

Algorithms for Computational Logic

Overconstrained Problems

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Outline

- 1 Maximum Satisfiability
- 2 Modeling Examples
- 3 Problems with MaxSAT Solving
- 4 MaxSAT Algorithms with Iterative Search
- 5 Core-Guided MaxSAT
- 6 The MaxHS algorithm for MaxSAT

- 1 **Maximum Satisfiability**
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 - MSU3 Algorithm
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$x_6 \vee x_2$	$\neg x_6 \vee x_2$	$\neg x_2 \vee x_1$	$\neg x_1$
$\neg x_6 \vee x_8$	$x_6 \vee \neg x_8$	$x_2 \vee x_4$	$\neg x_4 \vee x_5$
$x_7 \vee x_5$	$\neg x_7 \vee x_5$	$\neg x_5 \vee x_3$	$\neg x_3$

- **Unsatisfiable** formula
- Find **largest** subset of clauses that is satisfiable: the complement of a **minimum-size correction set**
- For above example, MaxSAT solution is 2:
 - By removing 2 clauses, the remaining are satisfiable

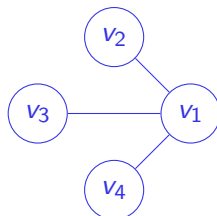
		Hard Clauses?	
		No	Yes
Weights?	No	Plain	Partial
	Yes	Weighted	Weighted Partial

- **Must** satisfy **hard** clauses, if any
- Compute set of satisfied **soft** clauses with **maximum cost**
 - Without weights, cost of each falsified soft clause is 1
- **Or**, compute set of falsified **soft** clauses with **minimum cost** (s.t. **hard** & remaining **soft** clauses are satisfied)
- **Note**: goal is to compute **set** of satisfied (or falsified) clauses; **not** just the cost !

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- The problem:

- ▶ Graph $G = (V, E)$
- ▶ Vertex cover $U \subseteq V$
 - ★ For each $(v_i, v_j) \in E$, either $v_i \in U$ or $v_j \in U$
- ▶ Minimum vertex cover: vertex cover U of minimum size

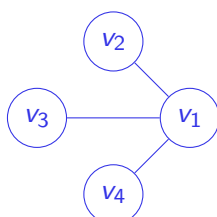


Vertex cover: $\{v_2, v_3, v_4\}$

Min vertex cover: $\{v_1\}$

- Partial MaxSAT formulation:

- ▶ Variables: x_i for each $v_i \in V$, with $x_i = 1$ iff $v_i \in U$
- ▶ Hard clauses: $(x_i \vee x_j)$ for each $(v_i, v_j) \in E$
- ▶ Soft clauses: $(\neg x_i)$ for each $v_i \in V$
 - ★ I.e. preferable **not** to include vertices in U



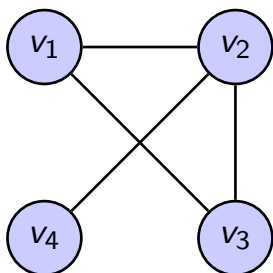
$$\mathcal{F}_H = \{(x_1 \vee x_2), (x_1 \vee x_3), (x_1 \vee x_4)\}$$

$$\mathcal{F}_S = \{(\neg x_1), (\neg x_2), (\neg x_3), (\neg x_4)\}$$

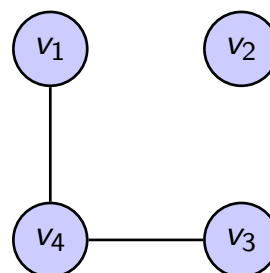
- ▶ Hard clauses have cost ∞
- ▶ Soft clauses have cost 1

- Given undirected graph $G = (V, E)$:
 - A **clique** is a complete subgraph of G , i.e. it is a set $L \subseteq V$ such that $\forall u, v \in L (u \neq v) \rightarrow (u, v) \in E$
 - A **vertex cover** $C \subseteq V$ is such that $\forall (u, v) \in E u \in C \vee v \in C$
 - An **independent set** $I \subseteq V$ is such that $\forall u, v \in I (v, u) \notin E$
- Properties:
 - If I is an independent set of $G = (V, E)$, then
 - $V - I$ is a vertex cover of G
 - I is a clique of the complement graph of G , G^C
 - A maximum independent set of G corresponds to a maximum clique of G^C

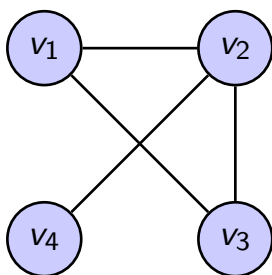
- G :



- G^C :



- $\{v_1, v_2, v_3\}$ is clique of G and an independent set of G^C
- $\{v_4\}$ is a vertex cover of G^C



$$\mathcal{F}_H \triangleq (\neg x_1 \vee \neg x_4) \wedge (\neg x_3 \vee \neg x_4)$$

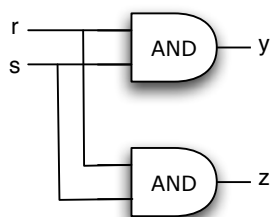
$$\mathcal{F}_S \triangleq \{(x_1), (x_2), (x_3), (x_4)\}$$

● MaxSAT formulation:

- ▶ x_i : assigned 1 if $v_i \in V$ included in clique
- ▶ If $\{x_i, x_j\} \notin E$, add **hard** clause $(\neg x_i \vee \neg x_j)$
- ▶ Soft clauses (x_i) for $v_i \in V$
- ▶ **Why?** Add as many vertices as possible to the clique such that non-adjacent vertices are not both selected

[SMVLS'07]

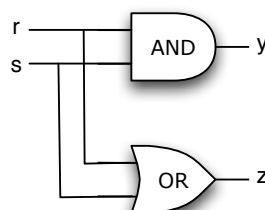
Correct circuit



Input stimuli: $\langle r, s \rangle = \langle 0, 1 \rangle$

Valid output: $\langle y, z \rangle = \langle 0, 0 \rangle$

Faulty circuit



Input stimuli: $\langle r, s \rangle = \langle 0, 1 \rangle$

Invalid output: $\langle y, z \rangle = \langle 0, 0 \rangle$

● The model:

- ▶ **Hard** clauses: Input and output values
- ▶ **Soft** clauses: CNF representation of circuit, each gate aggregated in group of clauses

● The problem:

- ▶ Maximize number of satisfied clauses (i.e. circuit gates)

- Universe of software packages: $\{p_1, \dots, p_n\}$
- Difference with respect to original installation: $\{p_1^\Delta, \dots, p_n^\Delta\}$
- Incompatibilities, dependencies and non-regression
 - ▶ **Hard clauses**
- Objective: minimize $\sum_{i=1}^n p_i^\Delta$
 - ▶ **Soft clauses** $(p_1^\Delta) \wedge (p_2^\Delta) \wedge \dots \wedge (p_i^\Delta)$

- Error localization in C code [JM'11]
- Haplotyping with pedigrees [GLMSO'10]
- Course timetabling [AN'10]
- Combinatorial auctions [HLGS'08]
- Minimizing Disclosure of Private Information in Credential-Based Interactions [AVFPS'10]
- Reasoning over Biological Networks [GL'12]
- Binate/unate covering
 - ▶ Haplotype inference [GMSLO'11]
 - ▶ Digital filter design [ACFM'08]
 - ▶ FSM synthesis [e.g. HS'96]
 - ▶ Logic minimization [e.g. HS'96]
 - ▶ ...
- ...

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- Example formula:

$$\mathcal{F} \triangleq (x_1) \wedge (x_2) \wedge (x_3) \wedge (\neg x_1 \vee \neg x_2) \wedge (\neg x_1 \vee \neg x_3)$$

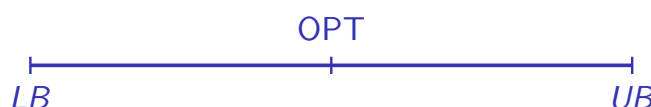
- Unit propagation falsifies two clauses: $(\neg x_1 \vee \neg x_2)$ and $(\neg x_1 \vee \neg x_3)$
- But, the MaxSAT solution is 1; $\mathcal{S} \subseteq \mathcal{F}$ is satisfiable:

$$\mathcal{S} \triangleq (x_2) \wedge (x_3) \wedge (\neg x_1 \vee \neg x_2) \wedge (\neg x_1 \vee \neg x_3)$$

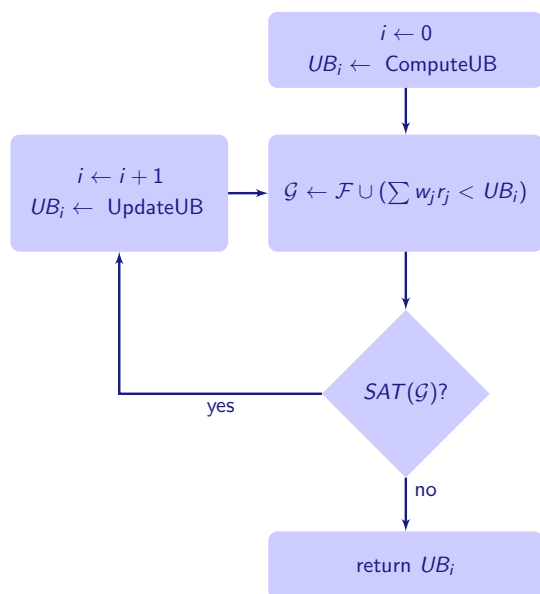
- **Cannot** apply unit propagation when solving MaxSAT
- **Cannot** apply hallmarks of CDCL SAT solving
- MaxSAT solving requires dedicated algorithms

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- Cost of assignment:
 - ▶ Sum of weights of falsified clauses



- Optimum solution (OPT):
 - ▶ Assignment with minimum cost
- Upper Bound (UB):
 - ▶ Assignment with cost $\geq OPT$
 - ▶ E.g. $\sum_{c_j \in \mathcal{F}} w_j + 1$; hard clauses may be inconsistent
- Lower Bound (LB):
 - ▶ No assignment with cost $\leq LB$
 - ▶ E.g. -1 ; it may be possible to satisfy all soft clauses
- Relax each soft clause c_j : $(c_j \vee r_j)$ (on-demand in core-guided)



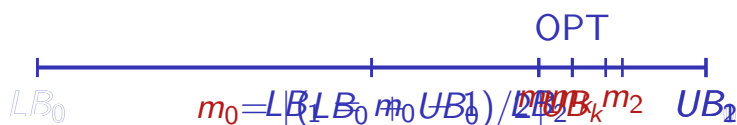
- Worst-case # of iterations **exponential** on instance size (# bits)
 - ▶ Improvement: use **binary search** instead
 - Many example solvers: **Minisat+**, **SAT4J**, **QMaxSat**
- [ES06,LBP10,KZFH12]

MaxSAT with iterative SAT solving – complete example

[illegible]

Example CNF formula Relax **all** clauses; Set $UB = 12 + 1$ Formula is **SAT**; E.g. all $x_i = 0$ and $r_1 = r_7 = r_9 = 1$ (i.e. cost = 3) Refine $UB = 3$ Formula is **SAT**; E.g. $x_1 = x_2 = 1$;

$x_3 = \dots = x_n = 0$ AtMost k /PB constraints cost = 2) Refine $UB = 2$ **All** (possibly many) ; terminate
 MaxSAT solver over **all** relaxation variables $UB = 2$ soft clauses relaxed



- Invariant: $LB_k \leq UB_k - 1$
- Require $\sum w_i r_i \leq m_0$
- Repeat
 - ▶ If **UNSAT**, refine $LB_1 = m_0, \dots$
 - ▶ Compute new mid value m_1, \dots
 - ▶ If **SAT**, refine $UB_3 = m_2, \dots$
- Until $LB_k = UB_k - 1$
- Worst-case # of iterations **linear** on instance size

Input: $max\text{-}sat(\phi, UB)$: A CNF formula ϕ and an upper bound UB

```

1:  $\phi \leftarrow simplifyFormula(\phi)$ ;
2: if  $\phi = \emptyset$  or  $\phi$  only contains empty clauses then
3:   return  $\#emptyClauses(\phi)$ ;
4: end if
5:  $LB \leftarrow \#emptyClauses(\phi) + underestimation(\phi, UB)$ ;
6: if  $LB \geq UB$  then
7:   return  $UB$ ;
8: end if
9:  $x \leftarrow selectVariable(\phi)$ ;
10:  $UB \leftarrow \min(UB, max\text{-}sat(\phi_{\bar{x}}, UB))$ ;
11: return  $\min(UB, max\text{-}sat(\phi_x, UB))$ ;

```

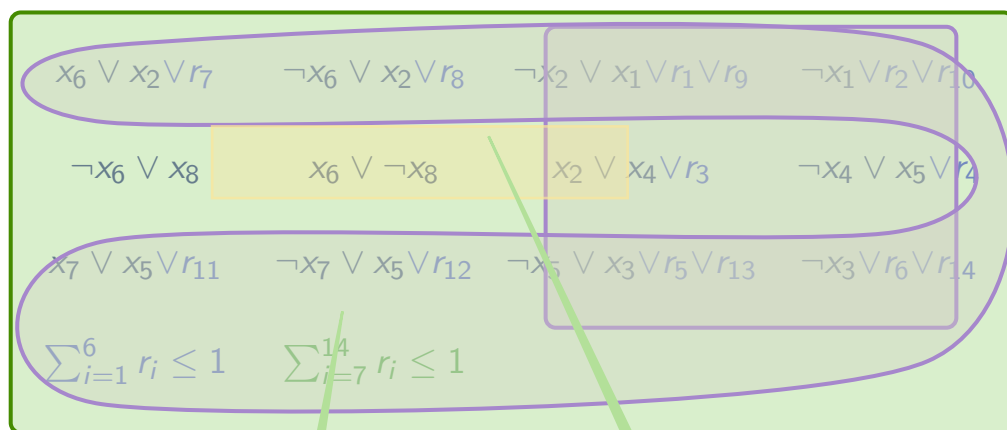
[LMP'07] **Output:** The minimal number of unsatisfied clauses of ϕ

- Many techniques for computing lower bounds, i.e. for lower bounding the search

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$\neg x_6 \vee x_8$	$x_6 \vee \neg x_8$	$x_2 \vee x_4$	$\neg x_4 \vee x_5$
$x_7 \vee x_5$	$\neg x_7 \vee x_5$	$\neg x_5 \vee x_3$	$\neg x_3$

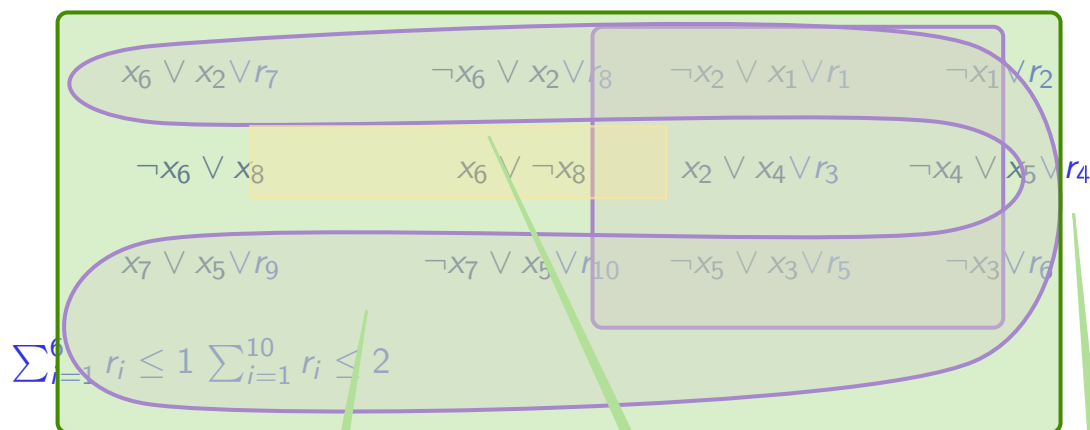
- **Goal:** Do **not** relax all clauses
 - ▶ **Why?**
 - ★ Some clauses **never** relevant for computing MaxSAT solution
 - ★ Simplify cardinality/PB constraints
- How to relax clauses **on demand?**
 - ▶ Relax clauses given **computed unsatisfiable cores**
 - ★ Many alternative ways to instrument code-guided algorithms



Example CNF formula Formula is UNSAT; $\text{OPT} \leq |\varphi| - 1$; Get unsat core Add relaxation variables and AtMost1 constraint Formula is (again) UNSAT; $\text{OPT} \leq |\varphi| - 2$; Get unsat core Add new relaxation constraints Only AtMost1 constraints used Some clauses are relaxed Relaxed soft clauses remain soft $|\varphi| - \mathcal{I} = 12$

Another example

$$\mathcal{F}_5 \triangleq (x_1) \wedge (\neg x_1 \vee x_2) \wedge (\neg x_1 \vee \neg x_2) \wedge (x_3) \wedge (\neg x_3) \wedge (x_4 \vee \neg x_5) \wedge (\neg x_4 \vee x_5)$$



Example CNF formula Formula is UNSAT; $\text{OPT} \leq |\varphi| - 1$; Get unsat core Add relaxation variables and AtMost1 constraint Formula is (again) UNSAT; $\text{OPT} \leq |\varphi| - 2$; Get unsat core Add new relaxation constraints and AtMostk/PB constraint Some clauses are relaxed distance is $|\varphi| - \mathcal{I} = 12$ Relaxed soft clauses become hard solution is

Another example

$$\mathcal{F}_S \triangleq (x_1) \wedge (\neg x_1 \vee x_2) \wedge (\neg x_1 \vee \neg x_2) \wedge (x_3) \wedge (\neg x_3) \wedge (x_4 \vee \neg x_5) \wedge (\neg x_4 \vee x_5)$$

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- **Remark 1:** The MaxSAT solution is a smallest MCS
- **Remark 2:** Any MCS is a hitting set of all MUSes
- **Approach:** [DB'11]
 - 1 Let \mathcal{K} be a set of unsatisfiable cores (or MUSes)
 - 2 Find a minimum hitting set \mathcal{H} of the set \mathcal{K} of already computed cores (or MUSes)
 - 3 Check satisfiability of $\mathcal{F} \setminus \mathcal{H}$
 - 4 If **satisfiable**, then \mathcal{H} is a smallest MCS; **terminate** and return \mathcal{H}
 - 5 **Otherwise**, compute core (or MUS) and add it to \mathcal{K}
 - 6 Loop from 2
- **Issue:** worst-case number of iterations worst-case exponential on number of clauses
 - ▶ But, quite effective in practice

$$\begin{aligned}
 c_1 &= x_6 \vee x_2 \vee A_1 A_1 & c_2 &= \neg x_6 \vee x_2 \vee A_2 A_2 & c_3 &= \neg x_2 \vee x_1 \vee A_3 A_3 & c_4 &= \neg x_1 \vee A_4 A_4 \\
 c_5 &= \neg x_6 \vee x_8 \vee A_5 A_5 & c_6 &= x_6 \vee \neg x_8 \vee A_6 A_6 & c_7 &= x_2 \vee x_4 \vee A_7 A_7 & c_8 &= \neg x_4 \vee x_5 \vee A_8 A_8 \\
 c_9 &= x_7 \vee x_5 \vee A_9 A_9 & c_{10} &= \neg x_7 \vee x_5 \vee A_{10} A_{10} & c_{11} &= \neg x_5 \vee x_3 \vee A_{11} A_{11} & c_{12} &= \neg x_3 \vee A_{12} A_{12}
 \end{aligned}$$

$$\mathcal{K} = \emptyset$$

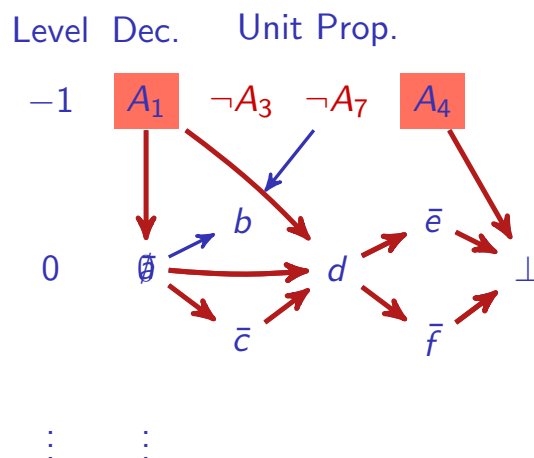
- To every $c_i \in \mathcal{F}$, add a new literal A_i . Set A_i to **true** to relax c_i , or to **false** to activate it
- Find MHS of \mathcal{K} : \emptyset
- $\text{SAT}(\mathcal{F} \setminus \emptyset)$? **No**
- Core of \mathcal{F} : $\{c_1, c_2, c_3, c_4\}$. Update \mathcal{K}
- Find MHS of \mathcal{K} : E.g. $\{c_1\}$

- Core of \mathcal{F} : $\{c_9, c_{10}, c_{11}, c_{12}\}$. Update \mathcal{K}
- Find MHS of \mathcal{K} : E.g. $\{c_1, c_9\}$
- $\text{SAT}(\mathcal{F} \setminus \{c_1, c_9\})$? **No**
- Core of \mathcal{F} : $\{c_3, c_4, c_7, c_8, c_{11}, c_{12}\}$. Update \mathcal{K}
- Find MHS of \mathcal{K} : E.g. $\{c_1, c_9\}$

Core Extraction Using CDCL

- terminate & return 2

- Assign the **activation** literals at a special decision level (-1)
- CDCL fails when finding a contradiction at level 0
 - The implication graph must involve some **activation** literals
- Do clause resolution until the cut contains only **activation** literals
- The resulting clause is a **MUS** of the original formula



Algorithm: MAXHS

```

 $\mathcal{K} \leftarrow \emptyset$  // The MUSs
 $\sigma \leftarrow \emptyset$  // The optimal model
while satisfiability  $\neq$  SAT do
     $hs \leftarrow \text{Find-MinCost-HittingSet}(\mathcal{K});$ 
     $(sat, \kappa, \sigma) \leftarrow \text{CDCL}(\mathcal{F} \setminus hs);$ 
    add  $\kappa$  to  $\mathcal{K}$ ;
end
return  $\sigma$ ;

```

- CDCL returns the tuple (sat, κ, σ) where:

- ▶ sat is in {SAT, UNSAT, UNKNOWN}
- ▶ κ is a MUS
- ▶ σ is a solution if $=(\text{SAT}) = \text{true}$

- **Je recrute un postdoc!**

- ▶ Planification des prises de vue et vidages d'une constellation de satellites d'observation (Projet JAPETUS – PROMETHEE, CNES, CNRS, LEANSAPCE)

