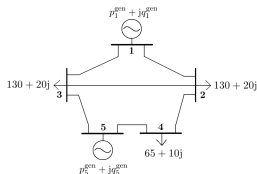
[D'Angelo Putinar '09, Josz et al. '18, Magron Wang '21]

6515_RTE → $n = 7000$ complex variables (14000 real variables)

solved at 0.6% gap within 3 hours on PFCALCUL at LAAS

Zoom: optimal power flow

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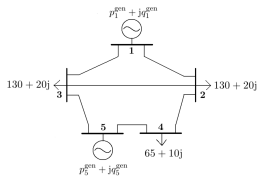
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SDP have **CONSTANT TRACE PROPERTY**

[PhD Mai '19-22]

Zoom: optimal power flow

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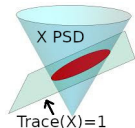
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SDP have **CONSTANT TRACE PROPERTY**

[PhD Mai '19-22]

💡 Replace interior-point solvers by 1st-order methods
⇒ handle matrices of size up to 2000 with more than 1.5 million constraints... in 1 hour!





Energy networks: interaction

MODELING, CERTIFICATION & EFFICIENCY



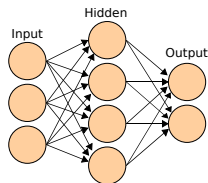
MAC Henrion Korda Lasserre
Mai Schlosser Wang
RTE Maeght Panciatici Ruiz
(AMIES/RTE funding)
Sorbonne Safey El Din Hieu
(POEMA funding)

 **U. Konstanz** Schweighofer
(POEMA funding)
 **Northeastern U.** Miller Sz-
naier

Deep learning

ROBUSTNESS CERTIFICATION OF NEURAL NETWORKS

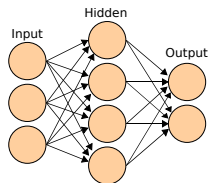
💡 **sparse** [Chen Lasserre Magron Pauwels '20]



Deep learning

ROBUSTNESS CERTIFICATION OF NEURAL NETWORKS

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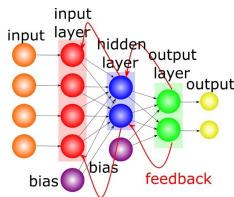
STABILITY ANALYSIS OF RECURRENT NETWORKS

💡 copositive program + integral quadratic constraints

[Megretski Rantzer '97]

[Ebihara Waki Mai Magron Peaucelle Tarbouriech '20]

💡 Formal proofs [Devadze Streif Magron '21]

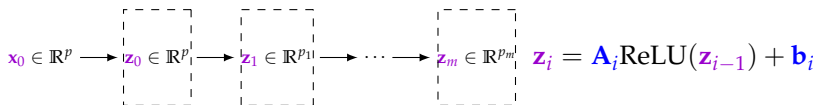


Zoom: robustness of NN [PhD Chen '19-22]

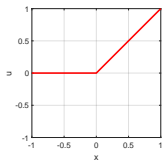
[SIAM News March '21]

“Yet DL has an Achilles’ heel. Current implementations can be highly unstable, meaning that a certain small perturbation to the input of a trained neural network can cause substantial change in its output. This phenomenon is both a nuisance and a major concern for the safety and robustness of DL-based systems in critical applications—like healthcare—where reliable computations are essential”

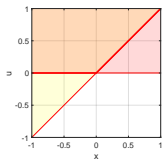
Zoom: robustness of NN [PhD Chen '19-22]



ReLU (left) & its “semialgebraicity” (right)



$$u = \max\{x, 0\}$$



$$u(u - x) = 0, u \geq x, u \geq 0$$

Zoom: robustness of NN [PhD Chen '19-22]

💡 “Direct” certification of a classifier with 1 hidden layer

$$\begin{aligned} \max_{\mathbf{x}, \mathbf{z}} \quad & (\mathbf{C}^{i,:} - \mathbf{C}^{k,:})\mathbf{z} \\ \text{s.t.} \quad & \begin{cases} \mathbf{z} = \text{ReLU}(\mathbf{A}\mathbf{x} + \mathbf{b}) \\ \|\mathbf{x} - \mathbf{x}_0\| \leq \epsilon \end{cases} \end{aligned}$$

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💡 Monotone equilibrium networks [Winston Kolter '20]

$$\mathbf{z} = \text{ReLU}(\mathbf{A}\mathbf{x} + \mathbf{b}) \rightarrow \mathbf{z} = \text{ReLU}(\mathbf{W}\mathbf{z} + \mathbf{A}\mathbf{x} + \mathbf{b})$$

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💡 “Indirect” with Lipschitz constant/ellipsoid approximation

Deep learning: interaction

MODELING, CERTIFICATION & EFFICIENCY



MAC Chen Korda Lasserre Mai
Peaucelle Tarbouriech (ANITI
funding)
UT3 Pauwels

 **TU Chemnitz** Devadze Streif
 **Kyushu U.** Ebihara Waki

Take-away

Why should you do polynomial optimization?

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💡 powerful & accurate **MODELING** tool

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💡 **CERTIFICATION** cost \simeq optimization cost

💡 **EFFICIENCY** guaranteed on structured applications

Thanks to all of my collaborators



And thanks for your presence and attention today!